12-BIT 200-KSPS 11-CHANNEL LOW-POWER SERIAL ANALOG-TO-DIGITAL CONVERTER WITH INTERNAL REFERENCE

FEATURES

- **12-Bit-Resolution Analog-to-Digital Converter (ADC)**
- **Up to 200-KSPS (150-KSPS for 3 V) Throughput Bit With 12-Output Mode Over Operating Temperature Range**
- **11 Analog Input Channels**
- **3 Built-In Self-Test Modes**
- **Programmable Reference (2.048 V/4.096 V Internal or External)**
- **Inherent Sample and Hold Function**
- **Linearity Error...±1 LSB Max**
- **On-Chip Conversion Clock**
- **Programmable Conversion Status Output: $\overline{\text{INT}}$ or EOC**
- **Unipolar or Bipolar Output Operation**
- **Programmable MSB or LSB First**
- **Programmable Power Down**
- **Programmable Output Data Length**
- **SPI Compatible Serial Interface With I/O Clock Frequencies up to 15 MHz (CPOL = 0, CPHA = 0)**

SUPPORTS DEFENSE, AEROSPACE, AND MEDICAL APPLICATIONS

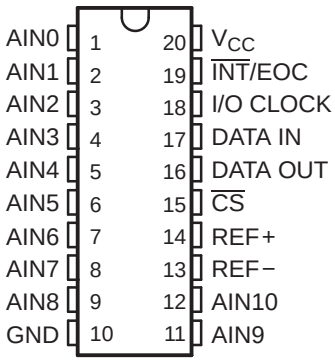
- **Controlled Baseline**
- **One Assembly/Test Site**
- **One Fabrication Site**
- **Available in Military (–55°C/125°C) Temperature Range**(1)
- **Extended Product Life Cycle**
- **Extended Product-Change Notification**
- **Product Traceability**

APPLICATIONS

- **Industrial Process Control**
- **Portable Data Logging**
- **Battery Powered Instruments**
- **Automotive**

(1) Additional temperature ranges are available - contact factory

PW AND DW PACKAGE
(TOP VIEW)



DESCRIPTION

The TLV2556 is a 12-bit, switched-capacitor, successive-approximation, analog-to-digital converter (ADC). The ADC has three control inputs [chip select ($\overline{\text{CS}}$), the input-output clock, and the address/control input (DATAIN)], designed for communication with the serial port of a host processor or peripheral through a serial 3-state output.

In addition to the high-speed converter and versatile control capability, the device has an on-chip 14-channel multiplexer that can select any one of 11 inputs or any one of three internal self-test voltages using configuration register 1. The sample-and-hold function is automatic. At the end of conversion, when programmed as EOC, the pin 19 output goes high to indicate that conversion is complete. If pin 19 is programmed as $\overline{\text{INT}}$, the signal goes low when the conversion is complete. The converter incorporated in the device features differential, high-impedance reference inputs that facilitate ratiometric conversion, scaling, and isolation of analog circuitry from logic and supply noise. A switched-capacitor design allows low-error conversion over the full operating temperature range. An internal reference is available and its voltage level is programmable via configuration register 2 (CFGR2).

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of the Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

Copyright © 2008–2009, Texas Instruments Incorporated

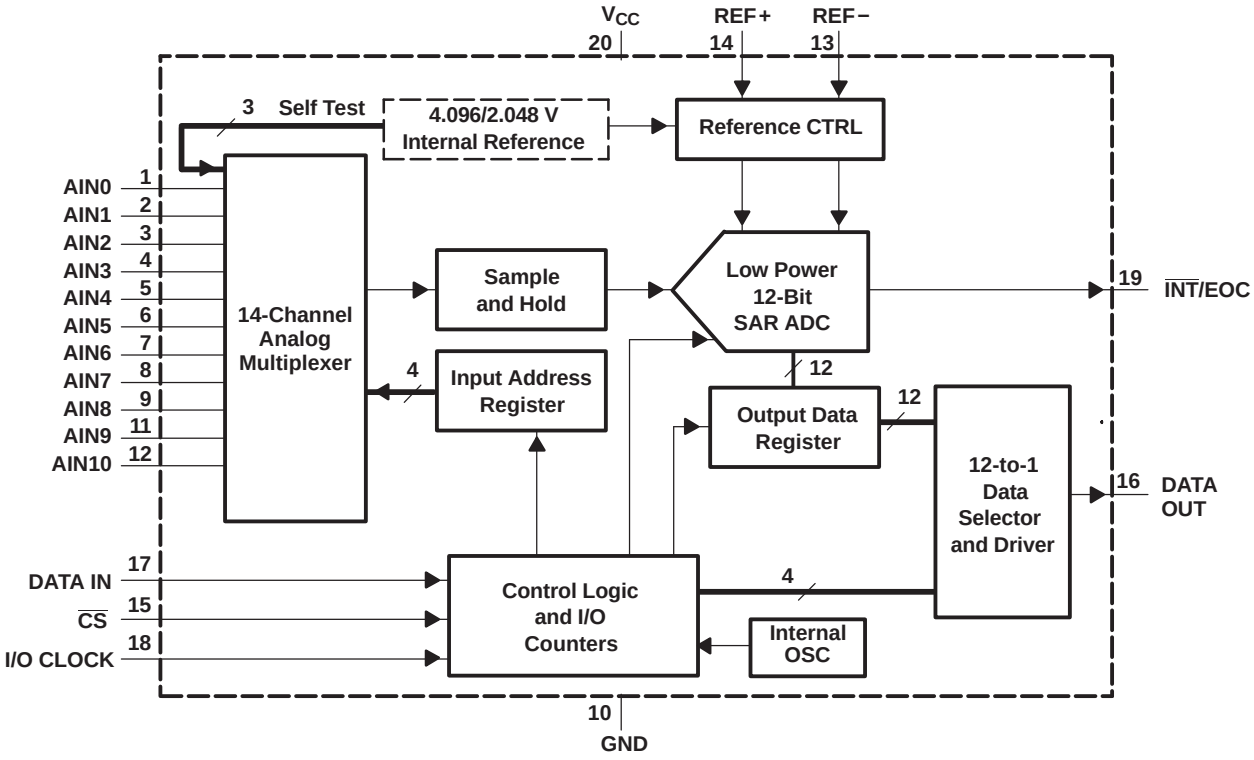
The TLV2556 is characterized for operation from T_A = –55°C to 125°C.

ORDERING INFORMATION(1)

T_A	PACKAGE(2)		ORDERABLE PART NUMBER	TOP-SIDE MARKING
–55°C to 125°C	TSSOP – PW	Reel of 2000	TLV2556MPWREP	TL2556EP

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.
(2) Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.

Functional Block Diagram



Copyright © 2008–2009, Texas Instruments Incorporated

TERMINAL FUNCTIONS

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
AIN0–AIN10	1–9, 11, 12	I	Analog input. These 11 analog-signal inputs are internally multiplexed.
$\overline{CS}$	15	I	Chip select. A high-to-low transition on $\overline{CS}$ resets the internal counters and controls and enables DATA OUT, DATA IN, and I/O CLOCK. A low-to-high transition disables DATA IN and I/O CLOCK within a setup time.
DATA IN	17	I	Serial data input. The 4-bit serial data can be used as address selects the desired analog input channel or test voltage to be converted next, or a command to activate other features. The input data is presented with the MSB (D7) first and is shifted in on the first four rising edges of the I/O CLOCK. After the four address/command bits are read into the command register CMR, I/O CLOCK clocks the remaining four bits of configuration in.
DATA OUT	16	O	The 3-state serial output for the A/D conversion result. DATA OUT is in the high-impedance state when $\overline{CS}$ is high and active when $\overline{CS}$ is low. With a valid $\overline{CS}$, DATA OUT is removed from the high-impedance state and is driven to the logic level corresponding to the MSB(most significant bit)/LSB(least significant bit) value of the previous conversion result. The next falling edge of I/O CLOCK drives DATA OUT to the logic level corresponding to the next MSB/LSB, and the remaining bits are shifted out in order.
$\overline{INT}$/EOC	19	O	Status output, used to indicate the end of conversion (EOC) or an interrupt ($\overline{INT}$) to host processor. Programmed as $\overline{INT}$ (interrupt): $\overline{INT}$ goes from a high to a low logic level after the conversion is complete and the data is ready for transfer. $\overline{INT}$ is cleared by a rising I/O CLOCK transition. Programmed as EOC: EOC goes from a high to a low logic level after the falling edge of the last I/O CLOCK and remains low until the conversion is complete and the data is ready for transfer.
GND	10		Ground. GND is the ground return terminal for the internal circuitry. Unless otherwise noted, all voltage measurements are with respect to GND.
I/O CLOCK	18	I	Input /output clock. I/O CLOCK receives the serial input and performs the following four functions: 1. It clocks the eight input data bits into the input data register on the first eight rising edges of I/O CLOCK with the multiplexer address available after the fourth rising edge. 2. On the fourth falling edge of I/O CLOCK, the analog input voltage on the selected multiplexer input begins charging the capacitor array and continues to do so until the last falling edge of I/O CLOCK. 3. The remaining 11 bits of the previous conversion data are shifted out on DATA OUT. Data changes on the falling edge of I/O CLOCK. 4. Control of the conversion is transferred to the internal state controller on the falling edge of the last I/O CLOCK.
REF+	14	I/O	Positive reference voltage The upper reference voltage value (nominally V_{CC}) is applied to REF+. The maximum analog input voltage range is determined by the difference between the voltage applied to terminals REF+ and REF–. When the internal reference is used it is capable of driving a 10-kΩ, 10-pF load.
REF–	13	I/O	Negative reference voltage. The lower reference voltage value (nominally ground) is applied to REF–. This pin is connected to analog ground (GND of the ADC) when the internal reference is used.
V_{CC}	20		Positive supply voltage

Copyright © 2008–2009, Texas Instruments Incorporated

ABSOLUTE MAXIMUM RATINGS(1)(2)

over operating free-air temperature range (unless otherwise noted)

V_{CC}	Supply voltage range	–0.5 V to 6.5 V
V_I	Input voltage range (any input)	–0.3 V to V_{CC} + 0.3 V
V_O	Output voltage range	–0.3 V to V_{CC} + 0.3 V
V_{REF+}	Positive reference voltage range	–0.3 V to V_{CC} + 0.3 V
$V_{REF–}$	Negative reference voltage range	–0.3 V to V_{CC} + 0.3 V
I_I	Peak input current (any input)	±20 mA
	Peak total input current (all inputs)	±30 mA
T_J	Operating virtual-junction temperature range	–55°C to 150°C
T_A	Operating free-air temperature range	–55°C to 125°C
T_{stg}	Storage temperature range	–65°C to 150°C
	Lead temperature 1,6 mm (1/16 inch) from the case for 10 seconds	260°C

(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltage values are with respect to the GND terminal with REF– and GND wired together (unless otherwise noted).

RECOMMENDED OPERATING CONDITIONS

				MIN	NOM	MAX	UNIT
V_{CC}	Supply voltage			2.7		5.5	V
	SCLK frequency	V_{CC} = 4.5 V to 5.5 V	16-bit I/O	0.01		15	MHz
			12-bit I/O	0.01		15	
			8-bit I/O	0.01		15	
		V_{CC} = 2.7 V to 3.6 V		0.01		10	
	Tolerable clock jitter, I/O CLOCK	V_{CC} = 4.5 V to 5.5 V				0.38	ns
	Aperture jitter	V_{CC} = 4.5 V to 5.5 V			100		ps
	Analog input voltage(1)	V_{CC} = 4.5 V to 5.5 V		0		(REF+) – (REF–)	V
		V_{CC} = 3 V to 3.6 V		0		(REF+) – (REF–)	
		V_{CC} = 2.7 V to 3 V		0		(REF+) – (REF–)	
V_{IH}	High level control input voltage	V_{CC} = 4.5 V to 5.5 V		2			V
		V_{CC} = 2.7 V to 3.6 V		2.1			
V_{IL}	Low level control input voltage	V_{CC} = 4.5 V to 5.5 V				0.8	V
		V_{CC} = 2.7 V to 3.6 V				0.6	
T_A	Operating free-air temperature			–55		125	°C

(1) Analog input voltages greater than the voltage applied to REF+ convert as all ones (111111111111), while input voltages less than the voltage applied to REF– convert as all zeros (000000000000).

Copyright © 2008–2009, Texas Instruments Incorporated

ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range, V_{REF+} = 5 V,
SCLK frequency = 15 MHz when V_{CC} = 5 V, V_{REF+} = 2.5 V,
SCLK frequency = 10 MHz when V_{CC} = 2.7 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP(1)	MAX	UNIT
V_{OH}	High-level output voltage	V_{CC} = 4.5 V, I_{OH} = –1.6 mA V_{CC} = 2.7 V, I_{OH} = –0.2 mA	30 pF	2.4			V
		V_{CC} = 4.5 V, I_{OH} = –20 µA V_{CC} = 2.7 V, I_{OH} = –20 µA		V_{CC} – 0.1			
V_{OH}	Low-level output voltage	V_{CC} = 5.5 V, I_{OL} = 1.6 mA V_{CC} = 3.6 V, I_{OL} = 0.8 mA	30 pF			0.4	V
		V_{CC} = 5.5 V, I_{OL} = –20 µA V_{CC} = 3.6 V, I_{OL} = –20 µA				0.1	
I_{OZ}	High impedance off state output current	V_O = V_{CC}, $\overline{CS}$ = V_{CC}			1	2.5	µA
		V_O = 0 V, $\overline{CS}$ = V_{CC}			–1	–2.5	
I_{CC}	Operating supply current	$\overline{CS}$ at 0 V, External reference	V_{CC} = 5 V			1.2	mA
			V_{CC} = 2.7 V			0.9	
		$\overline{CS}$ at 0 V, Internal reference	V_{CC} = 5 V			3	
			V_{CC} = 2.7 V			2.4	
$I_{CC(SPD)}$	Software power down current	For all digital inputs, 0 V ≤ V_I ≤ 0.5 V or V_I ≥ V_{CC} – 0.5 V, SCLK = 0 V	External reference		0.1	10	µA
			Internal reference		0.1	10	
$I_{CC(APD)}$	Auto power down current	For all digital inputs, 0 V ≤ V_I ≤ 0.5 V or V_I ≥ V_{CC} – 0.5 V, SCLK = 0 V	External reference		0.1	10	µA
			Internal reference			1800	
I_{IH}	High-level input current	V_I = V_{CC}			0.005	2.5	µA
I_{IL}	Low-level input current	V_I = 0 V			–0.005	–2.5	µA
I_{lkg}	Selected channel leakage current	Selected channel at V_{CC} , Unselected channel at 0 V				1	µA
		Selected channel at 0 V, Unselected channel at V_{CC}				–1	
$f_{(OSC)}$	Internal oscillator frequency	V_{CC} = 4.5 V to 5.5 V		3.0			MHz
		V_{CC} = 2.7 V to 3.6 V		2.1			
t_{conv}	Conversion time = 13.5 × $f_{(OSC)}$ + 25 ns	V_{CC} = 4.5 V to 5.5 V				4.53	µs
		V_{CC} = 2.7 V to 3.6 V				6.46	
	Internal oscillator frequency switch-over voltage				3.9		V
Z_i	Analog input MUX impedance(2)	V_{CC} = 4.5 V			600		Ω
		V_{CC} = 2.7 V			500		
C_i	Input capacitance	Analog inputs			45		pF
		Control inputs			5		

(1) All typical values are at V_{CC} = 5 V, T_A = 25°C.
(2) The switch resistance is very nonlinear and varies with input voltage and supply voltage.

Copyright © 2008–2009, Texas Instruments Incorporated

EXTERNAL REFERENCE SPECIFICATIONS(1)

PARAMETER	TEST CONDITIONS		MIN	TYP(2)	MAX	UNIT
Reference input voltage, REF–	V_{CC} = 4.5 V to 5.5 V		–0.1	0	0.1	V
	V_{CC} = 2.7 V to 3.6 V		–0.1	0	0.1	
Reference input voltage, REF+	V_{CC} = 4.5 V to 5.5 V		2		V_{CC}	V
	V_{CC} = 2.7 V to 3.6 V		2		V_{CC}	
External reference input voltage difference, (REF+) – (REF–)	V_{CC} = 4.5 V to 5.5 V		1.9		V_{CC}	V
	V_{CC} = 2.7 V to 3.6 V		1.9		V_{CC}	
External reference supply current	$\overline{CS}$ = 0 V	V_{CC} = 4.5 V to 5.5 V			1	mA
		V_{CC} = 2.7 V to 3.6 V			0.7	
Reference input impedance	V_{CC} = 5 V	Static		1		MΩ
		During sampling/conversion		9		kΩ
	V_{CC} = 2.7 V	Static		1		MΩ
		During sampling/conversion		9		kΩ

(1) Add a 0.1-µF capacitor between REF+ and REF– pins when external reference is used.
(2) All typical values are at V_{CC} = 5 V, T_A = 25°C.

INTERNAL REFERENCE SPECIFICATIONS(1)

PARAMETER	TEST CONDITIONS		MIN	TYP(2)	MAX	UNIT
Reference input voltage, REF–	V_{CC} = 2.7 V to 5.5 V, REF– = Analog GND			0		V
Internal reference voltage delta, (REF+) – (REF–)	V_{CC} = 5.5 V, Internal 4.096-V V_{REF} selected		3.95	4.065	4.25	V
	V_{CC} = 5.5 V, Internal 2.048-V V_{REF} selected		1.94	2.019	2.15	
	V_{CC} = 2.7 V, Internal 2.048-V V_{REF} selected		1.94	2.019	2.15	
Internal reference start up time	V_{CC} = 5 V	With 10-µF load		20		ms
	V_{CC} = 2.7 V			20		
Internal reference temperature coefficient	V_{CC} = 2.7 V to 5.5 V			±50		ppm/°C

(1) When an internal reference is used, the following conditions are required:
a. Add 0.1-µF and 10-µF capacitors between REF+ and REF– pins.
b. REF– must be connected to analog GND (the ground pin of the ADC).
(2) All typical values are at V_{CC} = 5 V, T_A = 25°C.

Copyright © 2008–2009, Texas Instruments Incorporated

OPERATING CHARACTERISTICS

over recommended operating free-air temperature range, V_{REF+} = 5 V,
SCLK frequency = 15 MHz when V_{CC} = 5 V, V_{REF+} = 2.5 V,
SCLK frequency = 10 MHz when V_{CC} = 2.7 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
INL	Integral nonlinearity error(2)		–1		1	LSB
DNL	Differential nonlinearity error		–1		1	LSB
E_O	Offset error(3)(4)		–2		2	mV
E_G	Gain error(3)(4)		–3		3	mV
E_T	Total unadjusted error(5)			±1.5		LSB
	Self-test output code(6) (see Table 2)	Address data input = 1011		2048		
		Address data input = 1100		0		
		Address data input = 1101		4095		

(1) All typical values are at V_{CC} = 5 V, T_A = 25°C.
(2) Linearity error is the maximum deviation from the best straight line through the A/D transfer characteristics.
(3) Analog input voltages greater than the voltage applied to REF+ convert as all ones (111111111111), while input voltages less than the voltage applied to REF– convert as all zeros (000000000000).
(4) Gain error is the difference between the actual mid-step value and the nominal mid-step value in the transfer diagram at the specified gain point after the offset error has been adjusted to zero. Offset error is the difference between the actual mid-step value and the nominal mid-step value at the offset point.
(5) Total unadjusted error comprises linearity, zero-scale, and full-scale errors.
(6) Both the input address and the output codes are expressed in positive logic.

Copyright © 2008–2009, Texas Instruments Incorporated

TIMING CHARACTERISTICS(1)

operating characteristics, V_{REF+} = 5 V, SCLK frequency = 15 MHz, V_{CC} = 5 V, load = 25 pF, T_A= -40°C to 85°C (unless otherwise noted)

PARAMETER			MIN	TYP	MAX	UNIT
t_{w1}	Pulse duration I/O CLOCK high or low		26.7		100000	ns
t_{su1}	Setup time DATA IN valid before I/O CLOCK rising edge (see Figure 38)		12			ns
t_{h1}	Hold time DATA IN valid after I/O CLOCK rising edge (see Figure 38)		0			ns
t_{su2}	Setup time $\overline{CS}$ low before 1st rising I/O CLOCK edge(2) (see Figure 39)		25			ns
t_{h2}	Hold time $\overline{CS}$ pulse duration high time (see Figure 39)		100			ns
t_{h3}	Hold time $\overline{CS}$ low after last I/O CLOCK falling edge (see Figure 39)		0			ns
t_{h4}	Hold time DATA OUT valid after I/O CLOCK falling edge (see Figure 40)		2			ns
t_{h5}	Hold time $\overline{CS}$ high after EOC rising edge when $\overline{CS}$ is toggled (see Figure 43)		0			ns
t_{h6}	Hold time $\overline{CS}$ high after $\overline{INT}$ falling edge (see Figure 43)		0			ns
t_{h7}	Hold time I/O CLOCK low after EOC rising edge or $\overline{INT}$ falling edge when $\overline{CS}$ is held low (see Figure 44)		10			ns
t_{d1}	Delay time $\overline{CS}$ falling edge to DATA OUT valid (MSB or LSB) (see Figure 37)	Load = 25 pF			28	ns
		Load = 10 pF			20	
t_{d2}	Delay time $\overline{CS}$ rising edge to DATA OUT high impedance (see Figure 37)				10	ns
t_{d3}	Delay time I/O CLOCK falling edge to next DATA OUT bit valid (see Figure 40)		2		20	ns
t_{d4}	Delay time last I/O CLOCK falling edge to EOC falling edge (see Figure 41)				55	ns
t_{d5}	Delay time last I/O CLOCK falling edge to $\overline{CS}$ falling edge to abort conversion				1.5	µs
t_{d6}	Delay time last I/O CLOCK falling edge to $\overline{INT}$ falling edge (see Figure 41)				MAX(t_{conv})	ns
t_{d7}	Delay time EOC rising edge or $\overline{INT}$ falling edge to DATA OUT valid: MSB or LSB first (see Figure 42)				4	ns
t_{d9}	Delay time I/O CLOCK high to $\overline{INT}$ rising edge when $\overline{CS}$ is held low (see Figure 44)		1		28	ns
t_{t1}	Transition time I/O CLOCK(2) (see Figure 40)				1	µs
t_{t2}	Transition time DATA OUT (see Figure 40)				5	ns
t_{t3}	Transition time $\overline{INT}$/EOC, CL = 7 pF (see Figure 41 and Figure 42)				2.4	ns
t_{t4}	Transition time DATA IN, $\overline{CS}$				10	µs
t_{cyc}	Total cycle time (sample, conversion and delays)(2)				MAX(t_{conv}) + I/O period (8/12/16 CLKs)	µs
t_{sample}	Channel acquisition time (sample), at 1 kΩ(2)	Source impedance = 25 Ω	600			ns
		Source impedance = 100 Ω	650			
		Source impedance = 500 Ω	700			
		Source impedance = 1 kΩ	1000			

(1) Timing parameters are not production tested.
(2) I/O CLOCK period = 8x [1/(I/O CLOCK frequency)] or 12x [1/(I/O CLOCK frequency)] or 16x [1/(I/O CLOCK frequency)] depends on I/O format selected.

Copyright © 2008–2009, Texas Instruments Incorporated

TIMING CHARACTERISTICS(1)

operating characteristics, V_{REF+} = 2.5 V, SCLK frequency = 10 MHz, V_{CC} = 2.7 V, load = 25 pF, T_A= -40°C to 85°C (unless otherwise noted)

PARAMETER			MIN	TYP	MAX	UNIT
t_{w1}	Pulse duration I/O CLOCK high or low		40		100000	ns
t_{su1}	Setup time DATA IN valid before I/O CLOCK rising edge (see Figure 38)		22			ns
t_{h1}	Hold time DATA IN valid after I/O CLOCK rising edge (see Figure 38)		0			ns
t_{su2}	Setup time $\overline{CS}$ low before 1st rising I/O CLOCK edge(2) (see Figure 39)		33			ns
t_{h2}	Hold time $\overline{CS}$ pulse duration high time (see Figure 39)		100			ns
t_{h3}	Hold time $\overline{CS}$ low after last I/O CLOCK falling edge (see Figure 39)		0			ns
t_{h4}	Hold time DATA OUT valid after I/O CLOCK falling edge (see Figure 40)		2			ns
t_{h5}	Hold time $\overline{CS}$ high after EOC rising edge when $\overline{CS}$ is toggled (see Figure 43)		0			ns
t_{h6}	Hold time $\overline{CS}$ high after $\overline{INT}$ falling edge (see Figure 43)		0			ns
t_{h7}	Hold time I/O CLOCK low after EOC rising edge or $\overline{INT}$ falling edge when $\overline{CS}$ is held low (see Figure 44)		10			ns
t_{d1}	Delay time $\overline{CS}$ falling edge to DATA OUT valid (MSB or LSB) (see Figure 37)	Load = 25 pF			30	ns
		Load = 10 pF			22	
t_{d2}	Delay time $\overline{CS}$ rising edge to DATA OUT high impedance (see Figure 37)				10	ns
t_{d3}	Delay time I/O CLOCK falling edge to next DATA OUT bit valid (see Figure 40)		2		33	ns
t_{d4}	Delay time last I/O CLOCK falling edge to EOC falling edge (see Figure 41)				75	ns
t_{d5}	Delay time last I/O CLOCK falling edge to $\overline{CS}$ falling edge to abort conversion				1.5	µs
t_{d6}	Delay time last I/O CLOCK falling edge to $\overline{INT}$ falling edge (see Figure 41)				MAX(t_{conv})	ns
t_{d7}	Delay time EOC rising edge or $\overline{INT}$ falling edge to DATA OUT valid: MSB or LSB first (see Figure 42)				20	ns
t_{d9}	Delay time I/O CLOCK high to $\overline{INT}$ rising edge when $\overline{CS}$ is held low (see Figure 44)		1		55	ns
t_{t1}	Transition time I/O CLOCK(2) (see Figure 40)				1	µs
t_{t2}	Transition time DATA OUT (see Figure 40)				5	ns
t_{t3}	Transition time $\overline{INT}$/EOC, CL = 7 pF (see Figure 41 and Figure 42)				4	ns
t_{t4}	Transition time DATA IN, $\overline{CS}$				10	µs
t_{cyc}	Total cycle time (sample, conversion and delays)(2)				MAX(t_{conv}) + I/O period (8/12/16 CLKs)	µs
t_{sample}	Channel acquisition time (sample), at 1 kΩ(2)	Source impedance = 25 Ω	800			ns
		Source impedance = 100 Ω	850			
		Source impedance = 500 Ω	1000			
		Source impedance = 1 kΩ	1600			

(1) Timing parameters are not production tested.
(2) I/O CLOCK period = 8x [1/(I/O CLOCK frequency)] or 12x [1/(I/O CLOCK frequency)] or 16x [1/(I/O CLOCK frequency)] depends on I/O format selected.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

SUPPLY CURRENT vs FREE-AIR TEMPERATURE

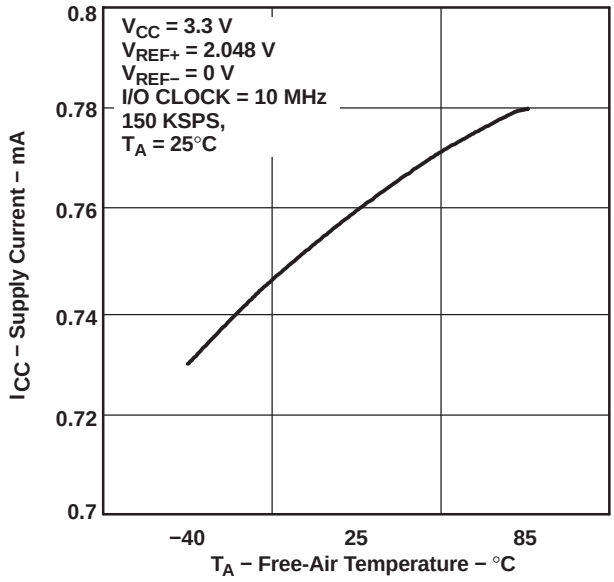


Figure 1.

AUTO POWER DOWN vs FREE-AIR TEMPERATURE

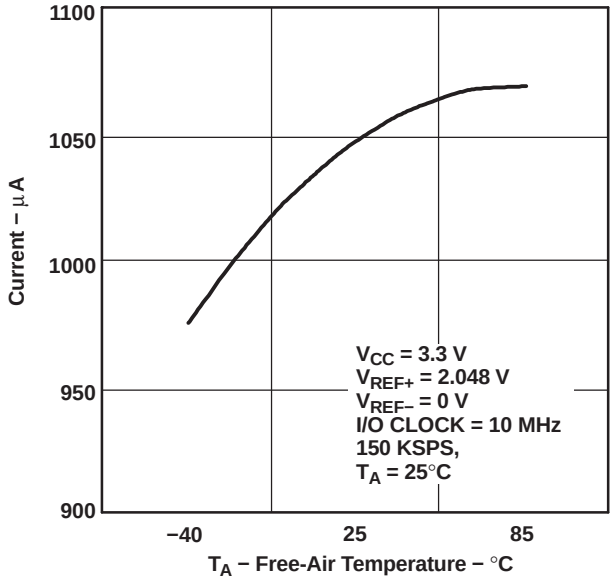


Figure 2.

SOFTWARE POWER DOWN vs FREE-AIR TEMPERATURE

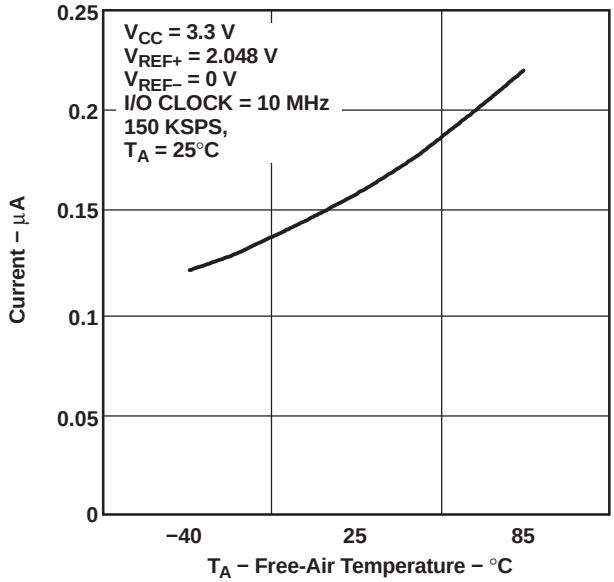


Figure 3.

2-V INTERNAL REFERENCE CURRENT vs FREE-AIR TEMPERATURE

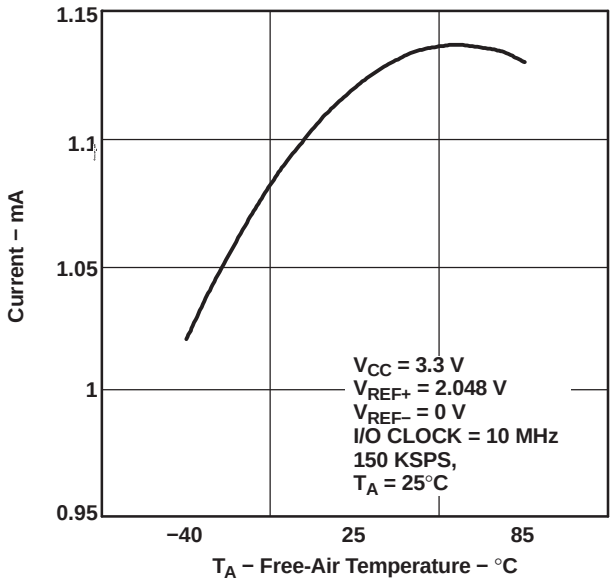


Figure 4.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

MAXIMUM DIFFERENTIAL NONLINEARITY vs FREE-AIR TEMPERATURE

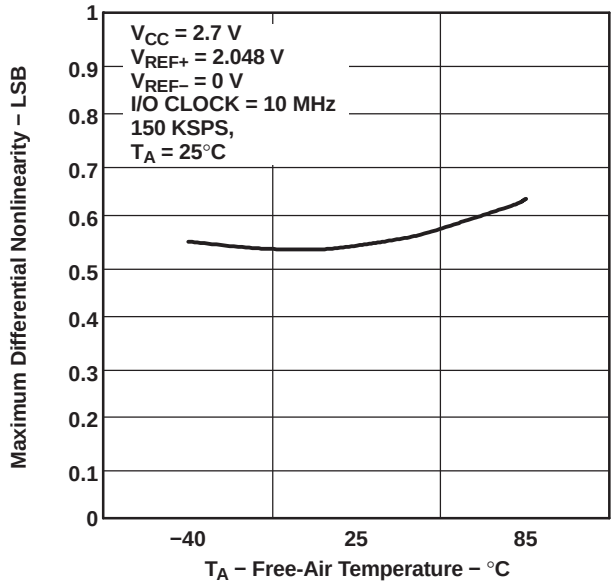


Figure 5.

MINIMUM DIFFERENTIAL NONLINEARITY vs FREE-AIR TEMPERATURE

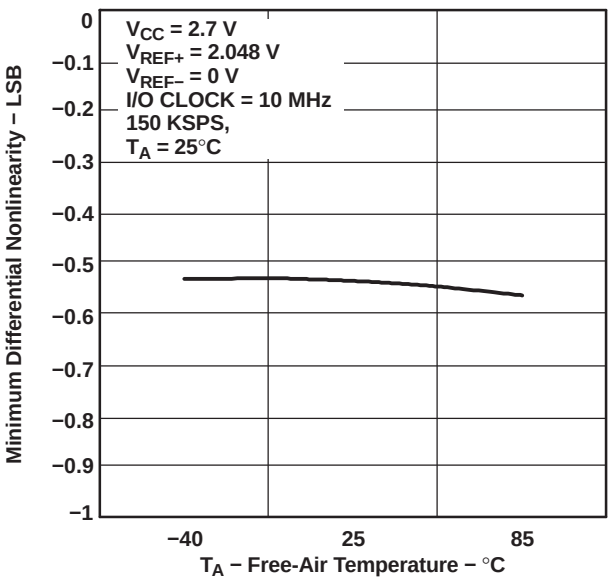


Figure 6.

MAXIMUM INTEGRAL NONLINEARITY vs FREE-AIR TEMPERATURE

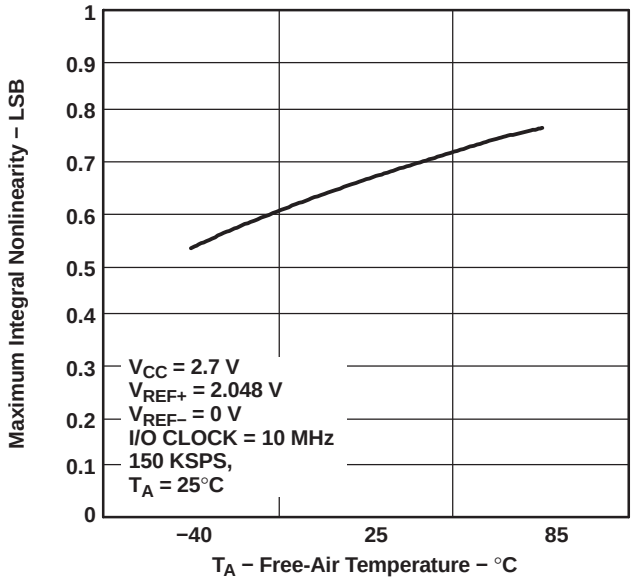


Figure 7.

MINIMUM INTEGRAL NONLINEARITY vs FREE-AIR TEMPERATURE

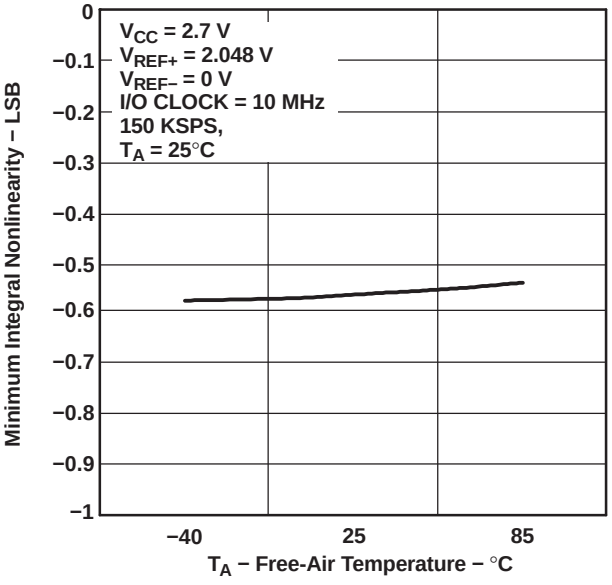


Figure 8.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

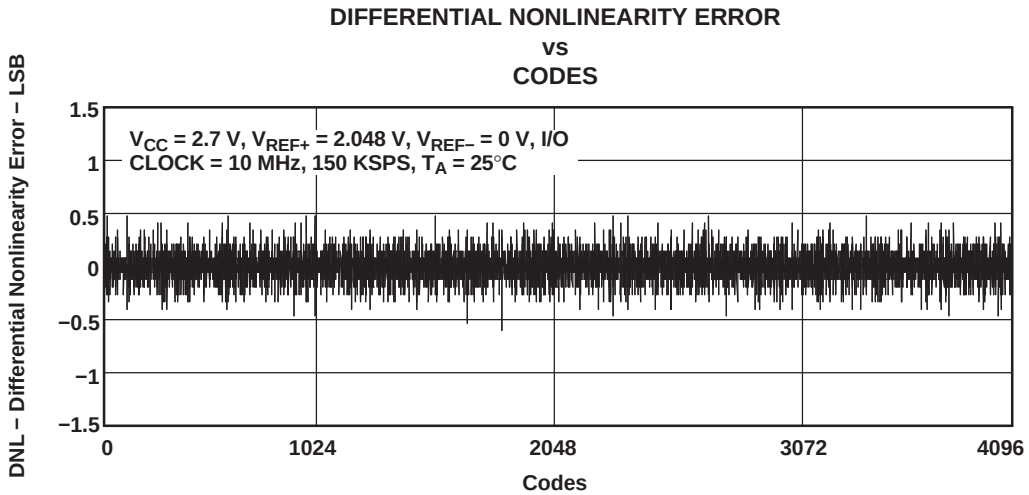


Figure 9.

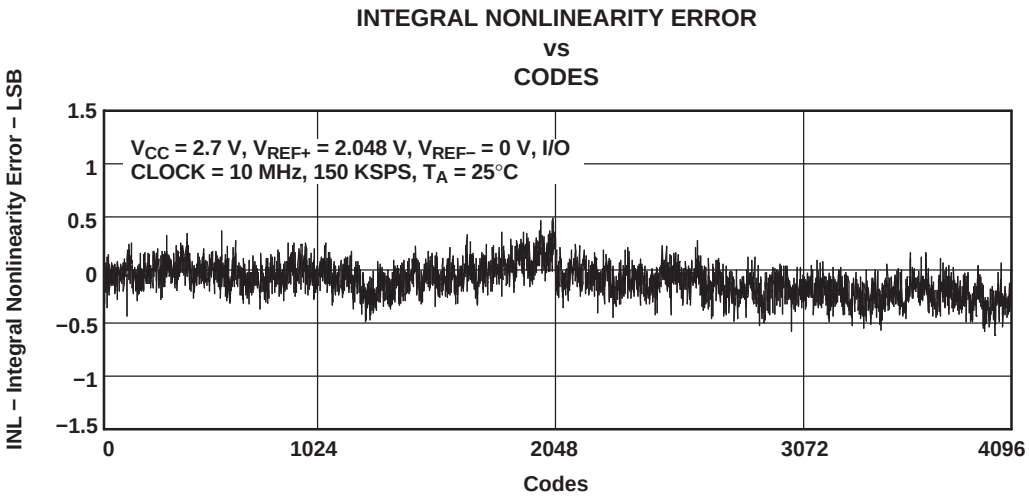


Figure 10.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

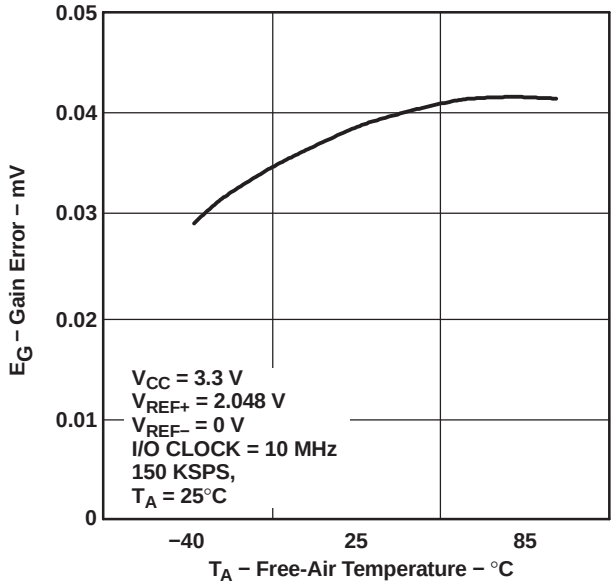


Figure 11.

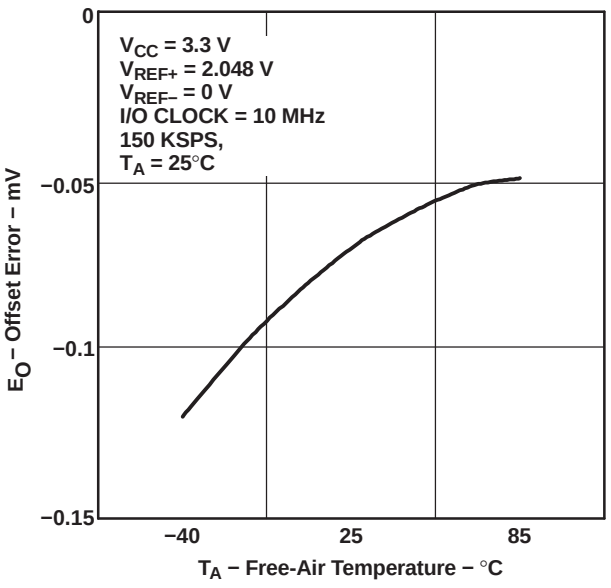


Figure 12.

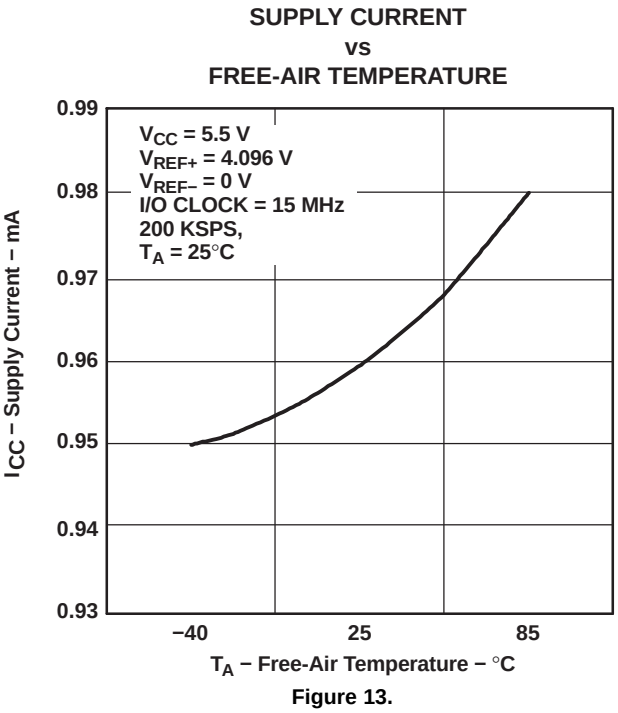


Figure 13.

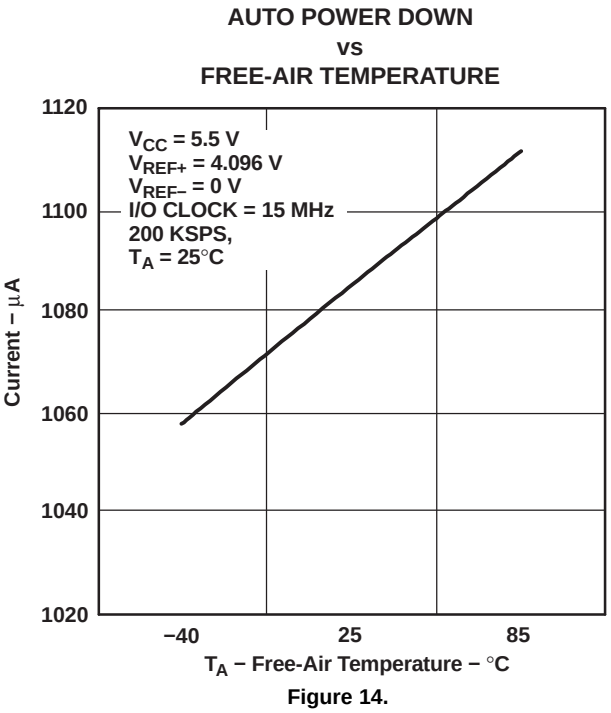


Figure 14.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

SOFTWARE POWER DOWN vs FREE-AIR TEMPERATURE

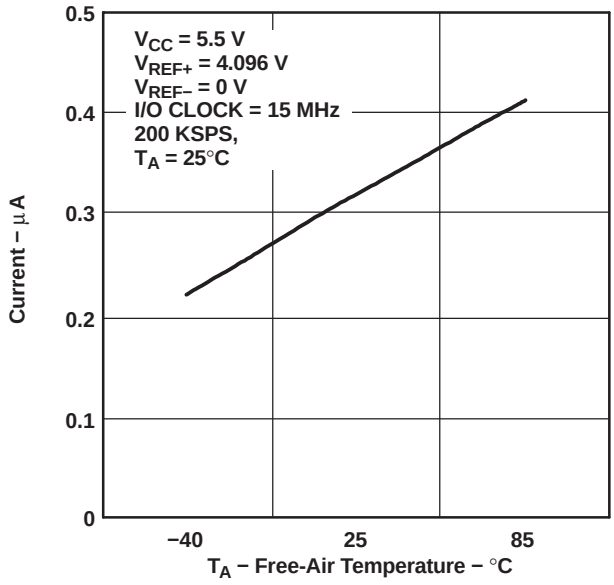


Figure 15.

4-V INTERNAL REFERENCE CURRENT vs FREE-AIR TEMPERATURE

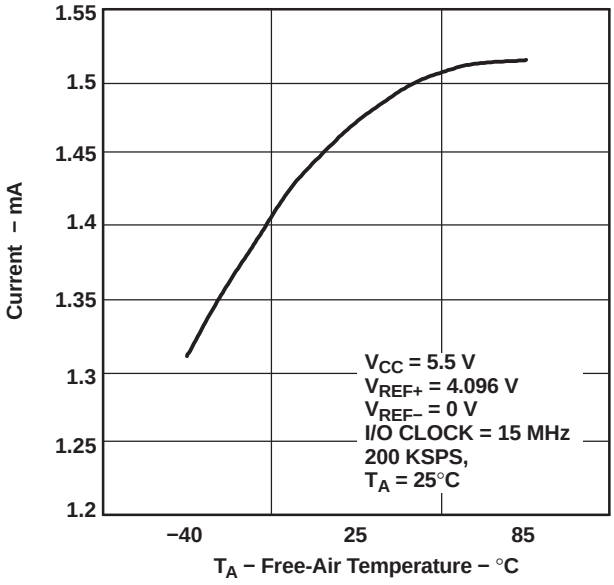


Figure 16.

MAXIMUM DIFFERENTIAL NONLINEARITY vs FREE-AIR TEMPERATURE

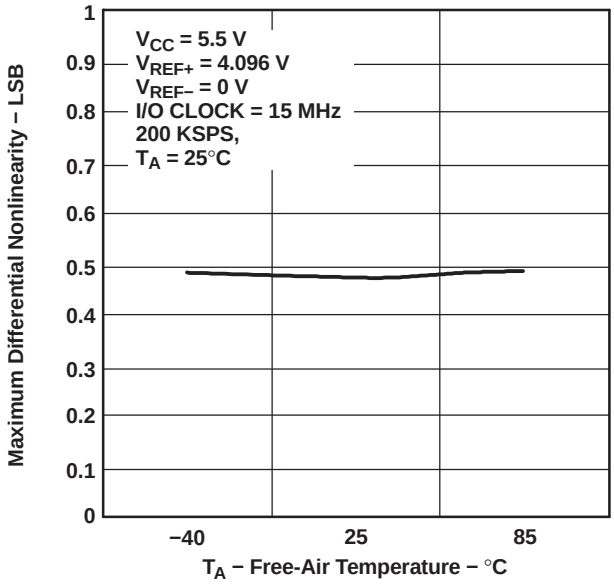


Figure 17.

MINIMUM DIFFERENTIAL NONLINEARITY vs FREE-AIR TEMPERATURE

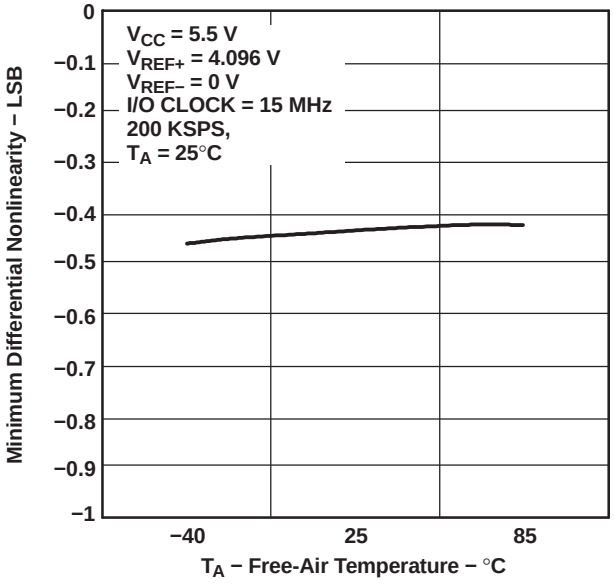


Figure 18.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

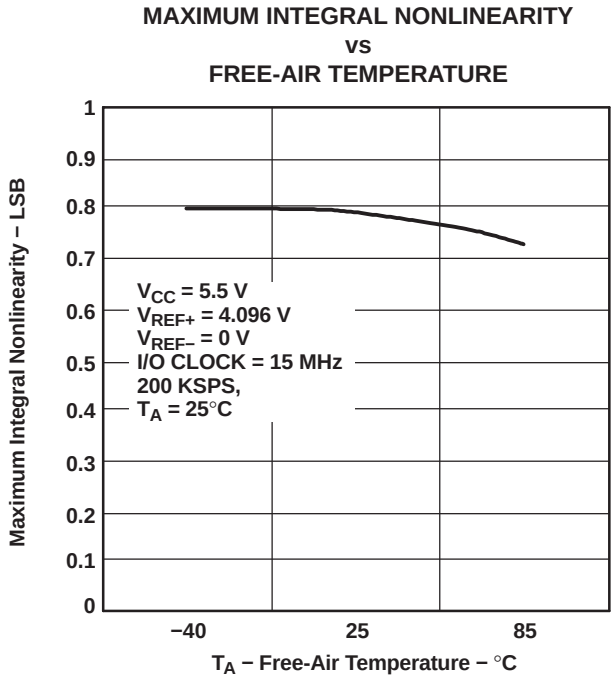


Figure 19.

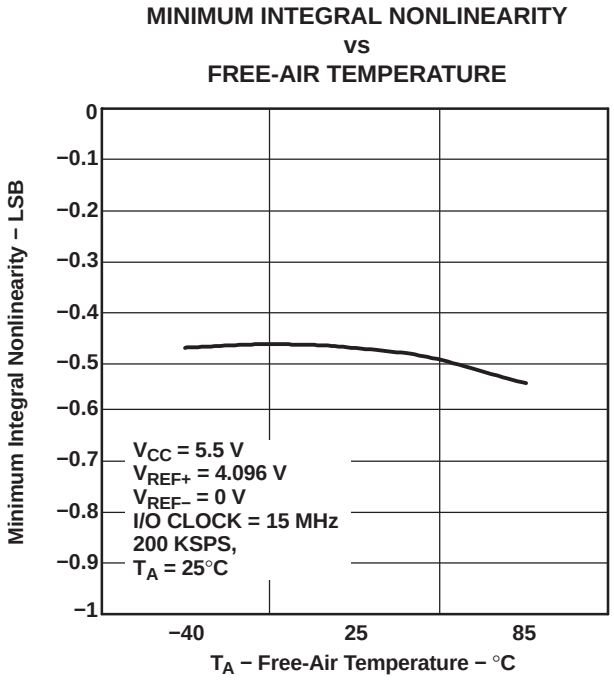


Figure 20.

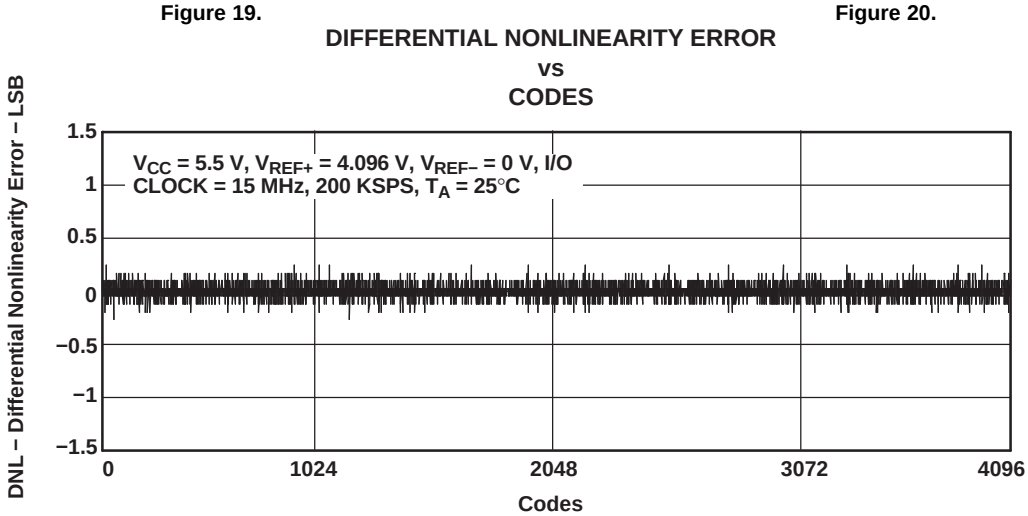


Figure 21.

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

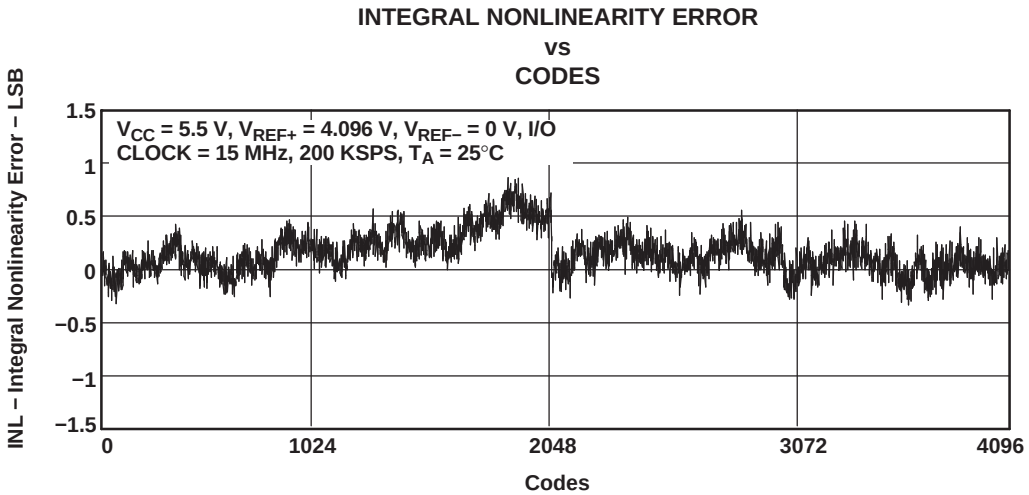


Figure 22.

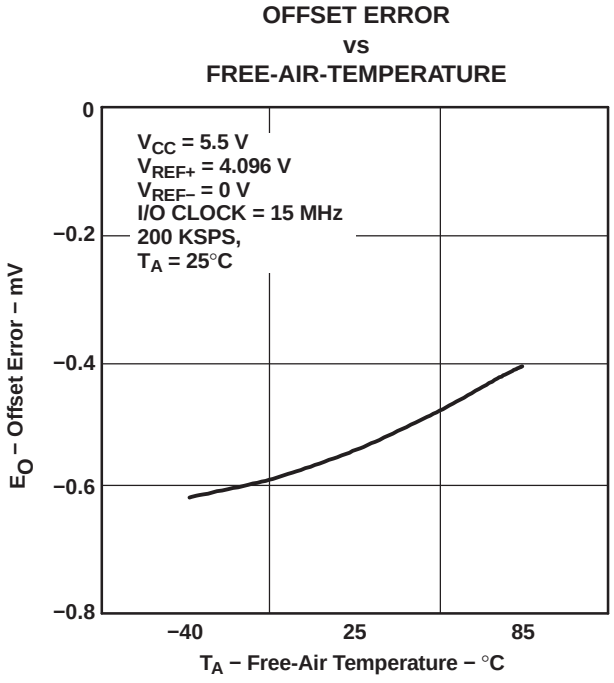


Figure 23.

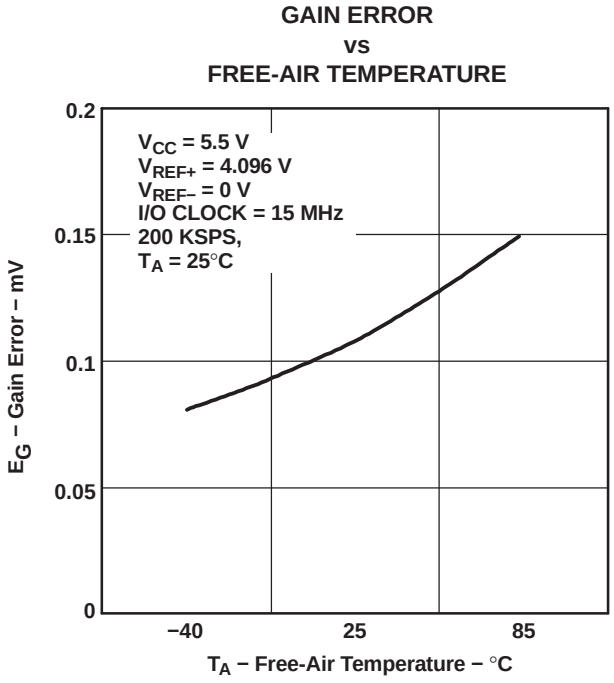


Figure 24.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

SUPPLY CURRENT vs FREE-AIR TEMPERATURE

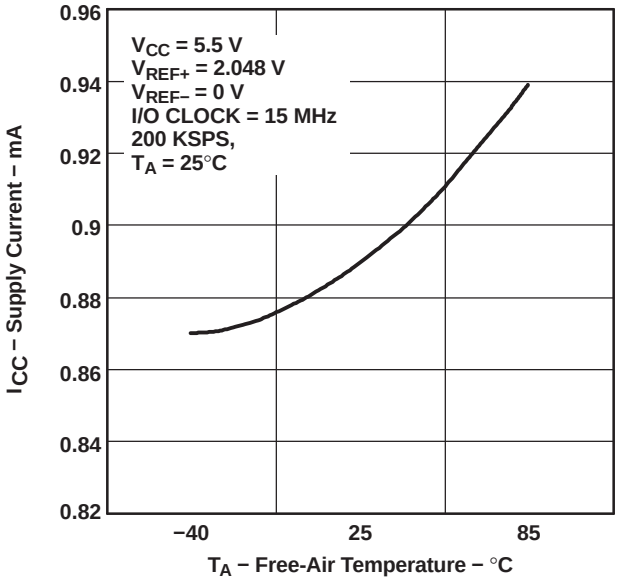


Figure 25.

SOFTWARE POWER DOWN vs FREE-AIR TEMPERATURE

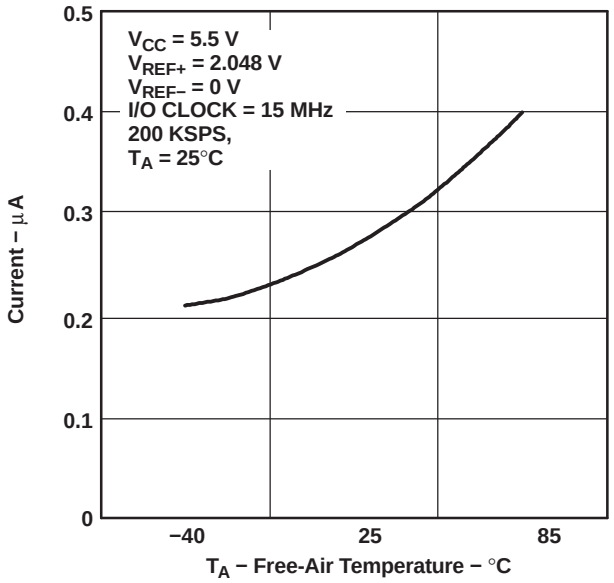


Figure 26.

AUTO POWER DOWN vs FREE-AIR TEMPERATURE

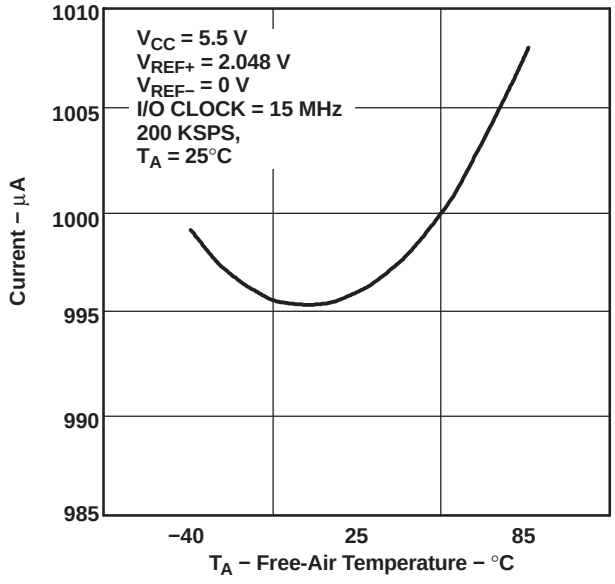


Figure 27.

2-V INTERNAL REFERENCE CURRENT vs FREE-AIR TEMPERATURE

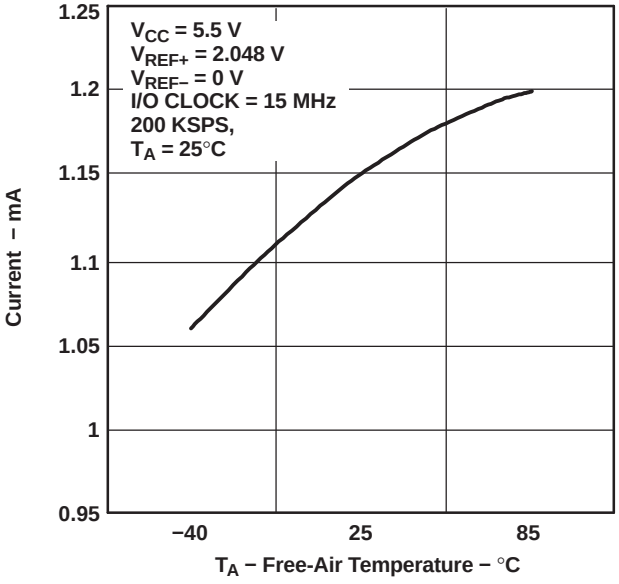


Figure 28.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

MAXIMUM DIFFERENTIAL NONLINEARITY
vs
FREE-AIR TEMPERATURE

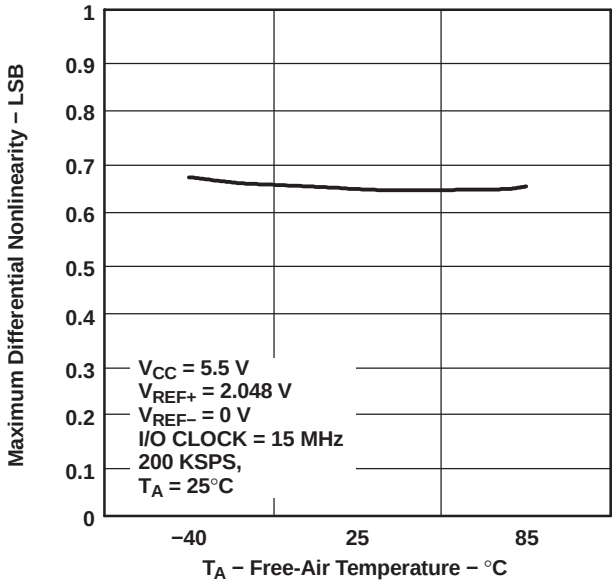


Figure 29.

MINIMUM DIFFERENTIAL NONLINEARITY
vs
FREE-AIR TEMPERATURE

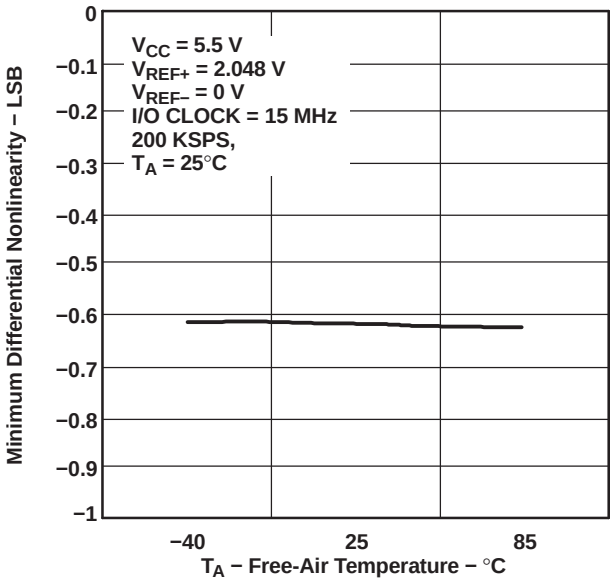


Figure 30.

MAXIMUM INTEGRAL NONLINEARITY
vs
FREE-AIR TEMPERATURE

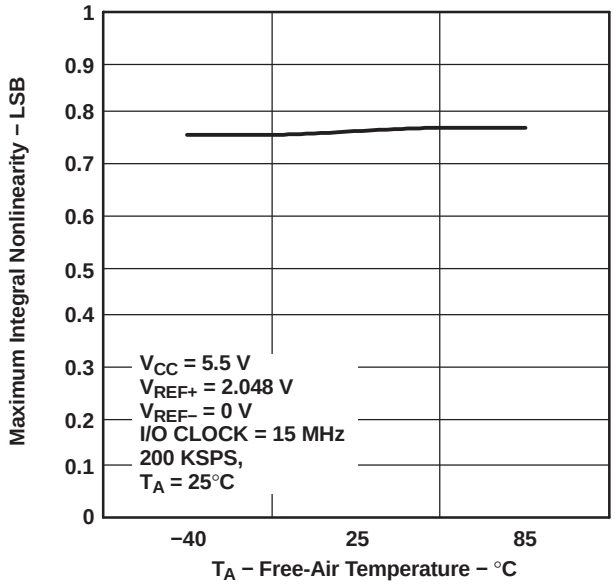


Figure 31.

MINIMUM INTEGRAL NONLINEARITY
vs
FREE-AIR TEMPERATURE

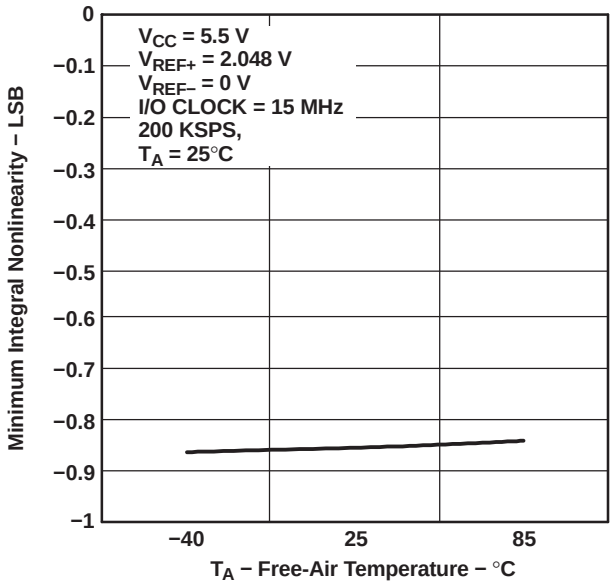


Figure 32.

Copyright © 2008–2009, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

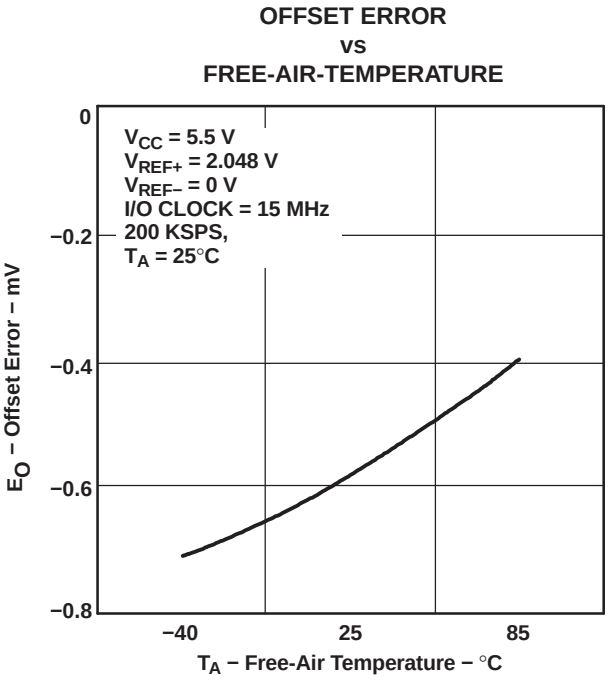


Figure 33.

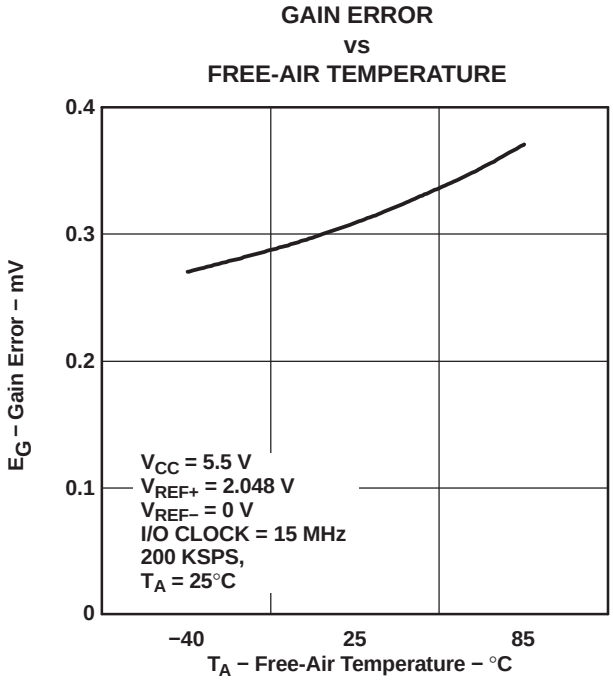


Figure 34.

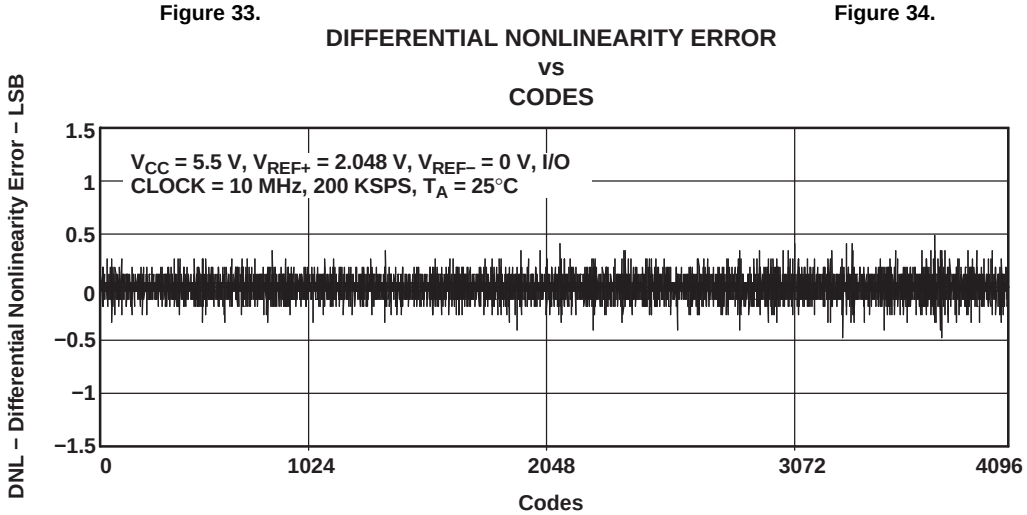


Figure 35.

TYPICAL CHARACTERISTICS (continued)

All typical curves are with internal reference unless specified otherwise. See the TLV2553 data sheet (SLAS354) for typical curves using an external reference.

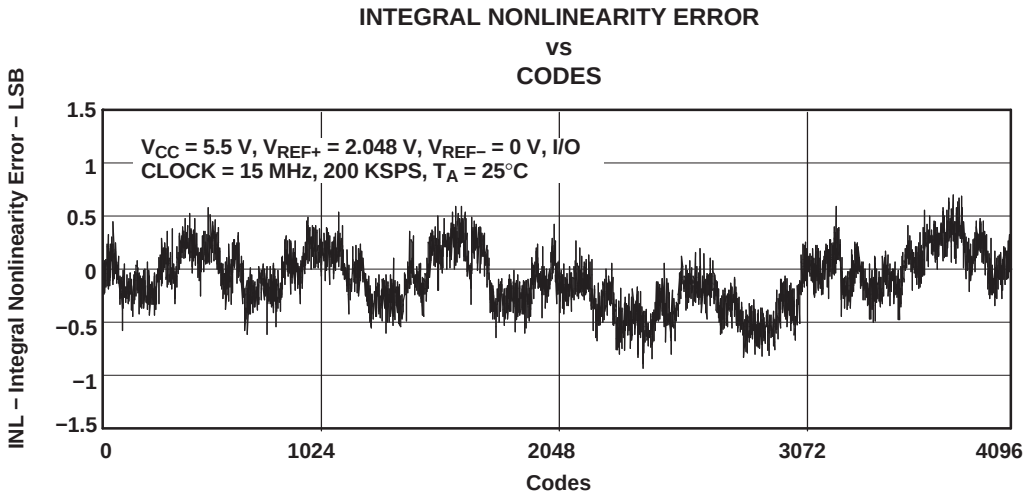


Figure 36.

Copyright © 2008–2009, Texas Instruments Incorporated

PARAMETER MEASUREMENT INFORMATION

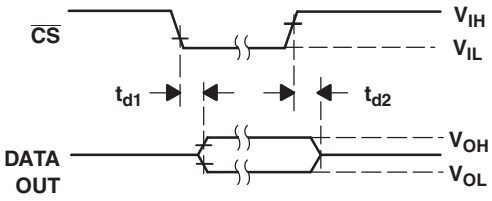


Figure 37. DATA OUT to Hi-Z Voltage Waveforms

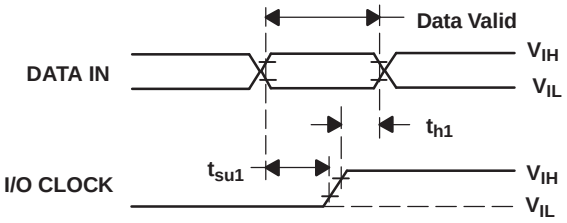


Figure 38. DATA IN and I/O CLOCK Voltage

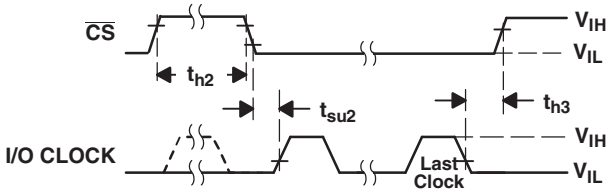


Figure 39. $\overline{CS}$ and I/O CLOCK Voltage Waveforms

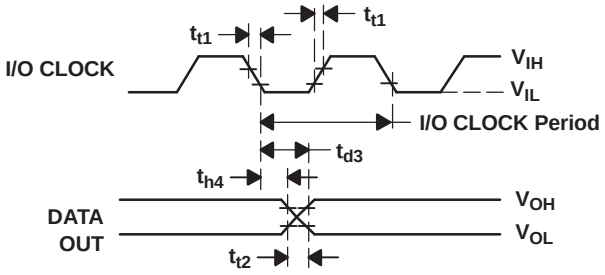


Figure 40. I/O CLOCK and DATA OUT Voltage Waveforms

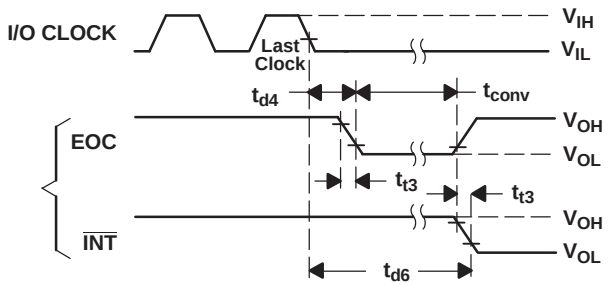


Figure 41. I/O CLOCK and EOC Voltage Waveforms

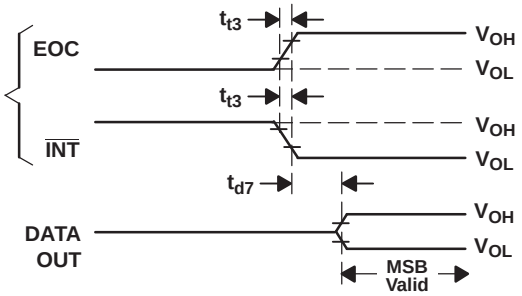


Figure 42. EOC and DATA OUT Voltage Waveforms

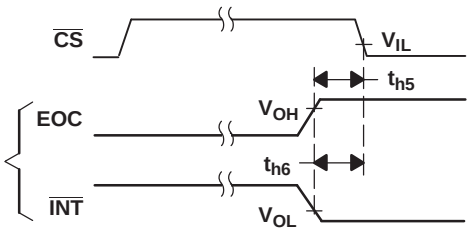


Figure 43. $\overline{CS}$ and EOC Voltage Waveforms

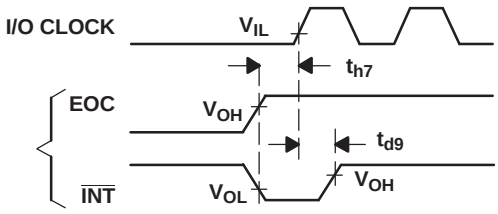


Figure 44. I/O CLOCK and EOC Voltage Waveforms

Copyright © 2008–2009, Texas Instruments Incorporated

PARAMETER MEASUREMENT INFORMATION (continued)

Timing Information

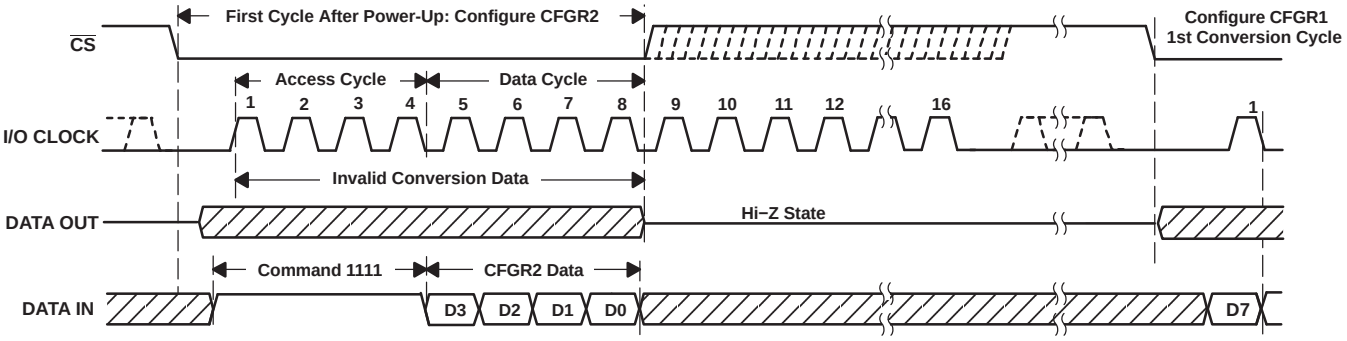
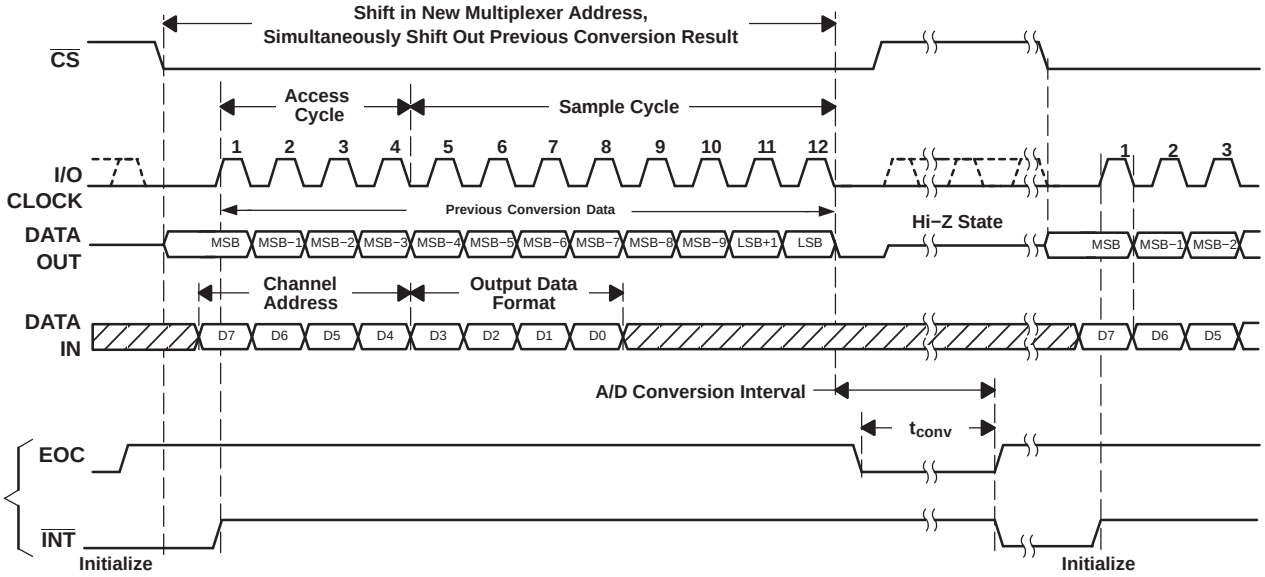


Figure 45. Timing for CFGR2 Configuration

The host must configure CFGR2 before valid device conversions can begin. This can be accessed through command 1111. This can be done using 8, 12, or 16 I/O CLOCK clocks. (A minimum of 8 is required to fully program CFGR2.)

After CFGR2 is configured, the following cycle configures CFGR1 and a valid sample/conversion is performed. $\overline{CS}$ can be held low for each remaining cycle. First valid conversion output data is available on the third cycle after power up.

Timing Diagrams

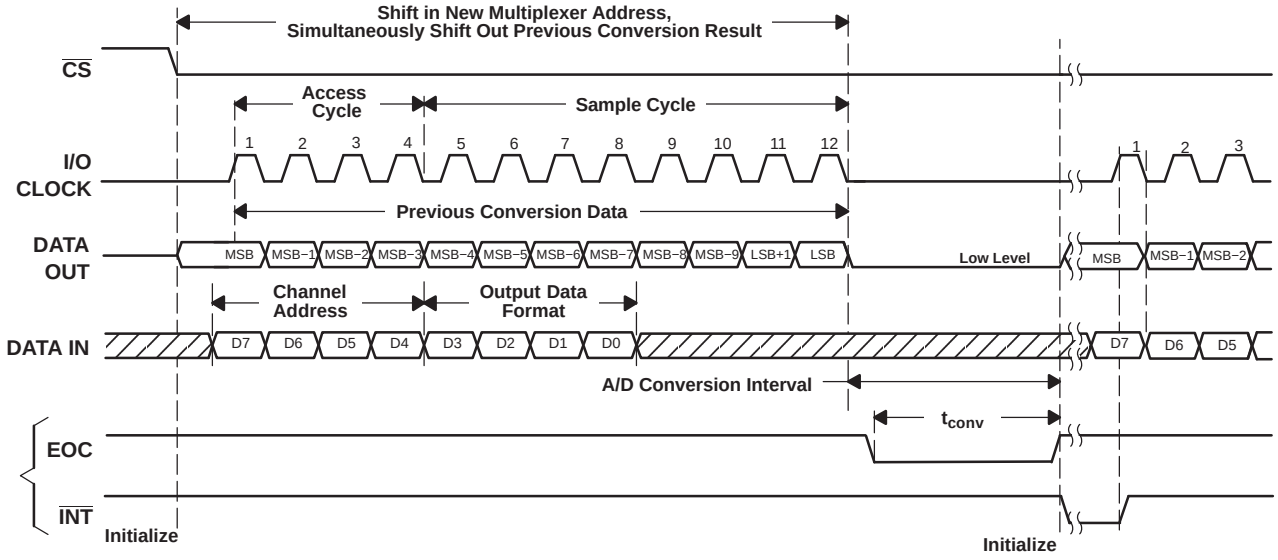


A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

Figure 46. Timing for 12-Clock Transfer Using $\overline{CS}$ With DATA OUT Set for MSB First

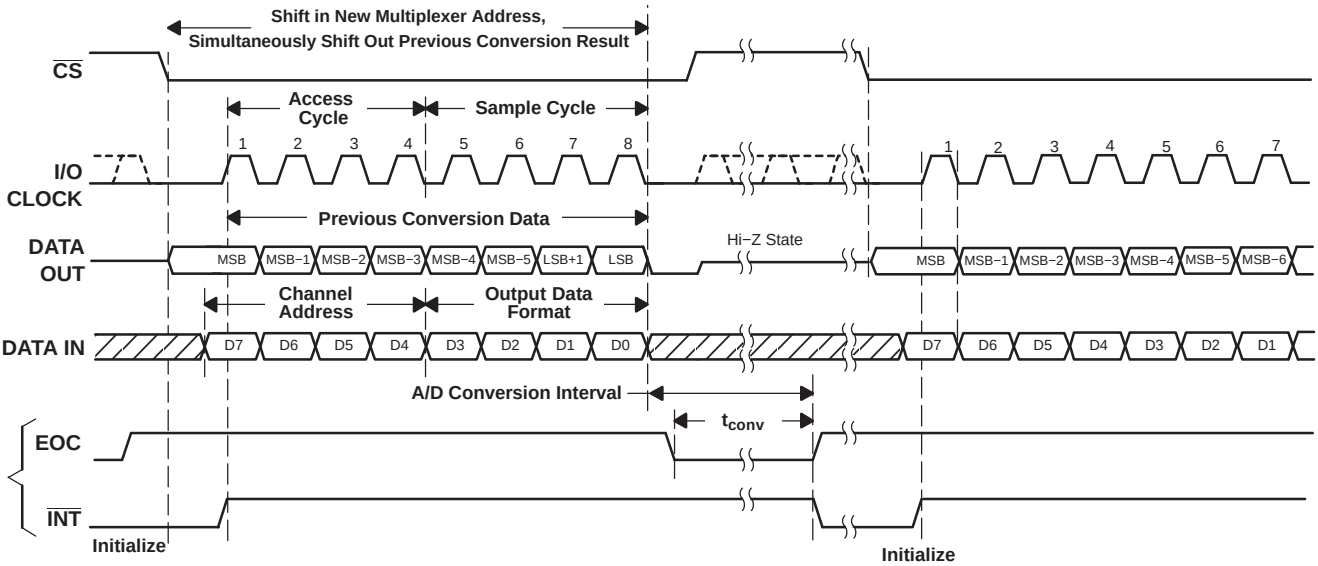
Copyright © 2008–2009, Texas Instruments Incorporated

PARAMETER MEASUREMENT INFORMATION (continued)



A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

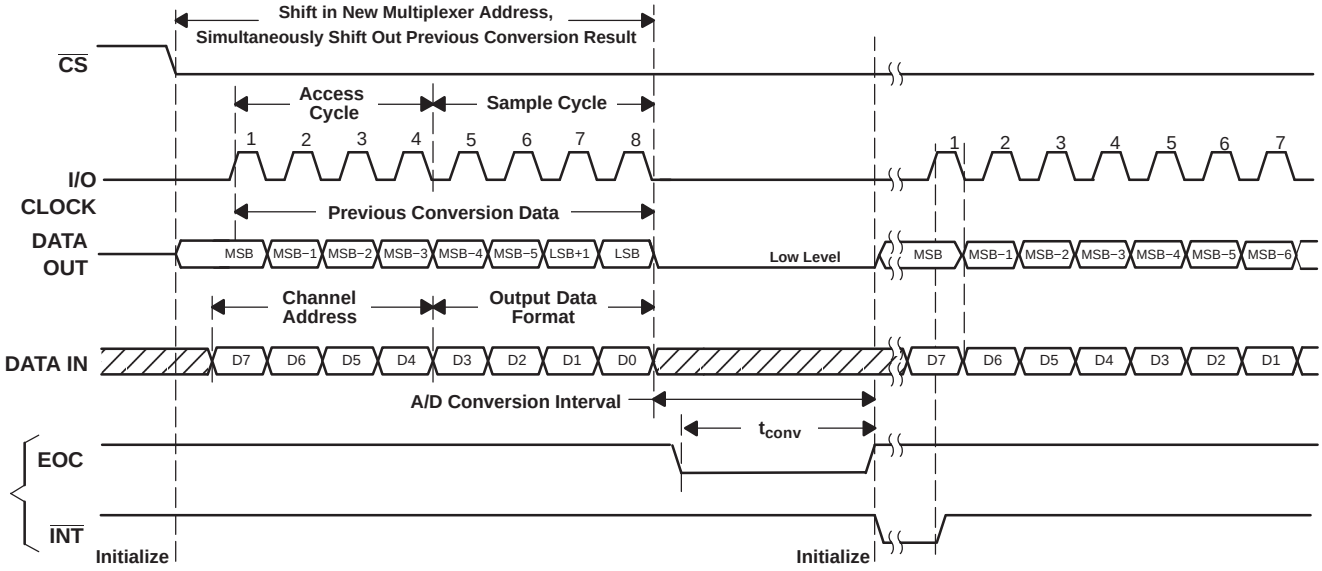
Figure 47. Timing for 12-Clock Transfer Not Using $\overline{CS}$ With DATA OUT Set for MSB First



A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

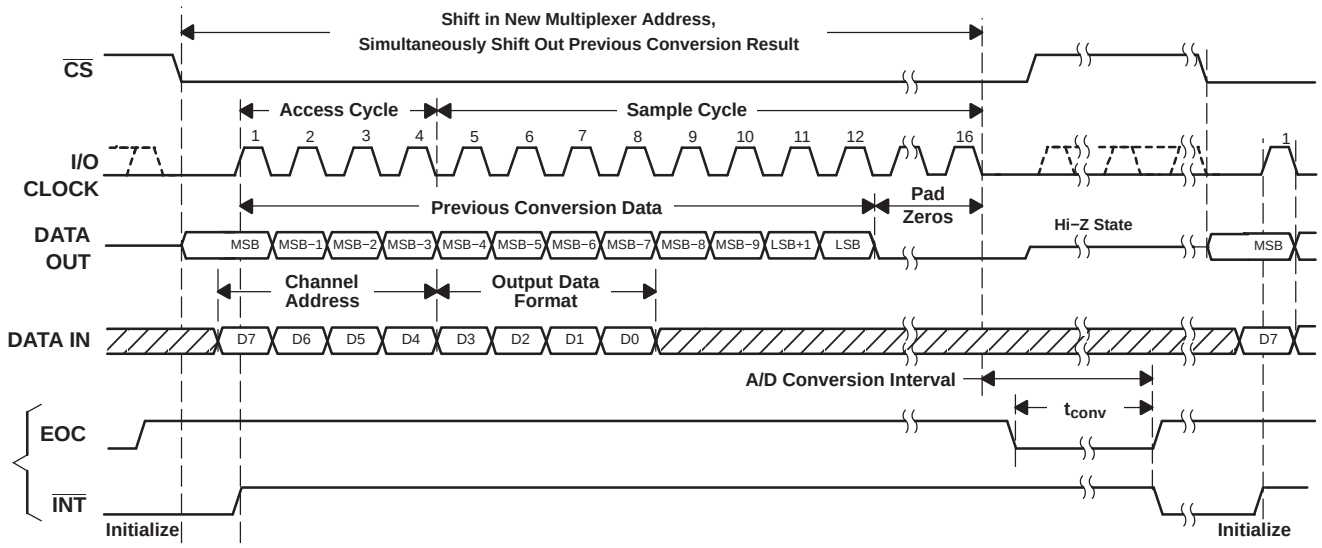
Figure 48. Timing for 8-Clock Transfer Using $\overline{CS}$ With DATA OUT Set for MSB First

PARAMETER MEASUREMENT INFORMATION (continued)



A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

Figure 49. Timing for 8-Clock Transfer Not Using $\overline{CS}$ With DATA OUT Set for MSB First

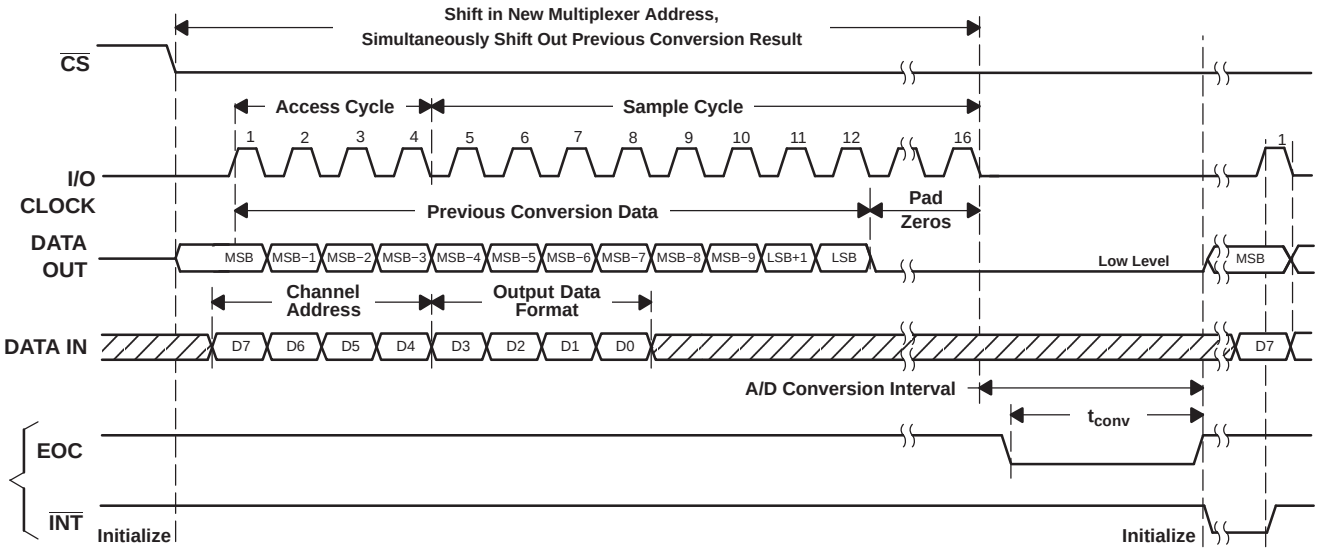


A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

Figure 50. Timing for 16-Clock Transfer Using $\overline{CS}$ With DATA OUT Set for MSB First

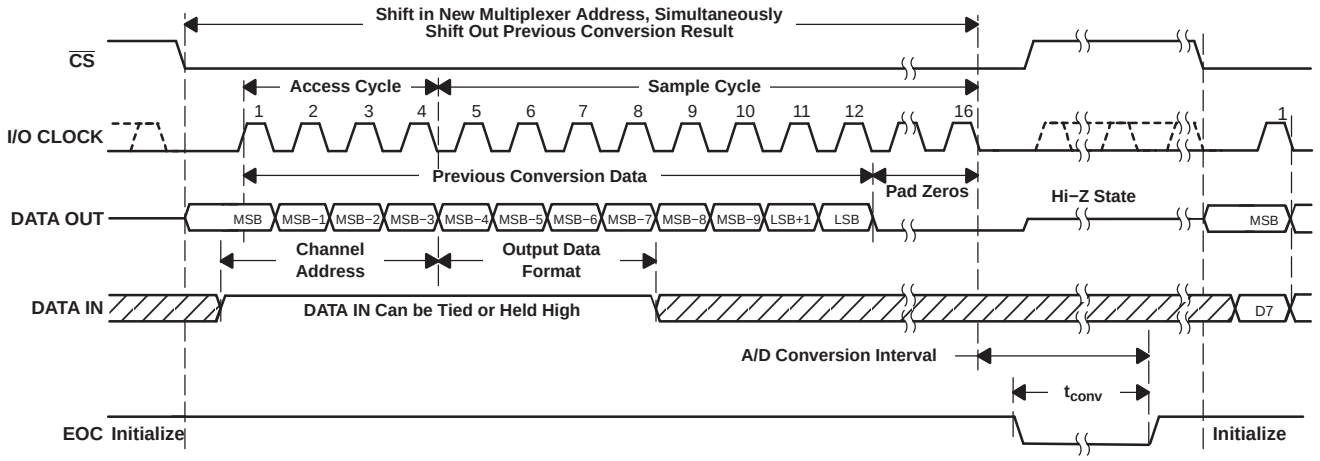
Copyright © 2008–2009, Texas Instruments Incorporated

PARAMETER MEASUREMENT INFORMATION (continued)



A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

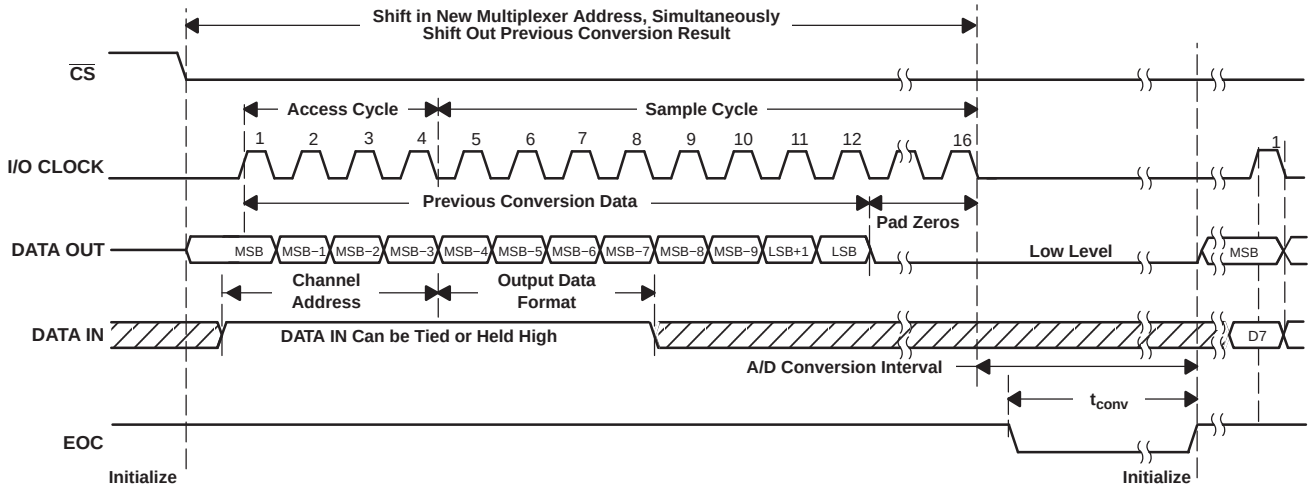
Figure 51. Timing for 16-Clock Transfer Not Using $\overline{CS}$ With DATA OUT Set for MSB First



A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

Figure 52. Timing for Default Mode Using $\overline{CS}$: (16-Clock Transfer, MSB First, External Reference, Pin 19 = EOC, Input = AIN0)

PARAMETER MEASUREMENT INFORMATION (continued)



A. To minimize errors caused by noise at $\overline{CS}$, the internal circuitry waits for a setup time after the $\overline{CS}$ falling edge before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum $\overline{CS}$ setup time has elapsed.

Figure 53. Timing for Default Mode Not Using $\overline{CS}$: (16-Clock Transfer, MSB First, External Reference, Pin 19 = EOC, Input = AIN0)

To remove the device from default mode, CFGR2–D0 must be reset to 0. Valid sample/convert cycles can resume on the cycle following the CFGR2 configuration.

Copyright © 2008–2009, Texas Instruments Incorporated

PRINCIPLES OF OPERATION

Initially, with chip select ($\overline{CS}$) high, I/O CLOCK and DATA IN are disabled and DATA OUT is in the high-impedance state. $\overline{CS}$ going low begins the conversion sequence by enabling I/O CLOCK and DATA IN and removes DATA OUT from the high-impedance state. The input data is an 8-bit data stream consisting of a 4-bit address or command (D7–D4) and a 4-bit configuration data (D3–D0). There are two sets of configuration registers, configuration register 1 – CFGR1 and configuration register 2 – CFGR2. CFGR1, which controls output data format configuration, consists of a 2-bit data length select (D3–D2), an output MSB or LSB first bit (D1), and a unipolar or bipolar output select bit (D0) that are applied to any command (from DATA IN) except for command 1111b. CFGR2, which provides configuration information other than data format, consists of a 2-bit reference select (D3–D2), an EOC/$\overline{INT}$ program bit (D1), and a default mode select bit (D0) that are applied to command 1111b. The I/O CLOCK sequence applied to the I/O CLOCK terminal transfers this data to the input data register. During this transfer, the I/O CLOCK sequence also shifts the previous conversion result from the output data register to DATA OUT. I/O CLOCK receives the input sequence of 8, 12, or 16 clock cycles long depending on the data-length selection in the input data register. Sampling of the analog input begins on the fourth falling edge of the input I/O CLOCK sequence and is held after the last falling edge of the I/O CLOCK sequence. The last falling edge of the I/O CLOCK sequence also takes EOC low (if pin 19 = EOC) and begins the conversion.

Converter Operation

The operation of the converter is organized as a succession of three distinct cycles: 1) the data I/O cycle, 2) the sampling cycle, and 3) the conversion cycle. The first two are partially overlapped.

Data I/O Cycle

The data I/O cycle is defined by the externally provided I/O CLOCK and lasts 8, 12, or 16 clock periods, depending on the selected output data length. During the I/O cycle, the following two operations take place simultaneously. An 8-bit data stream consisting of address/command and configuration information is provided to DATA IN. This data is shifted into the device on the rising edge of the first eight I/O CLOCK clocks. Data input is ignored after the first eight clocks during 12- or 16-clock I/O transfers. The data output, with a length of 8, 12, or 16 bits, is provided serially on DATA OUT. When $\overline{CS}$ is held low, the first output data bit occurs on the rising edge of EOC. When $\overline{CS}$ is toggled between conversions, the first output data bit occurs on the falling edge of $\overline{CS}$. This data is the result of the previous conversion period, and after the first output data bit, each succeeding bit is clocked out on the falling edge of each succeeding I/O CLOCK.

Sampling Period

During the sampling period, one of the analog inputs is internally connected to the capacitor array of the converter to store the analog input signal. The converter starts sampling the selected input immediately after the four address/command bits have been clocked into the input data register. Sampling starts on the fourth falling edge of I/O CLOCK. The converter remains in the sampling mode until the eighth, twelfth, or sixteenth falling edge of I/O CLOCK depending on the data-length selection.

After the 8-bit data stream has been clocked in, DATA IN should be held at a fixed digital level until EOC goes high or $\overline{INT}$ goes low (indicating that the conversion is complete) to maximize the sampling accuracy and minimize the influence of external digital noise.

Conversion Cycle

A conversion cycle is started only after the I/O cycle is completed, which minimizes the influence of external digital noise on the accuracy of the conversion. This cycle is transparent to the user because it is controlled by an internal clock (oscillator). The total conversion time is equal to 13.5 OSC clocks plus a small delay (~25 ns) to start the OSC. During the conversion period, the device performs a successive-approximation conversion on the analog input voltage.

When programmed as EOC, pin 19 goes low at the start of the conversion cycle and goes high when the conversion is complete and the output data register is latched. After EOC goes low, the analog input can be changed without affecting the conversion result. Since the delay from the falling edge of the last I/O CLOCK to the falling edge of EOC is fixed, any time-varying analog input signals can be digitized at a fixed rate without introducing systematic harmonic distortion or noise due to timing uncertainty.

Copyright © 2008–2009, Texas Instruments Incorporated

When programmed as $\overline{\text{INT}}$, pin 19 goes low when the conversion is complete and the output data register is latched. The next I/O CLOCK rising edge clears the $\overline{\text{INT}}$ output. The time from the last I/O CLOCK falling edge to the falling $\overline{\text{INT}}$ edge is equivalent to the EOC delay mentioned above plus the maximum conversion time. $\overline{\text{INT}}$ is cancelled by (or brought to high) by either the next $\overline{\text{CS}}$ falling edge or the next SCLK rising edge (when $\overline{\text{CS}}$ is held low all of the time for multiple cycles). When $\overline{\text{CS}}$ is held low continuously (for multiple cycles) MSB output occurs after the first rising edge of I/O CLOCK after EOC is inactive or the falling edge of $\overline{\text{INT}}$.

Power Up and Initialization

After power up, $\overline{\text{CS}}$ must be taken from high to low to begin an I/O cycle. $\overline{\text{INT}}$/EOC pin is initially high, and both configuration registers are set to all zeroes. The contents of the output data register are random, and the first conversion result should be ignored. To initialize during operation, $\overline{\text{CS}}$ is taken high and is then returned low to begin the next I/O cycle. The first conversion after the device has returned from the power-down state may not read accurately due to internal device settling.

Table 1. Operational Terminology

Current (N) I/O cycle	The entire I/O CLOCK sequence that transfers address and control data into the data register and clocks the digital result from the previous conversion from DATA OUT.
Current (N) conversion cycle	The conversion cycle starts immediately after the current I/O cycle. The end of the current I/O cycle is the last clock falling edge in the I/O CLOCK sequence. The current conversion result is loaded into the output register when conversion is complete.
Current (N) conversion result	The current conversion result is serially shifted out on the next I/O cycle.
Previous (N–1) conversion cycle	The conversion cycle just prior to the current I/O cycle
Next (N+1) I/O cycle	The I/O period that follows the current conversion cycle

Example

In 12-bit mode, the result of the current conversion cycle is a 12-bit serial-data stream clocked out during the next I/O cycle. The current I/O cycle must be exactly 12 bits long to maintain synchronization, even when this corrupts the output data from the previous conversion. The current conversion is begun immediately after the twelfth falling edge of the current I/O cycle.

Default Mode

When the DATA IN pin is held high, the ADC goes into hardware default mode because the CFGR2 bits are all programmed to the default values after eight I/O CLOCK cycles. This means the ADC is programmed for an external reference and pin 19 as EOC. In addition, channel AIN0 is selected. The first conversion is invalid therefore the conversion result should be ignored. On the next cycle, AIN0 is sampled and converted. This mode of operation is valid when $\overline{\text{CS}}$ is toggled or held low after the first cycle.

To remove the device from hardware default mode, CFGR2 bit D0 must be reset to 0. Once this is done, the host must program CFGR1 on the next cycle and disregard the result from the current cycle's conversion.

Data Input

The data input is internally connected to an 8-bit serial-input address and control register. The register defines the operation of the converter and the output data length. The host provides the input data byte with the MSB first. Each data bit is clocked in on the rising edge of the I/O CLOCK sequence (see Table 2 for the data input-register format).

Copyright © 2008–2009, Texas Instruments Incorporated

Table 2. Command Set (CMR) and Configuration

SDI D[7:4] Binary,	HEX	COMMAND
0000b	0h	SELECT analog input channel 0
0001b	1h	SELECT analog input channel 1
0010b	2h	SELECT analog input channel 2
0011b	3h	SELECT analog input channel 3
0100b	4h	SELECT analog input channel 4
0101b	5h	SELECT analog input channel 5
0110b	6h	SELECT analog input channel 6
0111b	7h	SELECT analog input channel 7
1000b	8h	SELECT analog input channel 8
1001b	9h	SELECT analog input channel 9
1010b	Ah	SELECT analog input channel 10
1011b	Bh	SELECT TEST, Voltage = (VREF+ + VREF−)/2
1100b	Ch	SELECT TEST, Voltage = REFM
1101b	Dh	SELECT TEST, Voltage = REFP
1110b	Eh	SW POWERDOWN (analog + reference)
1111b	Fh	ACCESS CFGR2

CFGR1

SDI D[3:0]	CONFIGURATION
D[3:2]	01: 8-bit output length X0: 12-bit output length 11: 16-bit output length (default)
D1	0: MSB out first (default) 1: LSB out first
D0	0: Unipolar binary (default) 1: Bipolar 2s complement

CFGR2

SDI D[3:0]	CONFIGURATION
D[3:2]	00: Internal 4.096 reference 01: Internal 2.048 reference 11: External reference (default)
D1	0: Pin 19 output EOC (default) 1: Pin 19 output $\overline{\text{Int}}$
D0	0: Normal mode (CFGR1 needs to be programmed) 1: Default mode enabled (D[3:0] of CFGR1 and D[3:1] of CFGR2 set to default)

Data Input – Address/Command Bits

The four MSBs (D7–D4) of the input data register are the address or command. These bits can be used to address one of the 11 input channels, select one of three reference-test voltages, activate the software power-down mode, or access the second configuration register, CFGR2. All address/command bits affect the current conversion, which is the conversion that immediately follows the current I/O cycle. They also allow access to CFGR1 except for command 1111b, which allows access to CFGR2.

Data Output Length

CFGR1 bits (D3 and D2) of the data register select the output data length. The data-length selection is valid for the current I/O cycle (the cycle in which the data is read). The data-length selection, being valid for the current I/O cycle, allows device start-up without losing I/O synchronization. A data length of 8, 12, or 16 bits can be selected. Since the converter has 12-bit resolution, a data length of 12 bits is suggested.

With D3 and D2 set to 00 or 10, the device is in the 12-bit data-length mode and the result of the current conversion is output as a 12-bit serial data stream during the next I/O cycle. The current I/O cycle must be exactly 12 bits long for proper synchronization, even when this means corrupting the output data from a previous conversion. The current conversion is started immediately after the twelfth falling edge of the current I/O cycle.

Copyright © 2008–2009, Texas Instruments Incorporated

With bits D3 and D2 set to 11, the 16-bit data-length mode is selected, which allows convenient communication with 16-bit serial interfaces. In the 16-bit mode, the result of the current conversion is output as a 16-bit serial data stream during the next I/O cycle with the four LSBs always reset to 0 (pad bits). The current I/O cycle must be exactly 16 bits long to maintain synchronization even when this means corrupting the output data from the previous conversion. The current conversion is started immediately after the sixteenth falling edge of the current I/O cycle.

With bits D3 and D2 set to 01, the 8-bit data-length mode is selected, which allows fast communication with 8-bit serial interfaces. In the 8-bit mode, the result of the current conversion is output as an 8-bit serial data stream during the next I/O cycle. The current I/O cycle must be exactly eight bits long to maintain synchronization, even when this means corrupting the output data from the previous conversion. The four LSBs of the conversion result are truncated and discarded. The current conversion is started immediately after the eighth falling edge of the current I/O cycle.

Because the D3 and D2 register settings take effect on the I/O cycle when the data length is programmed, there can be a conflict with the previous cycle if the data-word length was changed. This may occur when the data format is selected to be least significant bit first, since at the time the data length change becomes effective (six rising edges of I/O CLOCK), the previous conversion result has already started shifting out. In actual operation, when different data lengths are required within an application and the data length is changed between two conversions, no more than one conversion result can be corrupted and only when it is shifted out in LSB-first format.

LSB Out First

D1 in the CFGR1 controls the direction of the output (binary) data transfer. When D1 is reset to 0, the conversion result is shifted out MSB first. When set to 1, the data is shifted out LSB first. Selection of MSB first or LSB first always affects the next I/O cycle and not the current I/O cycle. When changing from one data direction to another, the current I/O cycle is never disrupted.

Bipolar Output Format

D0 in the CFGR1 controls the binary data format used to represent the conversion result. When D0 is cleared to 0, the conversion result is represented as unipolar (unsigned binary) data. Nominally, the conversion result of an input voltage equal to or less than $V_{REF–}$ is a code with all zeros (000...0) and the conversion result of an input voltage equal to or greater than V_{REF+} is a code of all ones (111...1). The conversion result of (V_{REF+} + $V_{REF–}$)/2 is a code of a one followed by zeros (100 ...0).

When D0 is set to 1, the conversion result is represented as bipolar (signed binary) data. Nominally, conversion of an input voltage equal to or less than $V_{REF–}$ is a code of a one followed by zeros (100...0), and the conversion of an input voltage equal to or greater than V_{REF+} is a code of a zero followed by all ones (011...1). The conversion result of (V_{REF+} + $V_{REF–}$)/2 is a code of all zeros (000...0). The MSB is interpreted as the sign bit. The bipolar data format is related to the unipolar format in that the MSBs are always each other's complement.

Selection of the unipolar or bipolar format always affects the current conversion cycle, and the result is output during the next I/O cycle. When changing between unipolar and bipolar formats, the data output during the current I/O cycle is not affected.

Reference

The device has a built-in reference with a programmable level of 2.048 V or 4.096 V. If the internal reference is used, REF+ is set to 2.048 V or 4.096 V and REF– is set to analog GND. An external reference can also be used through two reference input pins, REF+ and REF–, if the reference source is programmed as external. The voltage levels applied to these pins establish the upper and lower limits of the analog inputs to produce a full-scale and zero-scale reading respectively. The values of REF+, REF–, and the analog input should not exceed the positive supply or be lower than GND consistent with the specified absolute maximum ratings. The digital output is at full scale when the input signal is equal to or higher than REF+ and at zero when the input signal is equal to or lower than REF–.

Copyright © 2008–2009, Texas Instruments Incorporated

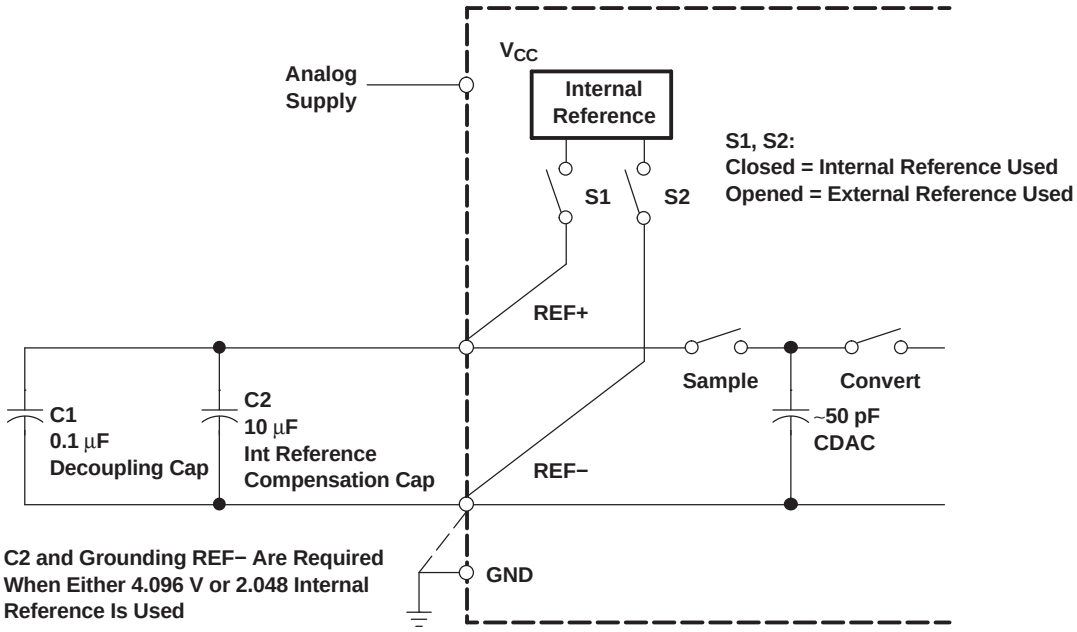


Figure 54. Reference Block

$\overline{\text{INT}}$/EOC Output

Pin 19 outputs the status of the ADC conversion. When programmed as EOC, the output indicates the beginning and the end of conversion. In the reset state, EOC is always high. During the sampling period (beginning after the fourth falling edge of the I/O CLOCK sequence), EOC remains high until the internal sampling switch of the converter is safely opened. The opening of the sampling switch occurs after the eighth, twelfth, or sixteenth I/O CLOCK falling edge, depending on the data-length selection in the input data register. After the EOC signal goes low, the analog input signal can be changed without affecting the conversion result.

The EOC signal goes high again after the conversion is completed and the conversion result is latched into the output data register. The rising edge of EOC returns the converter to a reset state and a new I/O cycle begins. On the rising edge of EOC, the first bit of the current conversion result is on DATA OUT when $\overline{\text{CS}}$ is low. When $\overline{\text{CS}}$ is toggled between conversions, the first bit of the current conversion result occurs on DATA OUT at the falling edge of $\overline{\text{CS}}$.

When programmed as $\overline{\text{INT}}$, the output indicates that the conversion is completed and the output data is ready to be read. In the reset state, $\overline{\text{INT}}$ is always high. $\overline{\text{INT}}$ is high during the sampling period and until the conversion is complete. After the conversion is finished and the output data is latched, $\overline{\text{INT}}$ goes low and remains low until it is cleared by the host. When $\overline{\text{CS}}$ is held low, the MSB (or LSB) of the conversion result is presented on DATA OUT on the falling edge of $\overline{\text{INT}}$. A rising I/O CLOCK edge clears the interrupt.

Chip-Select Input ($\overline{\text{CS}}$)

$\overline{\text{CS}}$ enables and disables the device. During normal operation, $\overline{\text{CS}}$ should be low. Although the use of $\overline{\text{CS}}$ is not necessary to synchronize a data transfer, it can be brought high between conversions to coordinate the data transfer of several devices sharing the same bus.

When $\overline{\text{CS}}$ is brought high, the serial-data output is immediately brought to the high-impedance state, releasing its output data line to other devices that may share it. After an internally generated debounce time, I/O CLOCK is inhibited, thus preventing any further change in the internal state.

When $\overline{\text{CS}}$ is subsequently brought low again, the device is reset. $\overline{\text{CS}}$ must be held low for an internal debounce time before the reset operation takes effect. After $\overline{\text{CS}}$ is debounced low, I/O CLOCK must remain inactive (low) for a minimum time before a new I/O cycle can start.

Copyright © 2008–2009, Texas Instruments Incorporated

$\overline{CS}$ can interrupt any ongoing data transfer or any ongoing conversion. When $\overline{CS}$ is debounced low long enough before the end of the current conversion cycle, the previous conversion result is saved in the internal output buffer and shifted out during the next I/O cycle.

When $\overline{CS}$ is held low continuously for multiple cycles, the first data bit of the newly completed conversion occurs on DATA OUT on the rising edge of EOC or falling edge of $\overline{INT}$. Note that the first cycle in the series still requires a transition of $\overline{CS}$ from high to low. When a new conversion is started after the last falling edge of I/O CLOCK, EOC goes low and the serial output is forced low until EOC goes high again.

When $\overline{CS}$ is toggled between conversions, the first data bit occurs on DATA OUT on the falling edge of $\overline{CS}$. On each subsequent falling edge of I/O CLOCK after the first data bit appears, the data is changed to the next bit in the serial conversion result until the required number of bits has been output.

Power-Down Features

When command (D7–D4) 1110b is clocked into the input data register during the first four I/O CLOCK cycles, the software power-down mode is selected. Software power down is activated on the falling edge of the fourth I/O CLOCK pulse.

During software power down, all internal circuitry is put in a low-current standby mode. The internal reference (if being used) is powered down. No conversion is performed. The internal output buffer keeps the previous conversion cycle data results provided that all digital inputs are held above V_{CC} – 0.5 V or below 0.5 V. The I/O logic remains active so the current I/O cycle must be completed even when the power-down mode is selected. Upon power-on reset and before the first I/O cycle, the converter normally begins in the power-down mode. The device remains in the software power-down mode until a valid input address (other than command 1110b) is clocked in. Upon completion of that I/O cycle, a normal conversion is performed with the results being shifted out during the next I/O cycle. If using the internal reference, care must be taken to allow the reference to power on completely before a valid conversion can be performed. It requires 1 ms to resume from a software power down.

The ADC also has an auto power-down mode. This is transparent to users. The ADC goes into auto power down within one I/O CLOCK cycle after the conversion is complete and resumes, with a small delay after an active $\overline{CS}$ is sent to the ADC. This mode keeps built-in reference so resumption is fast enough to be used between cycles.

Analog Multiplexer

The 11 analog inputs, three internal voltages, and power-down mode are selected by the input multiplexer according to the input addresses shown in Table 2. The input multiplexer is a break-before-make type to reduce input-to-input noise rejection resulting from channel switching. Sampling of the analog inputs starts on the falling edge of the fourth I/O CLOCK and continues for the remaining I/O CLOCK pulses. The sample is held on the falling edge of the last I/O CLOCK pulse. The three internal test inputs are applied to the multiplexer, then sampled and converted in the same manner as the external analog inputs. The first conversion after the device has returned from the power-down state may not read accurately due to internal device settling.

Copyright © 2008–2009, Texas Instruments Incorporated

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TLV2556MPWREP	Active	Production	TSSOP (PW) | 20	2000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-55 to 125	TL2556EP
TLV2556MPWREP.A	Active	Production	TSSOP (PW) | 20	2000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-55 to 125	TL2556EP
V62/08622-01XE	Active	Production	TSSOP (PW) | 20	2000 | LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-55 to 125	TL2556EP

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF TLV2556-EP :

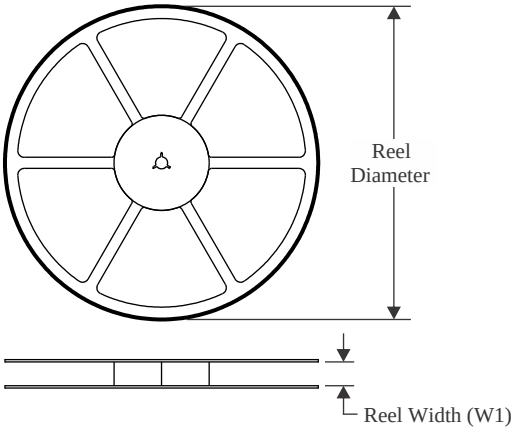
- Catalog : TLV2556

NOTE: Qualified Version Definitions:

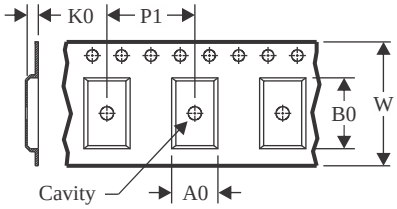
- Catalog - TI's standard catalog product

TAPE AND REEL INFORMATION

REEL DIMENSIONS

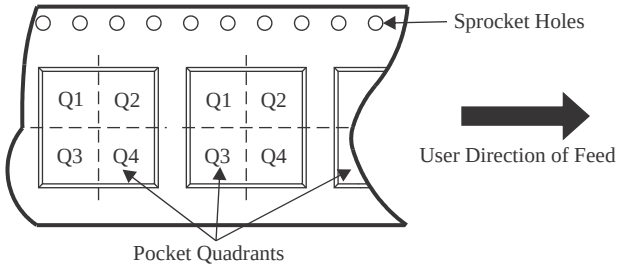


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

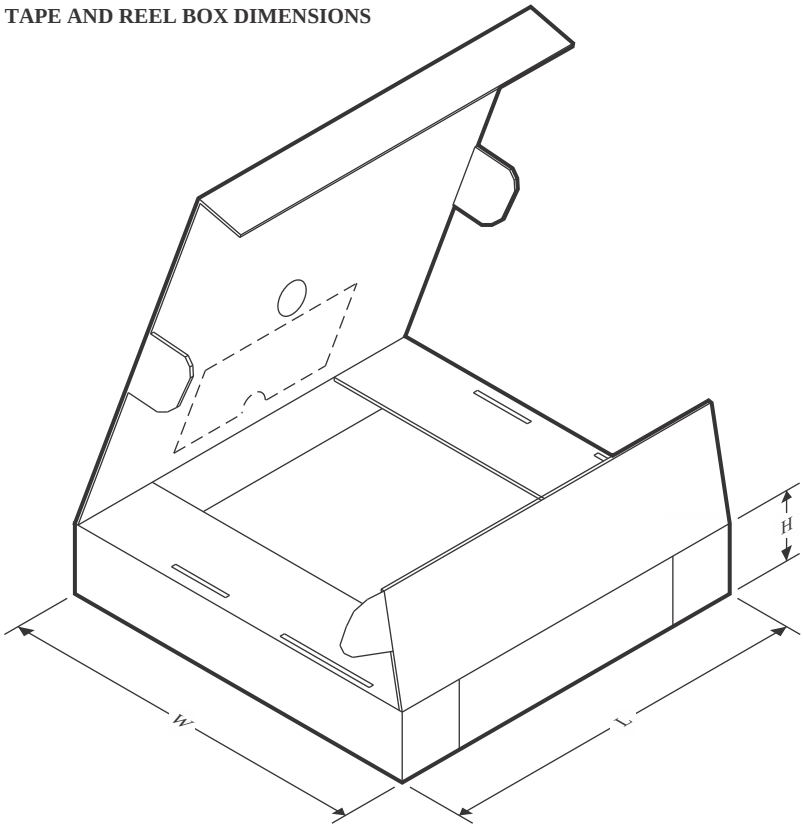
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TLV2556MPWREP	TSSOP	PW	20	2000	330.0	16.4	6.95	7.1	1.6	8.0	16.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

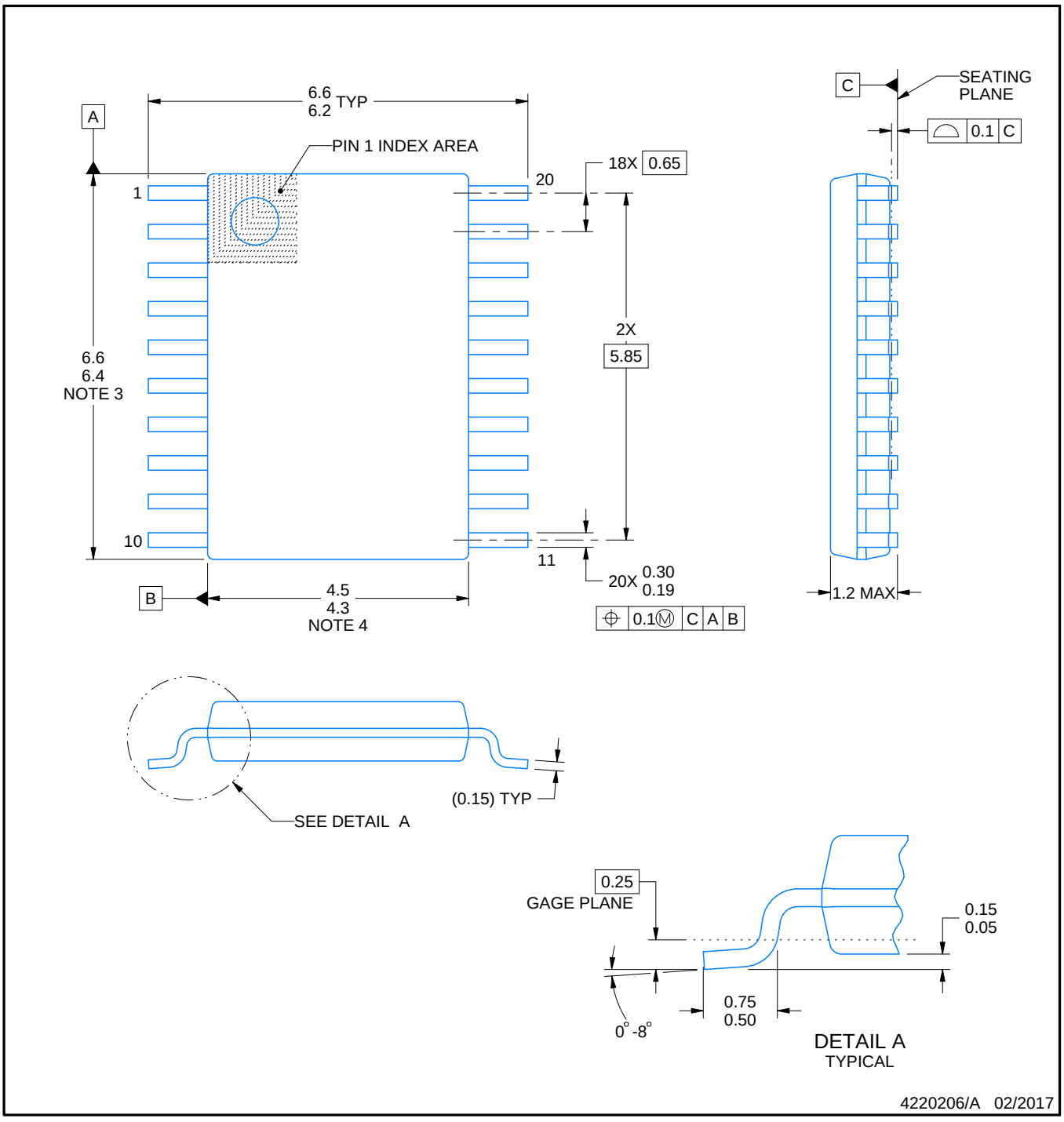
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TLV2556MPWREP	TSSOP	PW	20	2000	350.0	350.0	43.0

PACKAGE OUTLINE

PW0020A

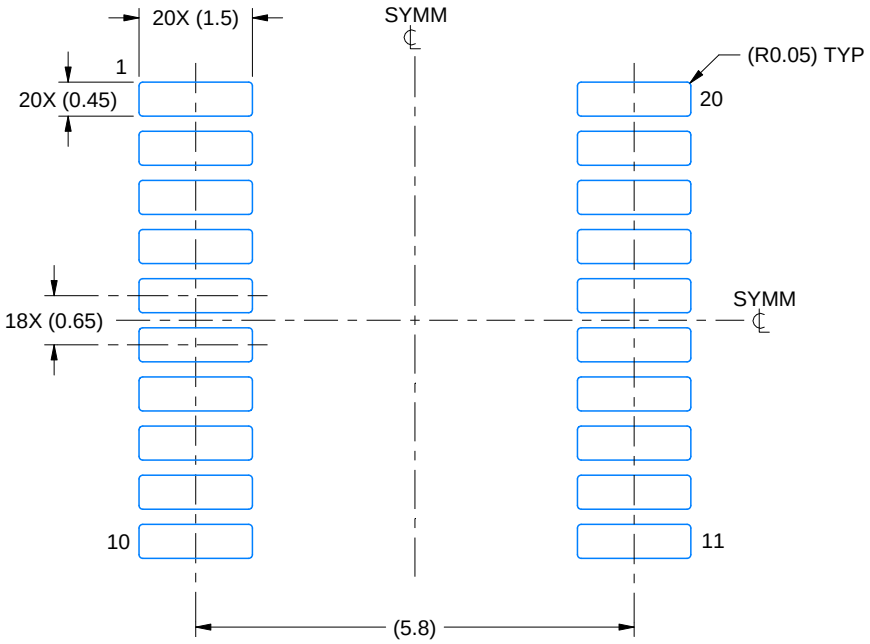
TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-153.



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 10X

NON-SOLDER MASK DEFINED (PREFERRED)

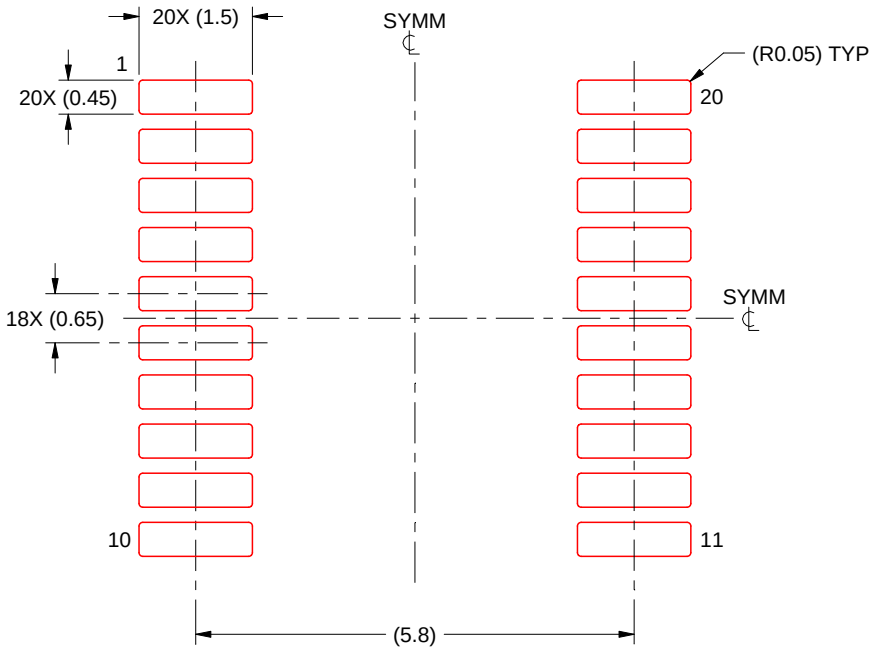
SOLDER MASK DEFINED

SOLDER MASK DETAILS

4220206/A 02/2017

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE: 10X

4220206/A 02/2017

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES “AS IS” AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI’s products are provided subject to TI’s Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI’s provision of these resources does not expand or otherwise alter TI’s applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated