

## WIDE-INPUT-RANGE NONSYNCHRONOUS VOLTAGE-MODE CONTROLLER

Check for Samples: [TPS40200-EP](#)

### FEATURES

- **Controlled Baseline**
  - One Assembly/Test Site, One Fabrication Site
- **Extended Temperature Performance of –55°C to 125°C**
- **Enhanced Diminishing Manufacturing Sources (DMS) Support**
- **Enhanced Product-Change Notification**
- **Qualification Pedigree <sup>(1)</sup>**
- **Input Voltage Range 4.5 V to 52 V**
- **Output Voltage (700 mV to 87%  $V_{in}$ )**
- **200-mA Internal P-Channel FET Driver**

(1) Component qualification in accordance with JEDEC and industry standards to ensure reliable operation over an extended temperature range. This includes, but is not limited to, Highly Accelerated Stress Test (HAST) or biased 85/85, temperature cycle, autoclave or unbiased HAST, electromigration, bond intermetallic life, and mold compound life. Such qualification testing should not be viewed as justifying use of this component beyond specified performance and environmental limits.

- **Voltage Feed-Forward Compensation**
- **Undervoltage Lockout**
- **Programmable Fixed-Frequency (35 kHz to 500 kHz) Operation**
- **Programmable Short-Circuit Protection**
- **Hiccup Overcurrent Fault Recovery**
- **Programmable Closed-Loop Soft Start**
- **700-mV 1% Reference Voltage**
- **External Synchronization**
- **Small 8-Pin Small-Outline Integrated Circuit (SOIC) (D) Package**

### APPLICATIONS

- **Industrial Control**
- **Distributed Power Systems**
- **DSL/Cable Modems**
- **Scanners**
- **Telecom**

### DESCRIPTION

The TPS40200 is a flexible nonsynchronous controller with a built-in 200-mA driver for P-channel FETs. The circuit operates with inputs up to 52 V, with a power-saving feature that turns off driver current once the external FET has been fully turned on. This feature extends the flexibility of the device, allowing it to operate with an input voltage up to 52 V, without dissipating excessive power. The circuit operates with voltage-mode feedback and has feed-forward input-voltage compensation that responds instantly to input-voltage change. The integral 700-mV reference is trimmed to 2%, providing the means to accurately control low voltages. The TPS40200 is available in an 8-pin SOIC, and supports many of the features of more complex controllers. Clock frequency, soft start, and overcurrent limit each are easily programmed by a single, external component. The part has undervoltage lockout, and can be easily synchronized to other controllers or a system clock to satisfy sequencing and/or noise-reduction requirements.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## TYPICAL APPLICATION

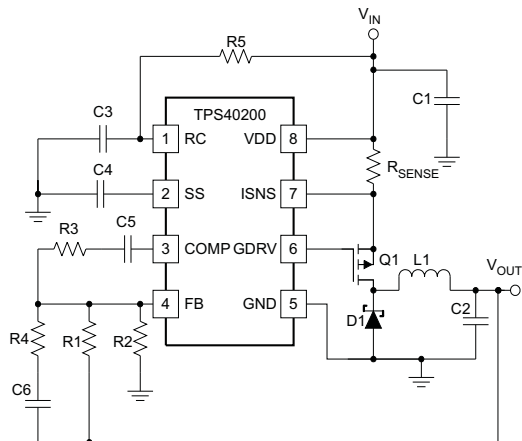


Figure 1. 12-V to 5-V Buck Converter With 94% Efficiency

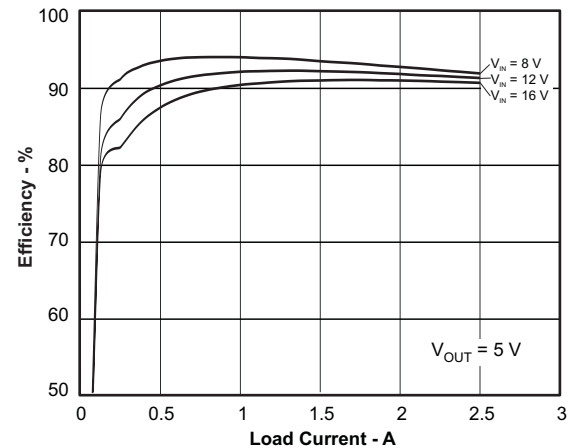


Figure 2. Typical Efficiency of Application Circuit 1 (Described in [Application 1](#))

## ELECTROSTATIC DISCHARGE (ESD) PROTECTION

	MIN	MAX	UNIT
Human-Body Model		1000	V
CDM		1500	V

## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

			UNIT
Input voltage range	V <sub>DD</sub> , ISNS	52	V
	RC, FB	–0.3 to 5.5	
	SS	–0.3 to 9	
Output voltage range	COMP	–0.3 to 9	V
	GDRV	(V <sub>IN</sub> – 10) to V <sub>IN</sub>	
T <sub>J</sub>	Operating virtual junction temperature range	–55 to 150	°C
T <sub>stg</sub>	Storage temperature range	–55 to 150	°C
Lead temperature 1,6 mm (1/16 in) from case for 10 s		260	°C

- (1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## RECOMMENDED OPERATING CONDITIONS

	MIN	MAX	UNIT
V <sub>DD</sub> Input voltage	4.5	52	V

## ELECTRICAL CHARACTERISTICS

–55°C < T<sub>A</sub> = T<sub>J</sub> < 125°C, V<sub>DD</sub> = 12 V, f<sub>OSC</sub> = 100 kHz (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
Voltage Reference							
V <sub>FB</sub>	Feedback voltage	COMP = FB, T <sub>J</sub> = 25°C		689	696	702	mV
		4.5 V < V <sub>DD</sub> < 52 V	T <sub>J</sub> = 25°C	686	696	703	
			–40°C < T <sub>J</sub> < 125°C	679	696	710	
			–55°C < T <sub>J</sub> < 125°C	675	696	710	
Gate Driver							
I <sub>src</sub>	Gate driver pullup current			125	300		mA
I <sub>snk</sub>	Gate driver pulldown current			200	300		mA
V <sub>GATE</sub>	Gate driver output voltage	V <sub>GATE</sub> = (V <sub>DD</sub> – V <sub>GDRV</sub> ), for 12 V < V <sub>DD</sub> < 52 V		6	8	10	V
Quiescent Current							
I <sub>qq</sub>	Device quiescent current	F <sub>OSC</sub> = 300 kHz, Driver not switching, 4.5 V < V <sub>DD</sub> < 52 V			1.5	3	mA
Undervoltage Lockout (UVLO)							
V <sub>UVLO(on)</sub>	Turnon threshold			3.8	4.25	4.5	V
V <sub>UVLO(off)</sub>	Turnoff threshold				4.05		
V <sub>UVLO(HYST)</sub>	Hysteresis			110	200	275	mV
Soft Start							
R <sub>SS(chg)</sub>	Internal soft-start pullup resistance			65	105	170	kΩ
R <sub>SS(dchg)</sub>	Internal soft-start pulldown resistance			190	305	485	kΩ
V <sub>SSRST</sub>	Soft-start reset threshold			100	150	200	mV
Overcurrent Protection							
V <sub>ILIM</sub>	Overcurrent threshold	4.5 V < V <sub>DD</sub> < 52 V	0°C < T <sub>J</sub> < 125°C	65	100	140	mV
			–40°C < T <sub>J</sub> < 125°C	55	100	140	
			–55°C < T <sub>J</sub> < 125°C	35	100	150	
OC <sub>DF</sub>	Overcurrent duty cycle <a href="#">Note 1</a>					2	%
V <sub>ILIM(rst)</sub>	Overcurrent reset threshold			100	150	200	mV
Oscillator							
F <sub>OSC</sub>	Oscillator frequency range <a href="#">Note</a>			35		500	kHz
	Oscillator frequency	R <sub>RC</sub> = 200 kΩ, C <sub>RC</sub> = 470 pF		85	100	115	
		R <sub>RC</sub> = 68.1 kΩ, C <sub>RC</sub> = 470 pF		255	300	345	
Frequency line regulation		12 V < V <sub>DD</sub> < 52 V		–9		0	%
		4.5 V < V <sub>DD</sub> < 12 V		–20		0	
V <sub>RMP</sub>	Ramp amplitude	4.5 V < V <sub>DD</sub> < 52 V		V <sub>DD</sub> ÷ 10			V
Pulse-Width Modulator							
t <sub>MIN</sub>	Minimum controllable pulse width	V <sub>DD</sub> = 12 V			200	500	ns
		V <sub>DD</sub> = 30 V			100	200	
D <sub>MAX</sub>	Maximum duty cycle	F <sub>OSC</sub> = 100 kHz, C <sub>L</sub> = 470 pF		93	95		%
		F <sub>OSC</sub> = 300 kHz, C <sub>L</sub> = 470 pF		87	93		
K <sub>PWM</sub>	Modulator and power-stage dc gain			8	10	12	V/V
Error Amplifier							
I <sub>IB</sub>	Input bias current				100	250	nA
AOL	Open-loop gain <a href="#">Note</a>			60	80		dB
GBWP	Unity gain bandwidth <a href="#">Note</a>			1.5	3		MHz
I <sub>COMP(src)</sub>	Output source current	V <sub>FB</sub> = 0.6 V, COMP = 1 V		100	250		μA
I <sub>COMP(snk)</sub>	Output sink current	V <sub>FB</sub> = 1.2 V, COMP = 1 V		1.0	2.5		mA

## THERMAL CHARACTERISTICS

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	TYP	UNIT
$\theta_{JC}$	Thermal resistance, junction to case	(1)	49	°C/W
$\theta_{JA}$	Thermal resistance, junction to ambient	(1)HIGH-K	97.5	°C/W
$\theta_{JA}$	Thermal resistance, junction to ambient	(1)LOW-K	176	°C/W

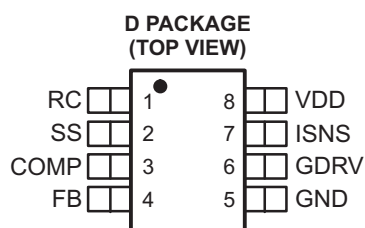
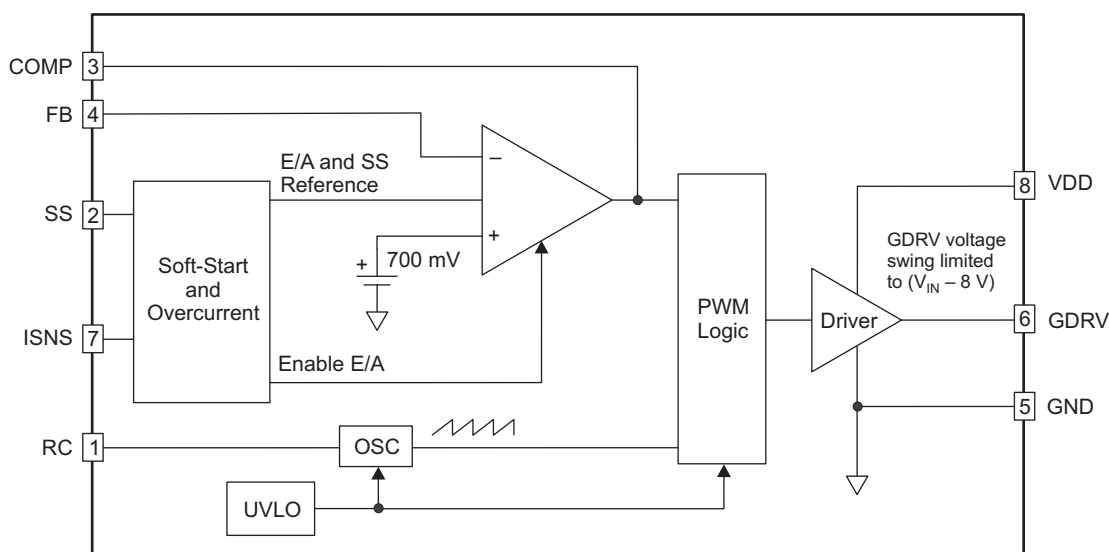
(1) TI uses test boards designed to JESD 51-3 and JESD 51-7 for thermal-impedance measurements. The parameters outlined in these standards also are used to set up thermal models.

**Table 1. ORDERING INFORMATION**

T <sub>A</sub>	OUTPUT VOLTAGE	PACKAGE	ORDERABLE PART NUMBER	MEDIUM	QUANTITY
–55°C to 125°C	Adjustable	SOIC – D	TPS40200MDREP	Tape and reel	2500/reel

## DEVICE INFORMATION

### Figure 3. Functional Block Diagram



## TERMINAL FUNCTIONS

TERMINAL NAME	NO.	I/O	DESCRIPTION
RC	1	I	Switching frequency-setting RC network. Connect capacitor from RC pin to GND pin and resistor from $V_{IN}$ pin to RC pin. The device may be synchronized to an external clock by connecting an open-drain output to this pin and pulling it to GND. The pulse width for synchronization should not be excessive.
SS	2	I	Soft-start programming pin. Connect capacitor from SS to GND to program soft-start time. Pulling this pin below 150 mV causes the output switching to stop, placing the device in a shutdown state. The pin also functions as a restart timer for overcurrent events.
COMP	3	O	Compensation. Error amplifier output. Connect control-loop compensation network from COMP to FB.
FB	4	I	Feedback. Error amplifier inverting input. Connect feedback resistor network center tap to this pin.
GND	5		Device ground
GDRV	6	O	Driver output for external P-channel MOSFET
ISNS	7	I	Current-sense comparator input. Connect a current sense resistor between ISNS and $V_{DD}$ in order to set desired overcurrent threshold.
VDD	8	I	System input voltage. Connect local bypass capacitor from $V_{DD}$ to GND.

## TYPICAL CHARACTERISTICS

**QUIESCENT CURRENT  
vs  
TEMPERATURE**

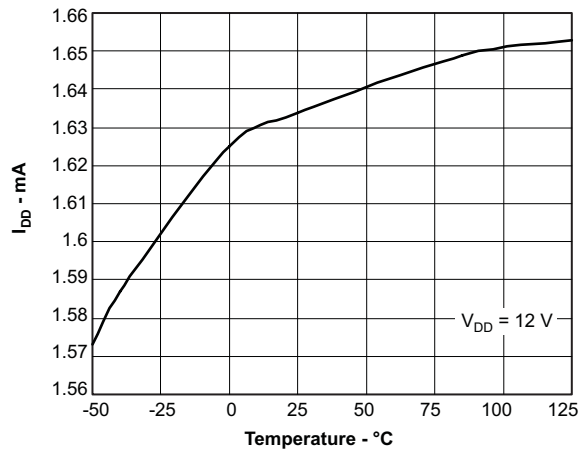


Figure 4.

**QUIESCENT CURRENT  
vs  
 $V_{DD}$**

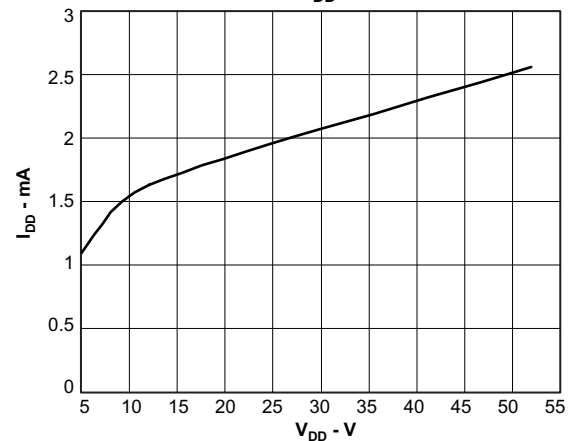


Figure 5.

**SOFT-START THRESHOLD  
vs  
TEMPERATURE**

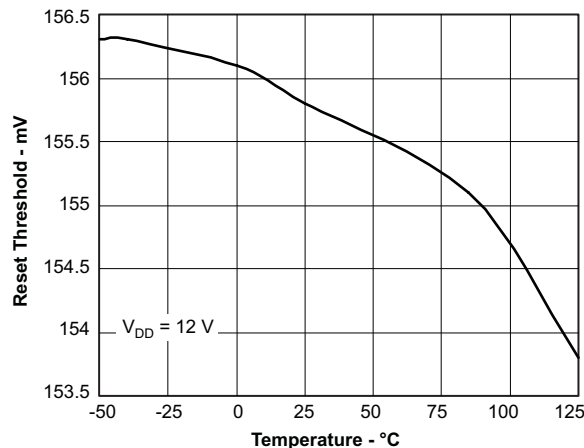


Figure 6.

**UVLO TURNON AND TUNOFF  
vs  
TEMPERATURE**

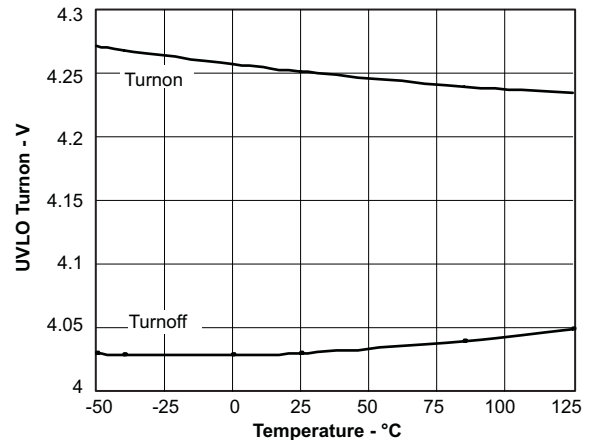


Figure 7.

## TYPICAL CHARACTERISTICS (continued)

**OSCILLATOR FREQUENCY  
vs  
TEMPERATURE**

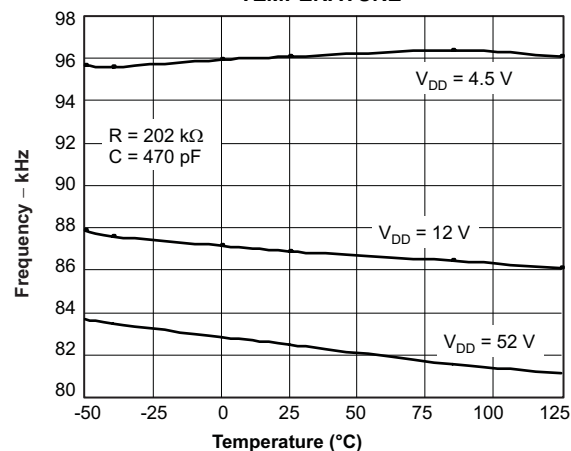


Figure 8.

**CURRENT-LIMIT THRESHOLD  
vs  
TEMPERATURE**

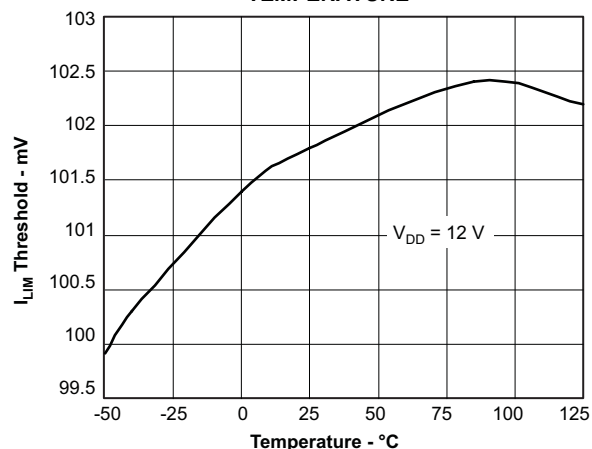


Figure 9.

**OSCILLATOR FREQUENCY  
vs  
 $V_{DD}$**

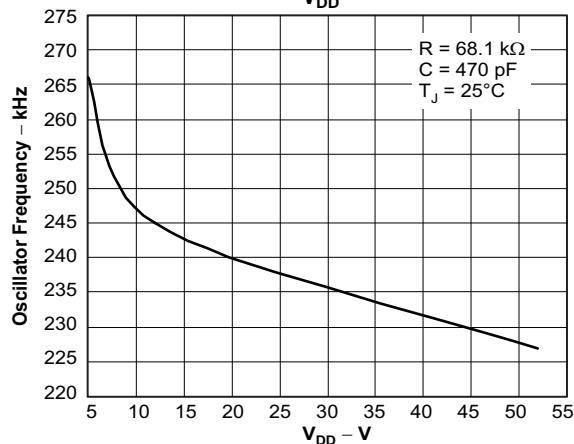


Figure 10.

**POWER-STAGE GAIN  
vs  
 $V_{DD}$**

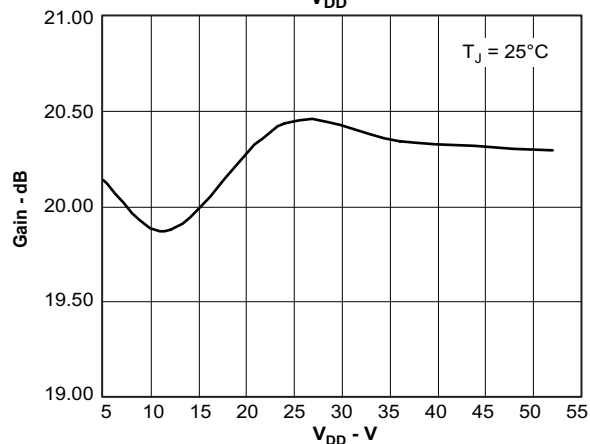


Figure 11.

## TYPICAL CHARACTERISTICS (continued)

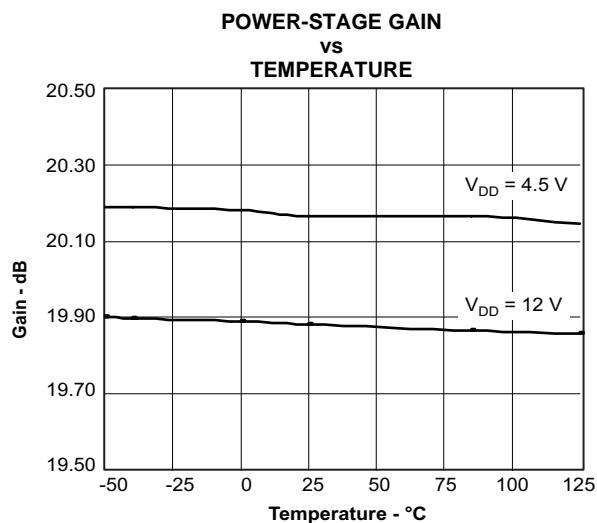


Figure 12.

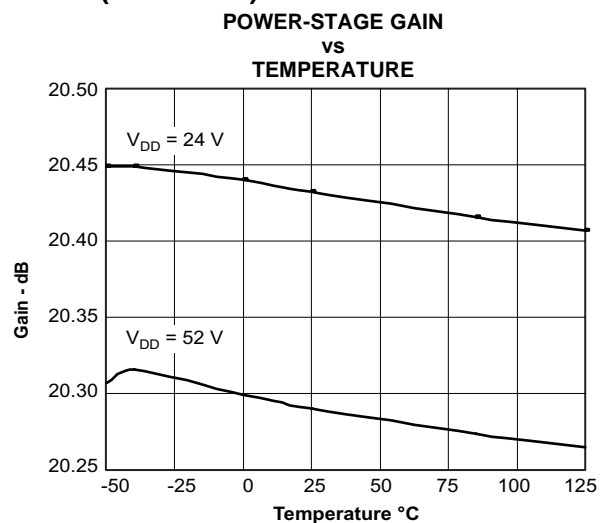


Figure 13.

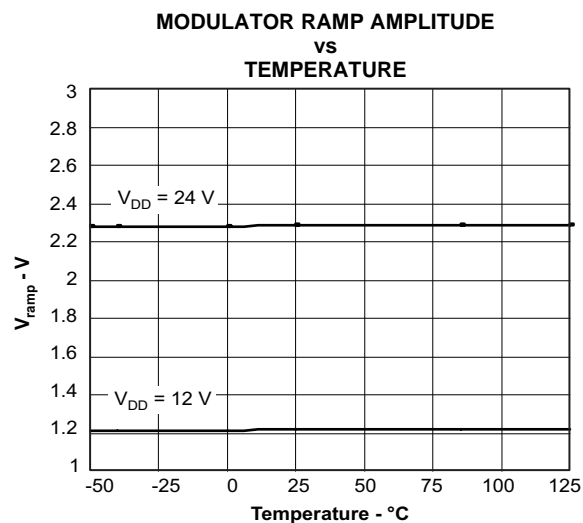


Figure 14.

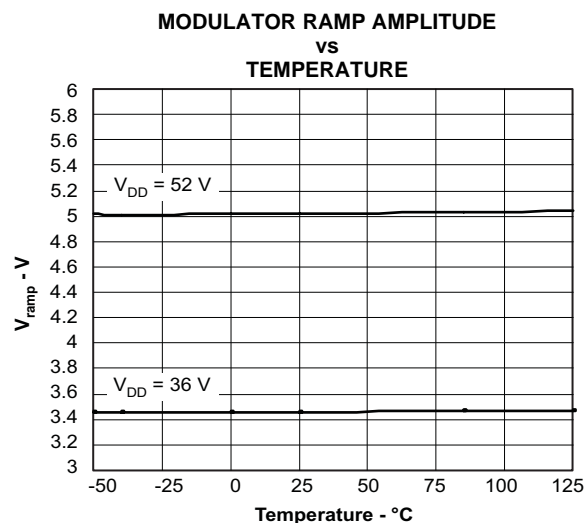


Figure 15.

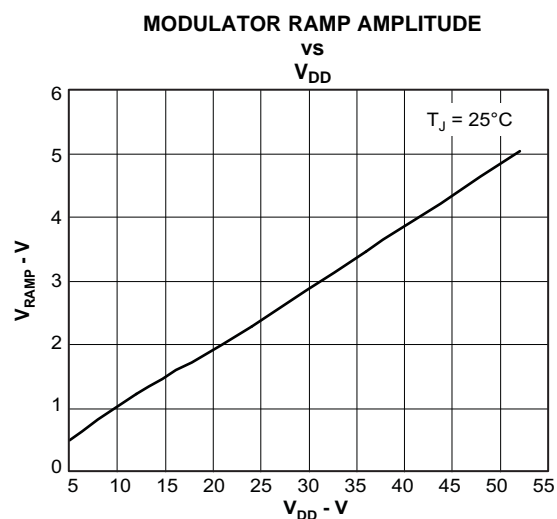
**TYPICAL CHARACTERISTICS (continued)**

Figure 16.

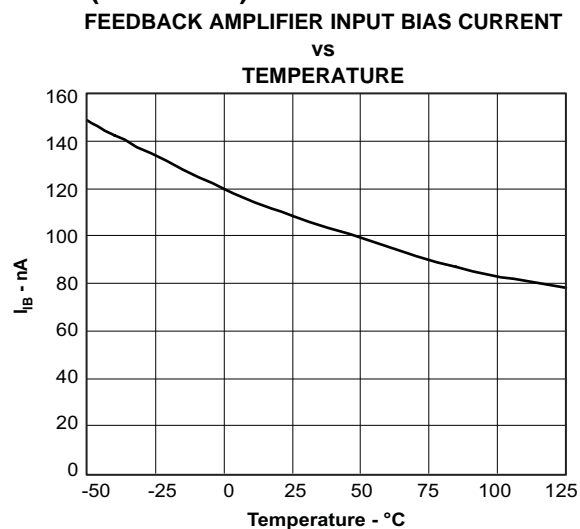


Figure 17.

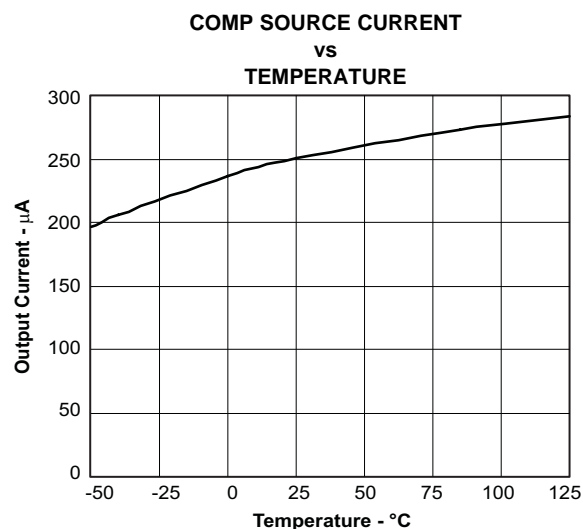


Figure 18.

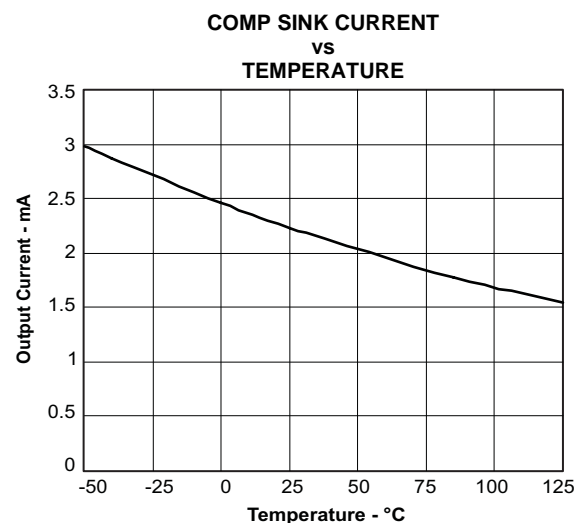


Figure 19.



## TYPICAL CHARACTERISTICS (continued)

**GATE DRIVE VOLTAGE  
vs  
TEMPERATURE**

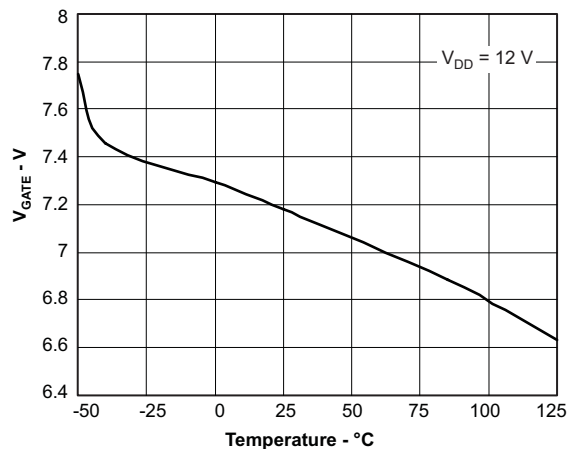


Figure 20.

**GATE DRIVE VOLTAGE  
vs  
V<sub>IN</sub>**

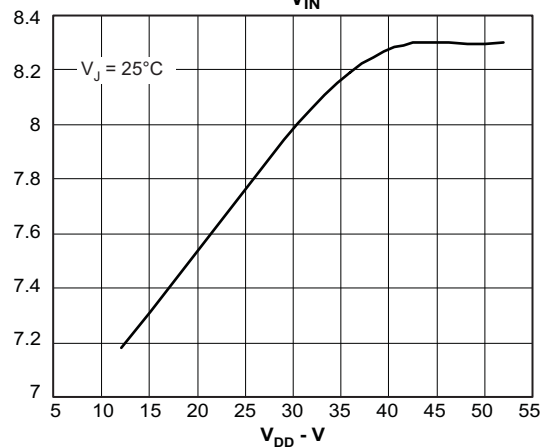


Figure 21.

**REFERENCE VOLTAGE  
vs  
TEMPERATURE**

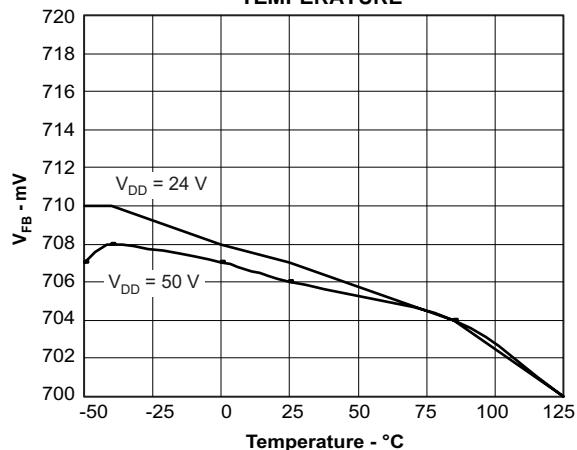


Figure 22.

**REFERENCE VOLTAGE  
vs  
TEMPERATURE**

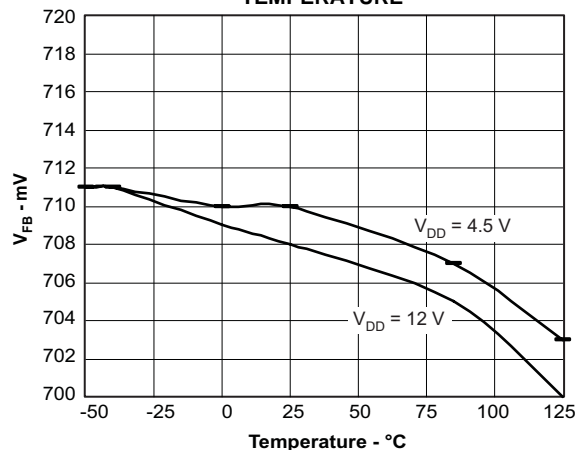


Figure 23.

## GENERAL INFORMATION

### Overview

The TPS40200 is a nonsynchronous controller with a built-in 200-mA driver, designed to drive high-speed P-channel FETS up to 500 kHz. Its small size combined with complete functionality makes the part both versatile and easy to use.

The controller uses a low-value current-sensing resistor in series with the input voltage and the power FET source connection to detect switching current. When the voltage drop across this resistor exceeds 100 mV, the part enters a hiccup fault mode at approximately 2% of the operating frequency.

The part uses voltage feedback to an error amplifier that is biased by a precision 700-mV reference. Feed-forward compensation from the input keeps the pulse-width modulator (PWM) gain constant over the full input voltage range, eliminating the need to change frequency compensation for different input voltages.

The part also incorporates a soft-start feature where the output follows a slowly rising soft-start voltage, preventing output-voltage overshoot.

### Programming the Operating Frequency

The operating frequency of the controller is determined by an external resistor,  $R_{RC}$ , that is connected from the RC pin to VDD and a capacitor attached from the RC pin to ground. This connection, and the two oscillator comparators inside the IC, are shown in [Figure 24](#). The oscillator frequency can be calculated from the following equation:

$$f_{SW} = \frac{1}{R_{RC} \times C_{RC} \times 0.105} \quad (1)$$

Where:

$f_{SW}$  = Clock frequency

$R_{RC}$  = Timing resistor value (in  $\Omega$ )

$C_{RC}$  = Timing capacitor value (in F)

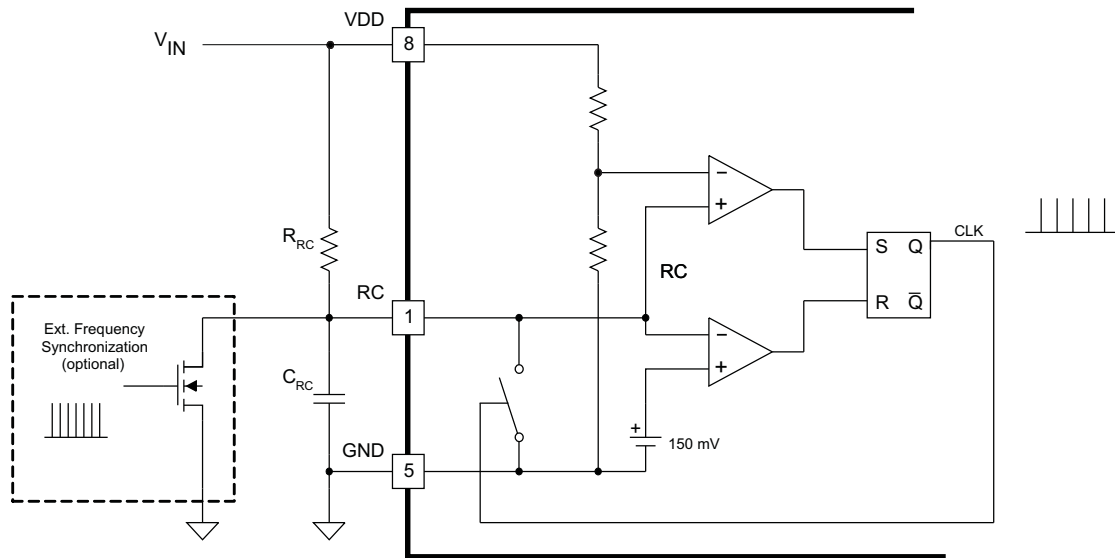
$R_{RC}$  must be kept large enough that the current through it does not exceed 750  $\mu$ A when the internal switch (shown in [Figure 24](#)) is discharging the timing capacitor. This condition may be expressed by:

$$\frac{V_{IN}}{R_{RC}} \leq 750 \mu A \quad (2)$$

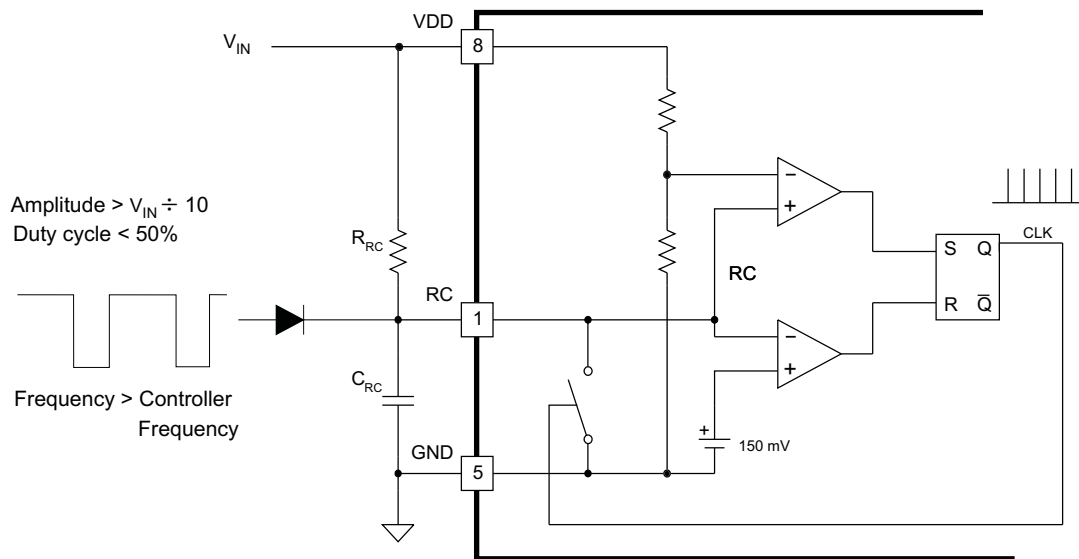
### Synchronizing the Oscillator

[Figure 24](#) shows the functional diagram of the TPS40200 oscillator. When synchronizing the oscillator to an external clock, RC must be pulled below 150 mV for 20 ns or more. The external clock frequency must be higher than the free-running frequency of the converter as well. When synchronizing the controller, if RC is held low for an excessive amount of time, erratic operation may occur. The maximum amount of time that RC should be held low is 50% of a nominal output pulse, or 10% of the period of the synchronization frequency.

Under circumstances where the input voltage is high and the duty cycle is less than 50%, a Schottky diode connected from RC to an external clock may be used to synchronize the oscillator. The cathode of the diode is connected to RC. The trip point of the oscillator is set by an internal voltage divider to be 1/10 of the input voltage. The clock signal must have an amplitude higher than this trip point. When the clock goes low, it allows the reset current to restart the RC ramp, synchronizing the oscillator to the external clock. This provides a simple, single-component method for clock synchronization.



**Figure 24. Oscillator Functional Diagram**



**Figure 25. Diode-Connected Synchronization**

## Current-Limit Resistor Selection

As shown in Figure 28, a resistor in series with the power MOSFET sets the overcurrent protection level. Use a low-inductance resistor to avoid problems with ringing signals and nuisance tripping. When the FET is on and the controller senses 100 mV or more drop from the VDD pin to the ISNS pin, an overcurrent condition is declared. When this happens, the FET is turned off and, as shown in Figure 29, the soft-start capacitor is discharged. When the soft-start capacitor reaches a level below 150 mV, the converter clears the overcurrent condition flag and attempts to restart. If the condition that caused the overcurrent event to occur is still present on the output of the converter (see Figure 28), another overcurrent condition is declared and the process repeats indefinitely. Figure 28 shows the soft-start capacitor voltage during an extended output fault condition. The overall duty cycle of current conduction during a persistent fault is approximately 2%.

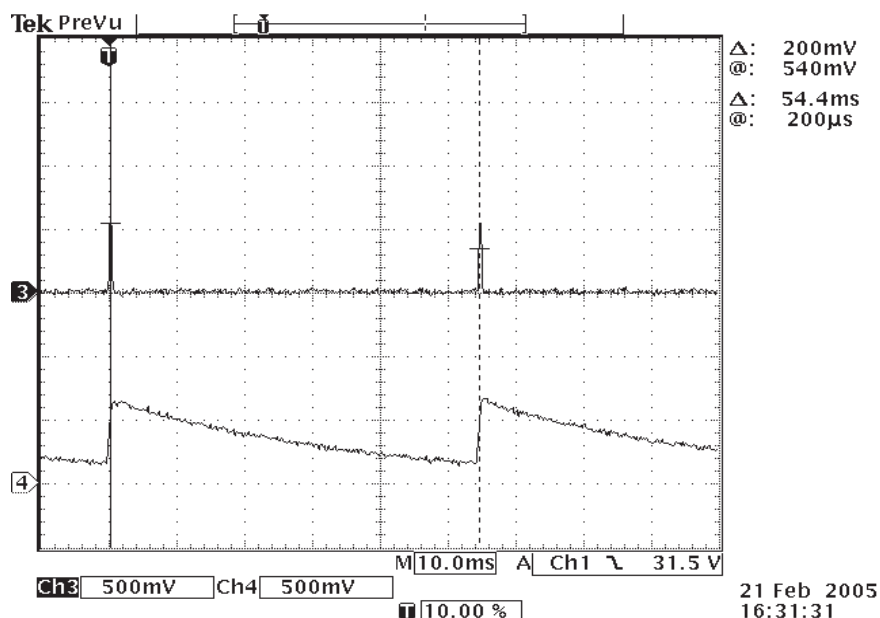


Figure 26. Typical Soft-Start Capacitor and  $V_{OUT}$  During Overcurrent

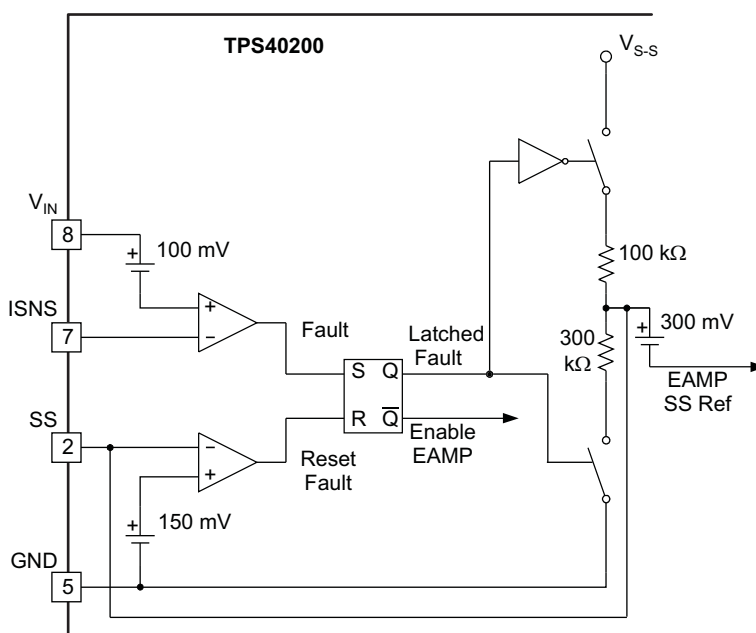


Figure 27. Current-Limit Reset

If necessary, a small R-C filter can be added to the current-sensing network to reduce nuisance tripping due to noise pickup. This filter also can be used to trim the overcurrent trip point to a higher level with the addition of a single resistor. See [Figure 28](#). The nominal overcurrent trip point using the circuit of [Figure 28](#) is described as:

$$I_{OC} = \frac{V_{ILIM}}{R_{ILIM}} \times \frac{R_{F1} + R_{F2}}{R_{F2}} \quad (3)$$

Where:

$I_{OC}$  = Overcurrent trip point, peak current in the inductor

$V_{ILIM}$  = Overcurrent threshold voltage for the TPS40200, typically 100 mV

$R_{ILIM}$  = Value of the current sense resistor (in  $\Omega$ )

$R_{F1}$  and  $R_{F2}$  = Values of the scaling resistors (in  $\Omega$ )

The value of the capacitor is determined by the nominal pulse width of the converter and the values of the scaling resistors  $R_{F1}$  and  $R_{F2}$ . It is best not to have the time constant of the filter longer than the nominal pulse width of the converter, otherwise a substantial increase in the overcurrent trip point occurs. Using this constraint, the capacitor value may be bounded by:

$$C_f \leq \frac{V_O}{V_{IN} \times f_{SW}} \div \frac{R_{f1} \times R_{f2}}{R_{f1} + R_{f2}} \quad (4)$$

Where:

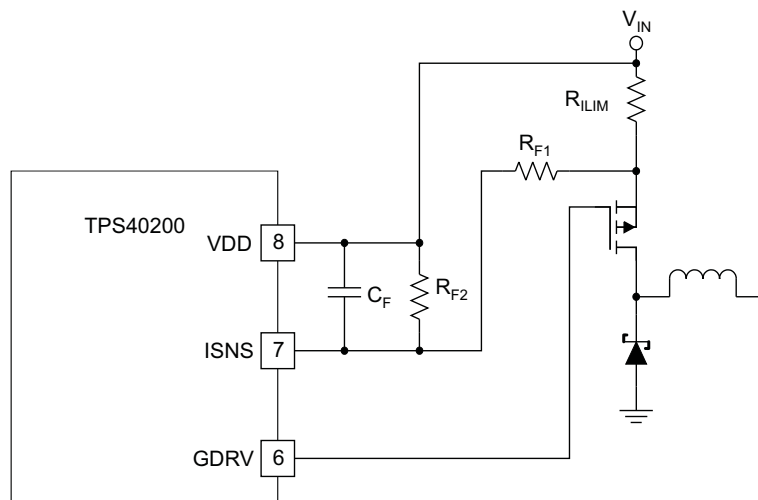
$C_f$  = Value of the current-limit filter capacitor (in F)

$V_O$  = Output voltage of the converter

$V_{IN}$  = Input voltage to the converter

$f_{SW}$  = Converter switching frequency

$R_{f1}$  and  $R_{f2}$  = Values of the scaling resistors (in  $\Omega$ )



NOTE: The current-limit resistor and its associated circuitry can be eliminated and pins 7 and 8 shorted. However, the result of this may result in damage to the part or PC board in the event of an overcurrent event.

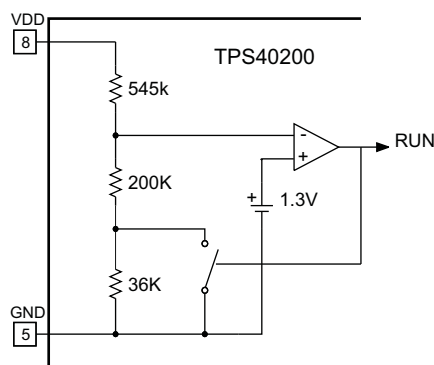
**Figure 28. Current-Limit Adjustment**

## MOSFET Gate Drive

The output driver sinking current is approximately 200 mA and is designed to drive P-channel power FETs. When the driver pulls the gate charge of the FET, it is controlling to  $-8$  V, the drive current folds back to a low level so that high power dissipation only occurs during the turnon period of the FET. This feature is particularly valuable when turning on a FET at high input voltages, where leaving the gate drive current on would otherwise cause unacceptable power dissipation.

## Undervoltage Lockout (UVLO) Protection

UVLO protection ensures proper startup of the device only when the input voltage has exceeded minimum operating voltage. Undervoltage protection incorporates hysteresis, which eliminates hiccup starting in cases where input supply impedance is high.



**Figure 29. Undervoltage Lockout**

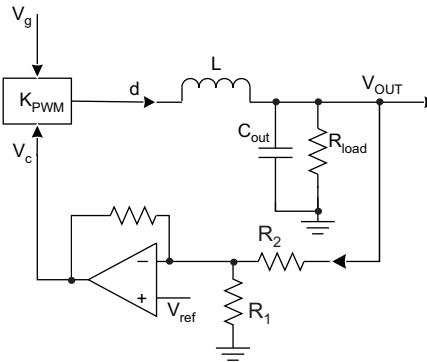
Undervoltage protection ensures proper startup of the device only when the input voltage has exceeded minimum operating voltage. The UVLO level is measured at the VDD pin with respect to GND. Startup voltage is typically 4.3 V, with approximately 200 mV of hysteresis. The part shuts off at a nominal 4.1 V. As shown in [Figure 29](#), when the input VDD voltage rises to 4.3 V, the 1.3-V comparator's threshold voltage is exceeded and a RUN signal occurs. Feedback from the output closes the switch and shunts the 200-k $\Omega$  resistor so that an approximate 200-mV lower voltage, or 4.1 V, is required before the part shuts down.



## Voltage Setting and Modulator Gain

Since the input current to the error amplifier is negligible, the feedback impedance can be selected over a wide range. Knowing that the reference voltage is 708 mV, pick a convenient value for R1 and then calculate the value of R2 from the following formula:

$$V_{OUT} = 0.708 \left( 1 + \frac{R_2}{R_1} \right) \quad (7)$$



**Figure 31. System Gain Elements**

The error amplifier has a DC open-loop gain of at least 60 dB, with a minimum of a 1.5-MHz gain bandwidth product, which gives the user flexibility with respect to the type of feedback compensation used for this particular application. The gain selected by the user at the crossover frequency is set to provide an overall unity gain for the system. The crossover frequency should be selected so that the error amplifier open-loop gain is high with respect to the required closed-loop gain. This ensures that the amplifier response is determined by the passive feedback elements.



## EXAMPLE APPLICATIONS

### Application 1: Buck Regulator, 8-V to 12-V Input, 3.3 V or 5 V at 2.5-A Output

#### Overview

The buck regulator design shown in Figure 32 illustrates the use of the TPS40200. It delivers 2.5 A at either 3.3 V or 5 V as selected by a single feedback resistor. It achieves approximately 90% efficiency at 3.3 V and 94% at 5 V. A discussion of design tradeoffs and methodology is included to serve as a guide to the successful design of forward converters using the TPS40200.

The Bill of Materials (BOM) for this application is given in Table 3. The efficiency and load regulation from boards built from this design are shown in Figure 33 and Figure 34. Gerber files and additional application information are available from the factory.

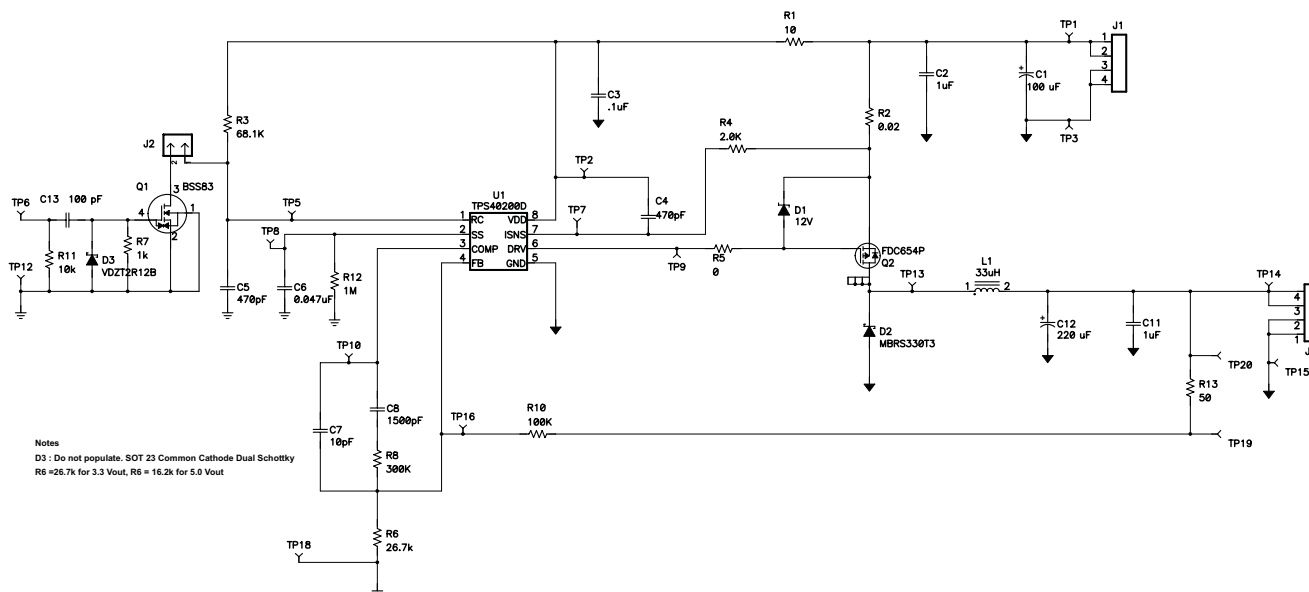


Figure 32. 8-V to 16-V  $V_{IN}$  Step-Down Buck Converter

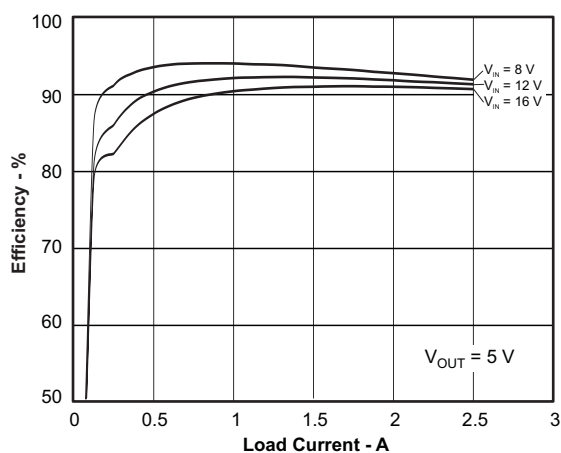


Figure 33. Full-Load Efficiency at 5-V  $V_{OUT}$

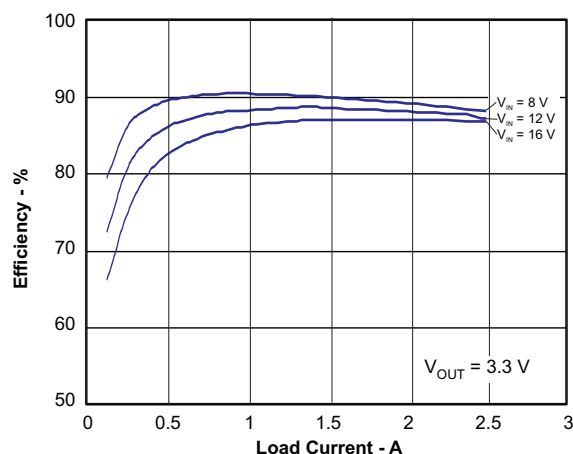


Figure 34. Full-Load Efficiency at 3.3-V  $V_{OUT}$

## Component Selection

**Table 2. Design Parameters**

SYMBOL	PARAMETER	TEST CONDITION	MIN	NOM	MAX	UNIT
V <sub>IN</sub>	Input voltage		8	12	16	V
V <sub>OUT</sub>	Output voltage	I <sub>OUT</sub> at 2.5 A	3.200	3.3	3.400 <sup>(1)</sup>	V
	Line regulation	±0.2% V <sub>OUT</sub>	3.293	3.3	3.307	V
	Load regulation	±0.2% V <sub>OUT</sub>	3.293	3.3	3.307	V
V <sub>OUT</sub>	Output voltage	I <sub>OUT</sub> at 2.5 A	4.85	5	5.150 <sup>(1)</sup>	V
	Line regulation	±0.2% V <sub>OUT</sub>	4.990	5	5.010	V
	Load regulation	±0.2% V <sub>OUT</sub>	4.990	5	5.010	V
V <sub>RIPPLE</sub>	Output ripple voltage	At maximum output current		60		mV
V <sub>OVER</sub>	Output overshoot	For 2.5-A load transient from 2.5 A to 0.25 A		100		mV
V <sub>UNDER</sub>	Output undershoot	For 2.5-A load transient from 0.25 A to 2.5 A		60		mV
I <sub>OUT</sub>	Output current		0.125		2.5	A
I <sub>SCP</sub>	Short-circuit current trip point		3.75		5.00	A
	Efficiency	At nominal input voltage and maximum output current		90		%
F <sub>S</sub>	Switching frequency			300		kHz

(1) Set-point accuracy is dependent on external resistor tolerance and the IC reference voltage. Line and load regulation values are referenced to the nominal design output voltage.

### FET Selection Criteria

- The maximum input voltage for this application is 16 V. Switching the inductor causes overshoot voltages that can equal the input voltage. Since the R<sub>DS(on)</sub> of the FET rises with breakdown voltage, select a FET with as low a breakdown voltage as possible. In this case, a 30-V FET was selected.
- The selection of a power FET's size requires knowing both the switching losses and dc losses in the application. AC losses are all frequency dependent and directly related to device capacitances and device size. Conversely, dc losses are inversely related to device size. The result is an optimum where the two types of losses are equal. Since device size is proportional to R<sub>DS(on)</sub>, a starting point is to select a device with an R<sub>DS(on)</sub> that results in a small loss of power relative to package thermal capability and overall efficiency objectives.
- In this application, the efficiency target is 90% and the output power 8.25 W. This gives a total power-loss budget of 0.916 W. Total FET losses must be small, relative to this number.

The dc conduction loss in the FET is given by:

$$P_{DC} = I_{rms}^2 \times R_{DS(on)} \quad (8)$$

The rms current is given by:

$$I_{rms} = \left[ D \times \left( I_{OUT}^2 + \frac{\Delta I_{pp}^2}{12} \right) \right]^{\frac{1}{2}} \quad (9)$$

Where:

$$\Delta I_{pp} = \Delta V \times D \times \frac{t_s}{L_1}$$

$$\Delta V = V_{IN} - V_{OUT} - (DCR + R_{DS(on)}) \times I_{OUT}$$

$R_{DS(on)}$  = FET on-state resistance

DCR = Inductor dc resistance

D = Duty cycle

$t_s$  = Reciprocal of the switching frequency

Using the values in this example, the dc power loss is 129 mW. The remaining FET losses are:

- $P_{SW}$  – Power dissipated while switching the FET on and off
- $P_{gate}$  – Power dissipated driving the FET gate capacitance
- $P_{COSS}$  – Power switching the FET output capacitance

The total power dissipated by the FET is the sum of these contributions:

$$P_{FET} = P_{SW} + P_{gate} + P_{COSS} + P_{RDS(on)}$$

The P-channel FET used in this application is an FDC654P, with the following characteristics:

$$t_{rise} = 13 \times 10^{-9} \quad C_{OSS} = 83 \times 10^{-12}$$

$$t_{fall} = 6 \times 10^{-9} \quad Q_g = 9 \text{ nC}$$

$$R_{DS(on)} = 0.1 \, \Omega \quad V_{gate} = 1.9 \text{ V}$$

$$Q_{gd} = 1.2 \times 10^{-9} \quad Q_{gs} = 1.0 \times 10^{-9}$$

Using these device characteristics and the following formulas produces:

$$P_{SW} = \frac{f_s}{2} \times \left( V_{IN} \times I_{pk} \times t_{CHON} \right) + \frac{f_s}{2} \left( V_{IN} \times I_{pk} \times t_{CHOFF} \right) = 10 \text{ mW} \quad (10)$$

Where:

$$t_{CHON} = \frac{Q_{GD} \times R_G}{V_{IN} - V_{TH}}$$

and

$$t_{CHOFF} = \frac{Q_{GD} \times R_G}{V_{IN}}$$

are the switching times for the power FET.

$$P_{GATE} = Q_G \times V_{GATE} \times f_s = 22 \text{ mW}$$

$$P_{COSS} = \frac{C_{OSS} \times V_{IN\_MAX}^2 \times f_s}{2} = 2 \text{ mW}$$

$$I_G = Q_G \times f_s = 2.7 \text{ mA is the gate current}$$

The sum of the switching losses is 34 mW and is comparable to the 129-mW dc losses. At added expense, a slightly larger FET would be better because the dc loss would drop and the ac losses would increase, with both moving toward the optimum point of equal losses.

## Rectifier Selection Criteria

- Rectifier breakdown voltage

The rectifier has to withstand the maximum input voltage which, in this case, is 16 V. To allow for switching transients that can approach the switching voltage, a 30-V rectifier was selected.

- Diode size

The importance of power losses from the Schottky rectifier (D2) is determined by the duty cycle. For a low duty-cycle application, the rectifier is conducting most of the time, and the current that flows through it times its forward drop can be the largest component of loss in the entire controller. In this application, the duty cycle ranges from 20% to 40%, which in the worst case means that the diode is conducting 80% of the time. Where efficiency is of major importance, choose a diode with as low a forward drop as possible. In more cost-sensitive applications, size may be reduced to the point of the thermal limitations of the diode package.

The device in this application is large, relative to the current required by the application. In a more cost-sensitive application, a smaller diode in a less-expensive package provides a less-efficient, but appropriate, solution.

The device used has the following characteristics:

- $V_f = 0.3 \text{ V}$  at 3 A
- $C_t = 300 \text{ pF}$  ( $C_t$  = the effective reverse-voltage capacitance of the synchronous rectifier, D2)

The two components of the losses from the diode D2 are:

$$P_{\text{COND}} = V_f \times \left( I_{\text{OUT}} + \frac{I_{\text{RIPPLE}}}{4} \right) \times (1 - D) = 653 \text{ mW} \quad (11)$$

Where:

D = Duty cycle

$I_{\text{RIPPLE}}$  = Ripple current

$I_{\text{OUT}}$  = Output current

$V_f$  = Forward voltage

$P_{\text{COND}}$  = Conduction power loss

The switching capacitance of this diode adds an AC loss, given by:

$$P_{\text{SW}} = \frac{1}{2} [C \times (V_{\text{IN}} + V_f)^2 \times f] = 6.8 \text{ mW} \quad (12)$$

This additional loss raises the total loss to: 660 mW.

At an output voltage of 3.3 V, the application runs at a nominal duty cycle of 27%, and the diode is conducting 72.5% of the time. As the output voltage is moved up to 5 V, the on time increases to 46%, and the diode is conducting only 54% of the time during each clock cycle. This change in duty cycle proportionately reduces the conduction power losses in the diode. This reduction may be expressed as:

$$660 \left( \frac{0.54}{0.725} \right) = 491 \text{ mW} \quad (13)$$

for a savings in power of  $660 - 491 = 169 \text{ mW}$ .

To illustrate the relevance of this power savings, the full-load module efficiency was measured for this application at 3.3 V and 5 V. The 5-V output efficiency is 92% versus 89% for the 3.3-V design. This difference in efficiency represents a 456-mW reduction in losses between the two conditions. This 169-mW power-loss reduction in the rectifier represents 37% of the difference.

## Inductor Selection Criteria

The TPS40200 P-channel FET driver facilitates switching the power FET at a high frequency. This, in turn, enables the use of smaller, less-expensive inductors as shown in this 300-kHz application. Ferrite, with its good high-frequency properties, is the material of choice. Several manufacturers provide catalogs with inductor saturation currents, inductance values, and LSRs (internal resistance) for their various-sized ferrites.

In this application, the part must deliver a maximum current of 2.5 A. This requires that the output inductor saturation current be above 2.5 A plus one-half the ripple current caused during inductor switching. The value of the inductor determines this ripple current. A low value of inductance has a higher ripple current that contributes to ripple voltage across the resistance of the output capacitors. The advantages of a low inductance are a higher transient response, lower DCR, higher saturation current, and a smaller, less-expensive part. Too low an inductor, however, leads to higher peak currents that ultimately are bounded by the overcurrent limit set to protect the output FET or by output ripple voltage. Fortunately, with low-ESR ceramic capacitors on the output, the resulting ripple voltage for relatively high ripple currents can be small.

For example, a single 1-μF 1206-sized 6.3-V ceramic capacitor has an internal resistance of 2 Ω at 1 MHz. For this 2.5-A application, a 10% ripple current of 0.25 A produces a 50-mV ripple voltage. This ripple voltage may be further reduced by additional parallel capacitors.

The other bound on inductance is the minimum current at which the controller enters discontinuous conduction. At this point, inductor current is zero. The minimum output current for this application is specified at 0.125 A. This average current is one-half the peak current that must develop during a minimum on time. The conditions for minimum on time are high line and low load, using:

$$L_{MAX} = \frac{V_{IN} - V_{OUT}}{I_{PEAK}} \times t_{ON} = 32 \mu H \quad (14)$$

Where:

$$V_{IN} = 16 \text{ V}$$

$$V_{OUT} = 3.3 \text{ V}$$

$$I_{PEAK} = 0.25 \text{ A}$$

$$t_{ON} = 0.686 \mu s$$

$$t_{ON} \text{ is given by } \frac{1}{300 \text{ kHz}} \times \frac{3.3 \text{ V}}{16 \text{ V}}$$

The inductor used in the circuit is the closest standard value of 33 μH. This is the maximum inductance that can be used in the converter to deliver the minimum current, while maintaining continuous conduction.

## Output Capacitance

In order to satisfy the output voltage overshoot and undershoot specifications, there must be enough output capacitance to keep the output voltage within the specified voltage limits during load current steps.

In a situation where a full load of 2.5 A within the specified voltage limits is suddenly removed, the output capacitor must absorb energy stored in the output inductor. This condition may be described by realizing that the energy stored in the inductor must be suddenly absorbed by the output capacitance. This energy relationship is written as:

$$\frac{1}{2} \times L_O I_O^2 \leq \frac{1}{2} \times [C_O (V_{OS}^2 - V_O^2)] \quad (15)$$

Where:

$V_{OS}$  = Allowed overshoot voltage above the output voltage

$L_O$  = Inductance

$I_O$  = Output current

$C_O$  = Output capacitance

$V_O$  = Output voltage

In this application, the worst-case load step is 2.25 A and the allowed overshoot is 100 mV. With a 33-μH output inductor, this implies an output capacitance of 249 μF for a 3.3-V output and 165 μF for a 5-V output.

When the load increases from minimum to full load, the output capacitor must deliver current to the load. The worst case is for a minimum on time that occurs at 16 V in and 3.3 V out and minimum load. This corresponds to an off time of (1 – 0.2) times the period 3.3 μs, and is the worst-case time before the inductor can start supplying current. This situation may be represented by:

$$\Delta V_O < \Delta I_O \times \frac{t_{OFFMAX}}{C_O} \quad (16)$$

Where:

$\Delta V_O$  = Undershoot specification of 60 mV

$\Delta I_O$  = Load current step

$t_{OFFMAX}$  = Maximum off time

This condition produces a requirement of 100 μF for the output capacitance. The larger of these two requirements becomes the minimum value of output capacitance.

The ripple current develops a voltage across the ESR of the output capacitance, so another requirement on this component is that its ESR be small relative to the ripple voltage specification.

## Switching Frequency

The TPS40200 has a built-in, 8-V, 200-mA, P-channel FET driver output that facilitates using P-channel switching FETs. A clock frequency of 300 kHz was chosen as a switching frequency which represents a compromise between a high frequency that allows the use of smaller capacitors and inductors, but one that is not so high as to cause excessive transistor switching losses. As previously discussed, an optimum frequency can be selected by picking a value where the dc and switching losses are equal.

The frequency is set by using the design formula given in the [FET Selection Criteria](#) section.

$$R_{RC} \times C_{RC} = \frac{1}{0.105 \times f_{SW}} \quad (17)$$

Where:

$R_{RC}$  = Timing resistor value (in ohms), or  $R_{RC} = 68.1 \, \Omega$

$C_{RC}$  = Timing capacitor value (in F), or  $C_5 = 470 \, \text{pF}$

$f_{SW}$  = Desired switching frequency (in Hz) which, in this case, calculates to 297 kHz

At a worst case of 16 V, the timing resistor draws about 250  $\mu\text{A}$ , which is well below the 750  $\mu\text{A}$  maximum that the circuit can pull down.

## Programming the Overcurrent Threshold Level

The current limit in the TSP40200 is triggered by a comparator with a 100-mV offset, whose inputs are connected across a current-sense resistor between  $V_{CC}$  and the source of the high-side switching FET. When current in this resistor develops more than 100 mV, the comparator trips and terminates the output gate drive.

In this application, the current-limit resistor is set by the peak output-stage current, which consists of the maximum load current plus one-half the ripple current (in this case,  $2.5 + 0.125 = 2.625 \, \text{A}$ ). To accommodate tolerances, a 25% margin is added, giving a 3.25-A peak current. Using the equation below then yields a value for  $R_{ILIM}$  of  $0.30 \, \Omega$ .

Current sensing in a switching environment requires attention to both circuit-board traces and noise pickup. In [Figure 35](#), a small RC filter has been added to the circuit to prevent switching noise from tripping the current-sense comparator. The requirements of this filter are board dependent, but with the layout used in this application, no spurious overcurrent was observed.

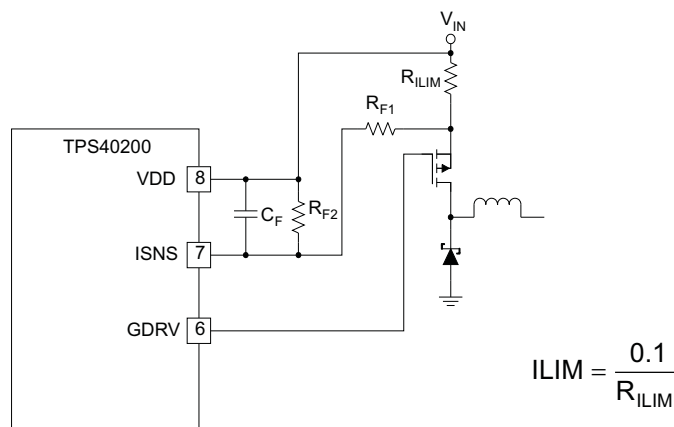


Figure 35. Overcurrent Trip Circuit for  $R_{F2}$  Open

## Soft-Start Capacitor

The soft-start interval is given (in pF) by:

$$C_{SS} = \frac{t_{SS}}{R \times \ln\left(\frac{V_{SST}}{V_{SST} - 1.4}\right)} \times 10^3 \quad (18)$$

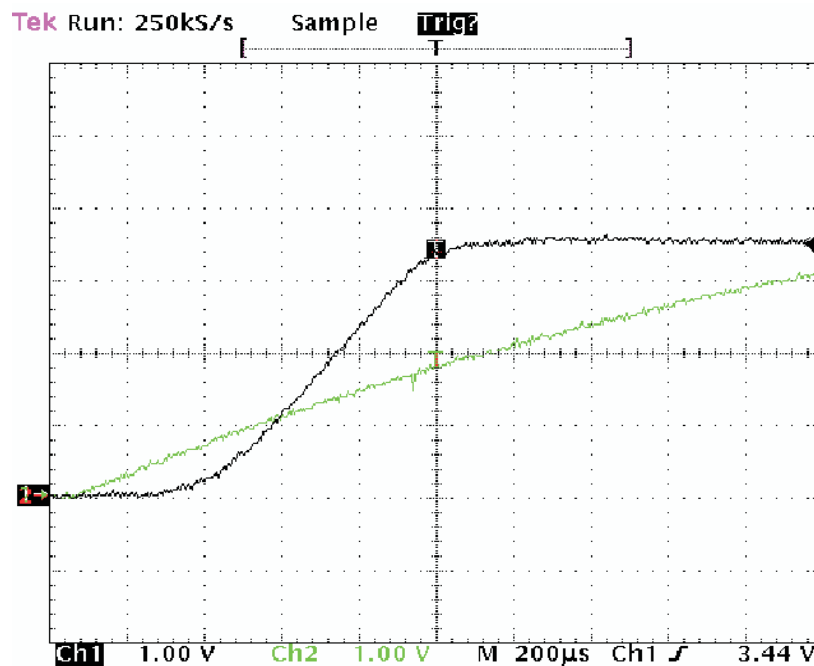
Where:

R = Internal 105-kΩ charging resistor

V<sub>CC</sub> = Input voltage up to 8 V, where the charging voltage is internally clamped to 8 V maximum

V<sub>OS</sub> = 700 mV and, because the input voltage is 12 V, V<sub>SST</sub> = 8 V

The oscilloscope output (see [Figure 36](#)) shows the expected delay at the output (middle trace) until the soft-start node (bottom trace) reaches 700 mV. At this point, the output rises following the exponential rise of the soft-start capacitor voltage until the soft-start capacitor reaches 1.4 V and the internal 700-mV reference takes over. This total time is approximately 1 ms, which agrees with the calculated value of 0.95 ms where the soft-start capacitance is 0.047 μF.



- A. Channel 1 is the output voltage rising to 3.3 V.
- B. Channel 2 is the soft-start (SS) pin.

**Figure 36. Soft Start Showing Output Delay and Controlled Rise to Programmed Output Voltage**



## Frequency Compensation

The four elements that determine the system overall response are discussed in the following paragraphs. The gain of the error amplifier ( $K_{EA}$ ) is the first of three elements. Its output develops a control voltage, which is the input to the PWM.

The TPS40200 has a unique modulator that scales the peak-to-peak amplitude of the PWM ramp to be 0.1 times the value of the input voltage. Since modulator gain is given by  $V_{IN}$  divided by  $V_{RAMP}$ , the modulator gain is 10 and is constant at 10 (20 dB) over the entire specified input voltage range.

The last two elements that affect system gain are the transfer characteristic of the output LC filter and the feedback network from the output to the input to the error amplifier.

These four elements may be expressed by the following expression that represents the system transfer function (see [Figure 37](#)).

$$T_V(s) = K_{FB} \times K_{EA}(s) \times K_{PWM} \times X_{LC}(s) \quad (19)$$

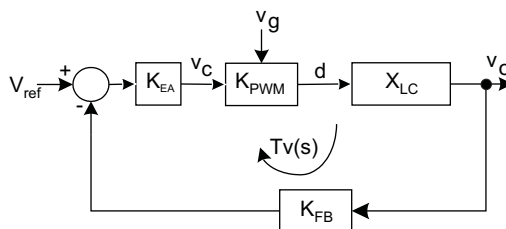
Where:

$K_{FB}$  = Output voltage setting divider

$K_{EA}$  = Error amplifier feedback

$K_{PWM}$  = Modulator gain

$X_{LC}$  = Filter transfer function



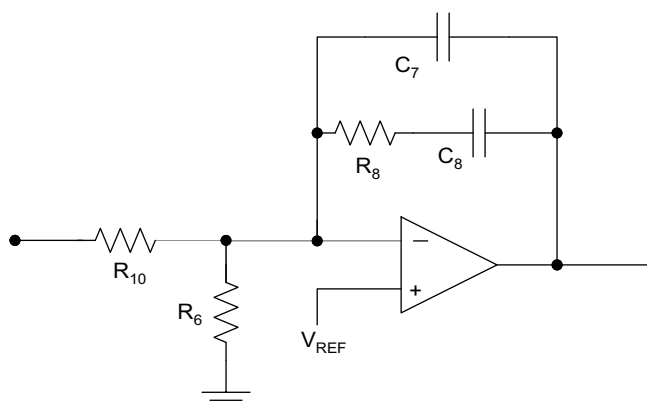
**Figure 37. Control Loop**

Figure 38 shows the feedback network used in this application. This is a type-2 compensation network, which gives a combination of good transient response and phase boost for good stability. This type of compensation has a pole at the origin, causing a  $-20\text{-dB/decade}$  ( $-1$ ) slope, followed by a zero that causes a region of flat gain, followed by a final pole that returns the gain slope to  $-1$ . The Bode plot in Figure 39 shows the effect of these poles and zeros.

The procedure for setting up the compensation network is as follows:

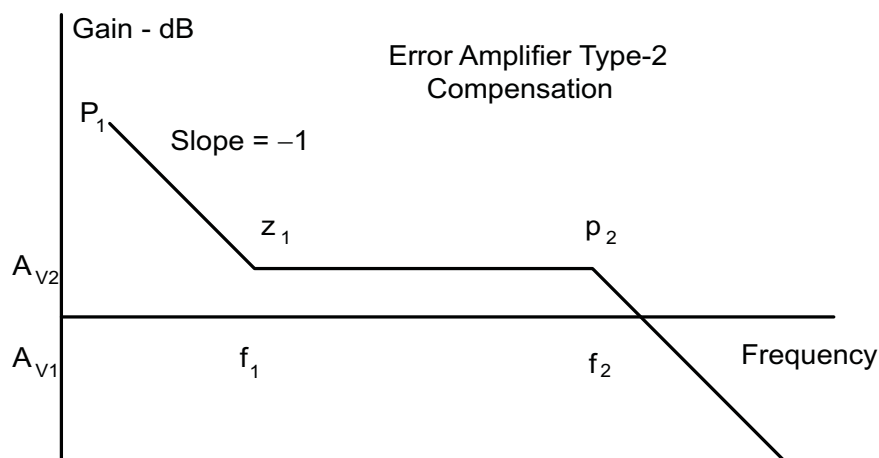
1. Determine the break frequency of the output capacitor.
2. Select a zero frequency well below this break frequency.
3. From the gain bandwidth of the error amplifier, select a crossover frequency where the amplifier gain is large, relative to expected closed-loop gain.
4. Select a second zero well above the crossover frequency, which returns the gain slope to a  $-1$  slope.
5. Calculate the required gain for the amplifier at crossover

Be prepared to iterate this procedure to optimize the pole and zero locations as needed.



**Figure 38. Error Amplifier Feedback Elements**

The frequency response of this converter is largely determined by two poles that arise from the LC output filter and a higher-frequency zero caused by the ESR of the output capacitance. The poles from the output filter cause a  $40\text{-dB/decade}$  rolloff with a phase shift approaching  $180^\circ$ , followed by the output capacitor zero that reduced the rolloff to  $-20\text{ dB}$  and gives a phase boost back toward  $90^\circ$ . In other nomenclature, this is a  $-2$  slope followed by a  $-1$  slope. The two zeros in the compensation network act to cancel the double pole from the output filter. The compensation network's two poles produce a region where the error amplifier is flat and can be set to a gain, such that the overall gain of the system is  $0\text{ dB}$ . This region is set so that it brackets the system crossover frequency.



**Figure 39. Error Amplifier Bode Plot**

In order to properly compensate this system, it is necessary to know the frequencies of its poles and zeros.

### Step 1

The break frequency of the output capacitor is given by:

$$F_{\text{esr}} = \frac{1}{2\pi R_{\text{esr}} C} \quad (20)$$

Where:

$$L = 33 \mu\text{H}$$

$$C = 221 \mu\text{F}$$

Because of the ESR of the output capacitor, this output filter has a single-pole response above the 1.8-kHz break frequency of the output capacitor and its ESR. This simplifies compensation since the system becomes essentially a single-pole system.

### Step 2

The first zero is placed well below the 1.8-kHz break frequency of the output capacitor and its ESR. Phase boost from this zero is shown in [Figure 40](#).

$$f_{Z1} = \frac{1}{2\pi R_8 C_8} \quad (21)$$

Where:

$$R_8 = 100 \text{ k}\Omega$$

$$C_8 = 1500 \text{ pF}$$

$$F_{Z1} = 354 \text{ Hz}$$

### Step 3

From a minimum gain bandwidth product of 1.5 MHz, and knowing it has a 20-dB/decade rolloff, the gain of the error amplifier is 33 dB at 35 kHz. This approximate frequency is chosen for a crossover frequency to keep the amplifier gain contribution to the overall system gain small.

### Step 4

The second zero is placed well above the 35-kHz crossover frequency.

$$f_{P3} = \frac{1}{2\pi \times C_7 \times C_8 \times R_8} \times (C_7 + C_8) \quad (22)$$

Where:

$$R_8 = 300 \text{ k}\Omega$$

$$C_7 = 10 \text{ pF}$$

$$C_8 = 1500 \text{ pF}$$

$$f_{P3} = 53 \text{ kHz}$$

**Step 5**

Calculate the three other gain elements of the system to determine the gain required by the error amplifier at 35-kHz to make the overall gain 0 dB:

$$T_V(S) = K_{FB} \times K_{EA}(S) \times K_{PWM} \times X_{LC}(S) \quad (23)$$

Where:

$K_{FB}$  = Output voltage setting divider

$K_{EA}$  = Error amplifier feedback

$K_{PWM}$  = Modulator gain

$X_{LC}$  = Filter transfer function

The output filter transfer characteristic is given by the following:

$$X_{LC}(S) = \frac{Z_{OUT}(S)}{Z_{OUT}(S) + Z(S) + R_{SW} \times D + R_{SR} \times (1 - D)} \quad (24)$$

Where:

$Z_{OUT}$  = Parallel combination of output capacitor(s) and the load

$Z_{OUT}$  and  $Z_I$  should include parasitic R and L.

Evaluating the response at 35-kHz gives the following:

- The full current output load at 3.3 V is 1.32  $\Omega$ , and is in parallel with the 0.4- $\Omega$  ESR of the output capacitor.
- Including the 400 m $\Omega$  of ESR, the capacitive impedance is 14 m $\Omega$ , and  $Z_{OUT} = 414$  m $\Omega$ .
- The impedance of the inductor is  $Z_I = 1.659$   $\Omega$ .
- $X_{LC}(S) = 0.033$ , or  $-29.6$  dB

The feedback network has a gain to the error amplifier given by:

$$K_{fb} = \frac{R_{10}}{R_6} \quad (25)$$

Where:

$R_6 = 26.7$  k $\Omega$

Using the values in this application,  $K_{fb} = 11.4$  dB.

The modulator has a gain of 10 that is flat to well beyond 35 kHz, so  $K_{PWM} = 20$  dB.

The amplifier gain, including the feedback gain,  $K_{fb}$ , can be approximated by this expression:

$$\frac{V_O}{V_{IN}}(S) = \frac{-A_{VOL}}{1 + \frac{Z_I(S)}{R_6} + \frac{R_{10}}{Z_f(S)} \times (1 + A_{VOL})} \quad (26)$$

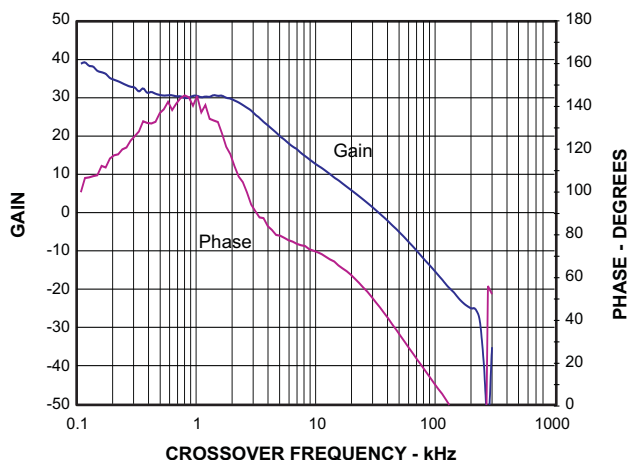
Where:

$Z_I = R_{10}$

$Z_f$  = Parallel combination of  $C_7$  in parallel with the sum of  $R_8$  and the impedance of  $C_8$

The gain required to achieve 0-dB system gain is simply the sum of the other three gains:  $-(-29.6 + 11.4 + 20) = 1.8$  dB. With an open-loop gain of 33 dB, the closed-loop gain of the amplifier is 0.8, or  $-1.66$  dB, which gives a 0.13-dB gain at 35 kHz.

Figure 40 shows the result of the compensation. The crossover frequency is 35 kHz, and the phase margin is 45°. The response of the system is dominated by the ESR of the output capacitor and is exploited to produce an essentially single-pole system with simple compensation.



**Figure 40. Overall System Gain and Phase Response**

Figure 40 also shows the phase boost that gives the system a crossover phase margin of 47°.

The Bill of Materials (BOM) for this application is given in Table 3. The efficiency and load regulation from boards built from this design are shown in Figure 45 and Figure 46. Gerber PC layout files and additional application information are available from the factory.

**Table 3. Bill of Materials, Buck Regulator, 12 V to 3.3 V and 5 V**

REF. DES.	VALUE	DESCRIPTION	SIZE	MFR.	PART NUMBER
C1	100 $\mu$ F	Capacitor, Aluminum, SM, 25-V, 0.3 $\Omega$	8 x 10 mm	Sanyo	20SVP100M
C12	220 $\mu$ F	Capacitor, Aluminum, SM, 6.3-V, 0.4 $\Omega$	8 x 6.2 mm	Panasonic	EEVFC0J221P
C13	100 pF	Capacitor, Ceramic, 50V, [COG], [20%]	603	muRata	Std.
C3	0.1 pF	Capacitor, Ceramic, 50V, [X7R], [20%]	603	muRata	Std.
C2, C11	1 $\mu$ F	Capacitor, Ceramic, 50V, [X7R], [20%]	603	muRata	Std.
C4, C5	470 pF	Capacitor, Ceramic, 50V, [X7R], [20%]	603	muRata	Std.
C6	0.047 $\mu$ F	Capacitor, Ceramic, 50V, [X7R], [20%]	603	muRata	Std.
C7	10 pF	Capacitor, Ceramic, 50V, [COG], [20%]	603	muRata	Std.
C8	1500 pF	Capacitor, Ceramic, 50V, [X7R], [20%]	603	muRata	Std.
D1	12 V	Diode, Zener, 12-V, 350-mW	SOT23	Diodes, Inc.	BZX84C12T
D2		Diode, Schottky, 30-A, 30-V	SMC	On Semi	MBRS330T3
D3	12 V	Diode Zener 12-V 5 mA	VMD2	Rohm	VDZT2R12B
J1,J3		Terminal Block 4-Pin 15-Amp 5.1-mm	0.8 x 0.35	OST	ED2227
J2		Header, 2-pin, 100-mil spacing, (36-pin strip)	0.100 x 2	Sullins	PTC36SAAN
L1	33 $\mu$ H	Inductor, SMT, 3.2 A, .039 $\Omega$	12.5 x 12.5 mm	TDK	SLF12575T330M3R2PF
PCB		2 Layer PCB 2 Ounce Cu	1.4 x 2.12 x 0.062		HPA164
Q1		Trans, N-Chan Enhancement Switching, 50 mA	SOT-143B	Phillips	BSS83
Q2		MOSFET, P-ch, 30-V, 3.6-A, 75-m $\Omega$	SuperSOT-6	Fairchild	FDC654P
U1		IC, Low Cost Non-Sync Buck Controller	SO-8	TI	TPS40200D
R1	10 $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R10	100 k $\Omega$	Resistor, Chip, , 1/16W, 1%	603	Std.	Std.
R11	10 k $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R12	1 M $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R13	49.9 $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R2	0.02 $\Omega$	Resistor, Chip, $\diamond$ W, 5%	2010	Std.	Std.
R3	68.1 k $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R4	2.0 k $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R5	0 $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R6	26.7 k $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R7	1.0 k $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.
R8	300 k $\Omega$	Resistor, Chip, 1/16 W, 1%	603	Std.	Std.

## PC Board Plots

Figure 41 through Figure 43 show the design of the TPS40200EVM-001 printed circuit board. The design uses 2-layer, 2-oz copper and is 1.4-in  $\times$  2.3-in in size. All components are mounted on the top side to allow the user to easily view, probe, and evaluate the TPS40200 control IC in a practical application. Moving components to both sides of the PCB or using additional internal layers can offer additional size reduction for space-constrained applications.

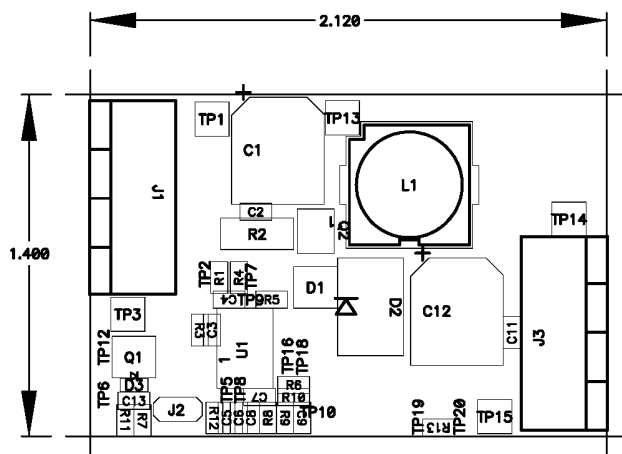


Figure 41. TPS40200EVM-001 Component Placement (Viewed From Top)

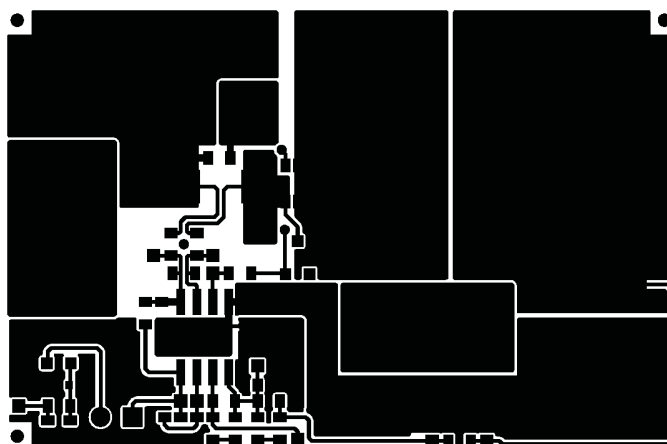


Figure 42. TPS40200EVM001 Top Copper (Viewed From Top)



Figure 43. TPS40200EVM-001 Bottom Copper (X-Ray View From Top)

## Application 2: 18-V to 50-V Input, 16 V at 1-A Output

This is an example of using the TPS40200 in a higher-voltage application. The output voltage is 16 V at 1 A, with an 18-V to 50-V input. Module boards built to this schematic, and a test report, are available from the factory. The following shows some of the test results.

### Test Results

Figure 45 and Figure 46 show some of the performance obtained from this application. Further information and support material is available from the factory.

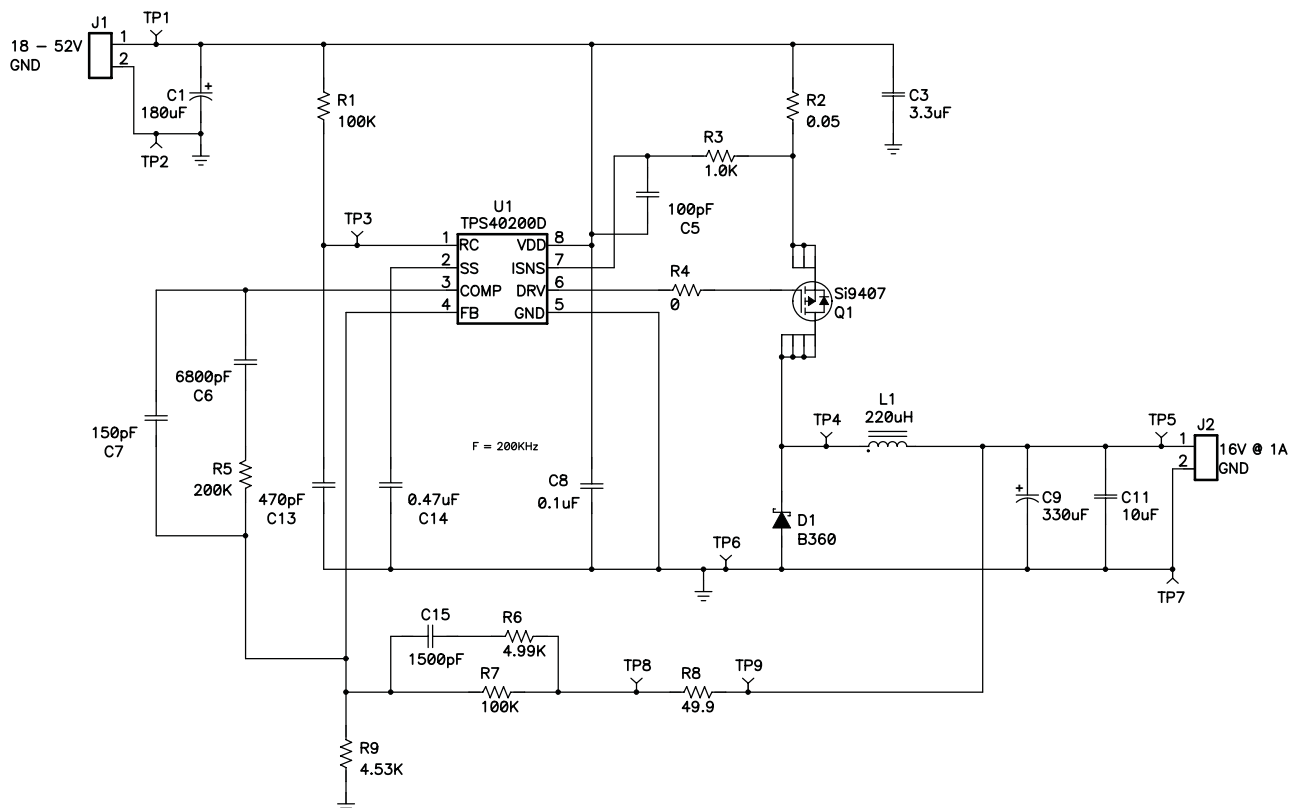


Figure 44. Buck Converter ( $V_{IN} = 18\text{ V to } 50\text{ V}$ ;  $V_{OUT} = 16\text{ V at } 1\text{ A}$ )

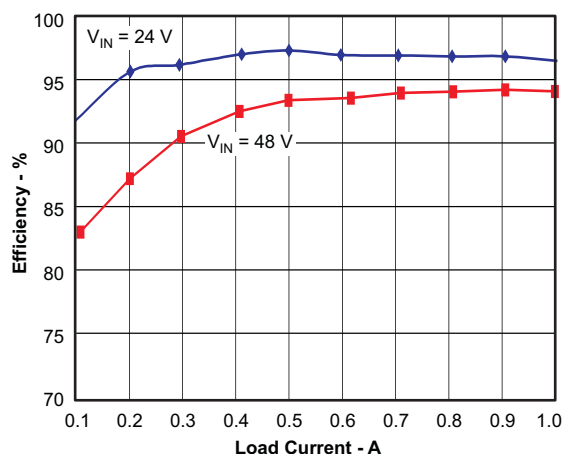


Figure 45. Efficiency vs Load

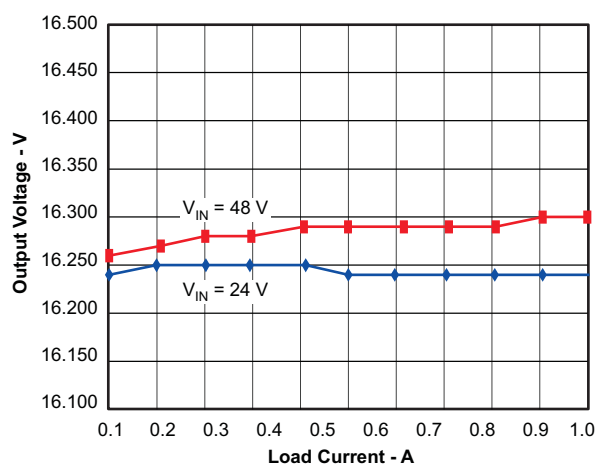


Figure 46. Load Regulation, Two Input Voltage Extremes



### Application 3: Wide Input Voltage LED Constant-Current Driver

This application uses the TPS40200 as a buck controller that drives a string of LED diodes. The feedback point for this circuit is a sense resistor in series with this string. The low 0.7-V reference minimizes power wasted in this resistor, and maintains the LED current at a value given by  $0.7/R_{\text{SENSE}}$ . As the input voltage is varied, the duty cycle changes to maintain the LED current at a constant value so that the light intensity does not change with large input voltage variations.

Vin 12V – 30 V

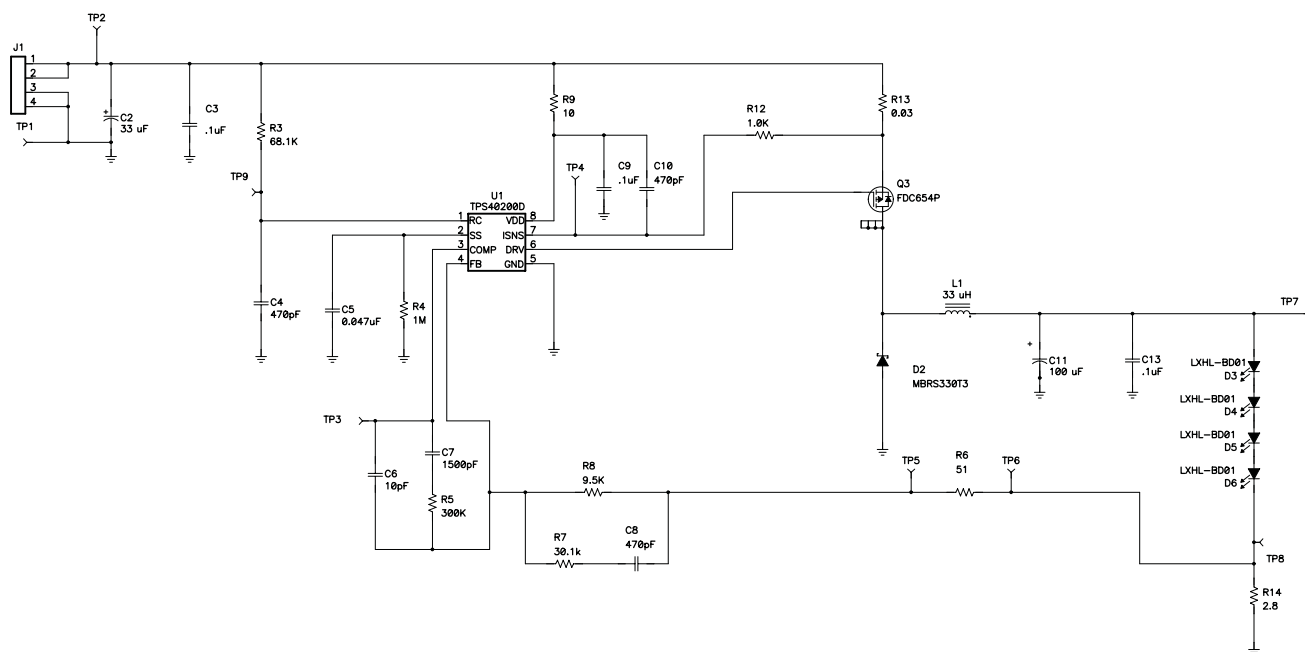


Figure 47. Wide Input Voltage-Range LED Driver

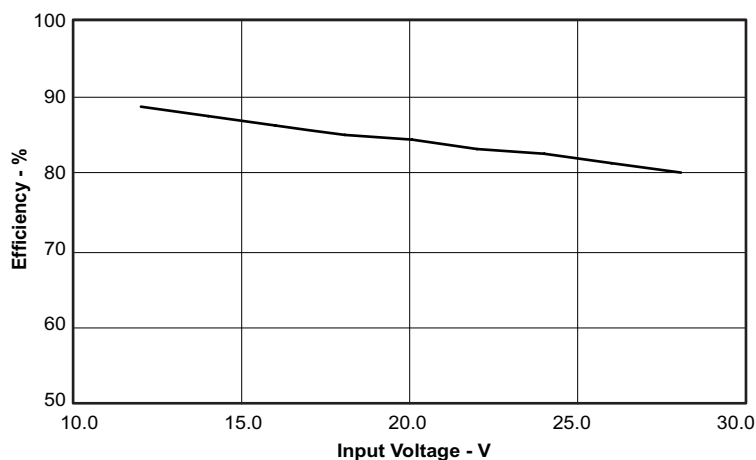
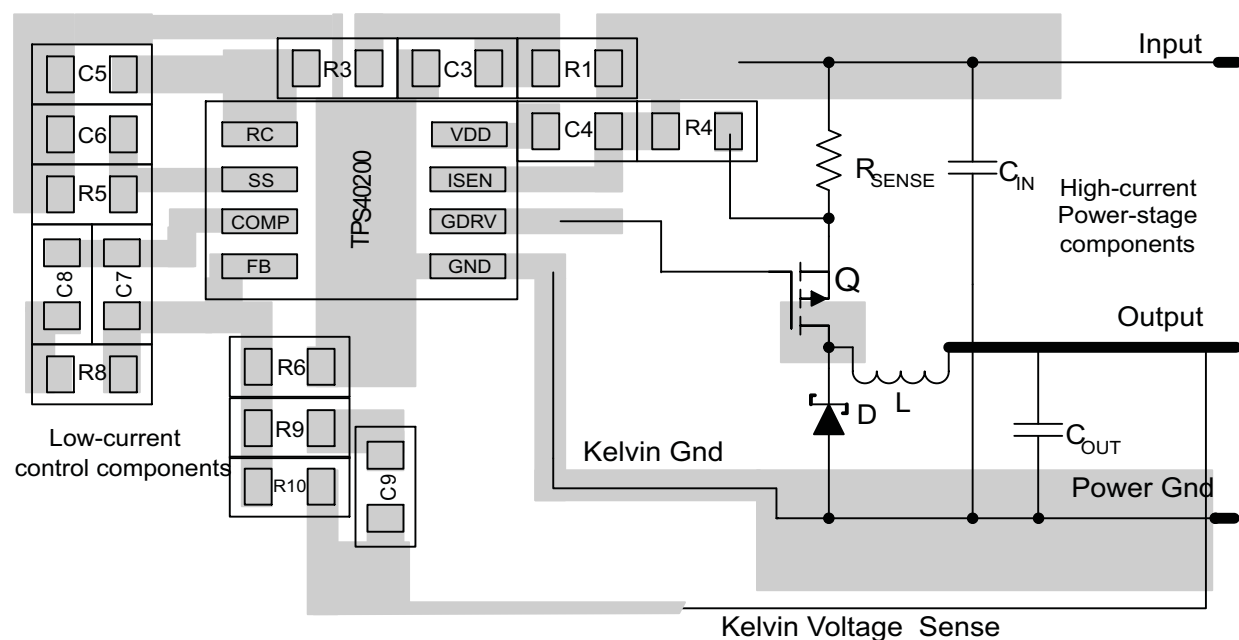
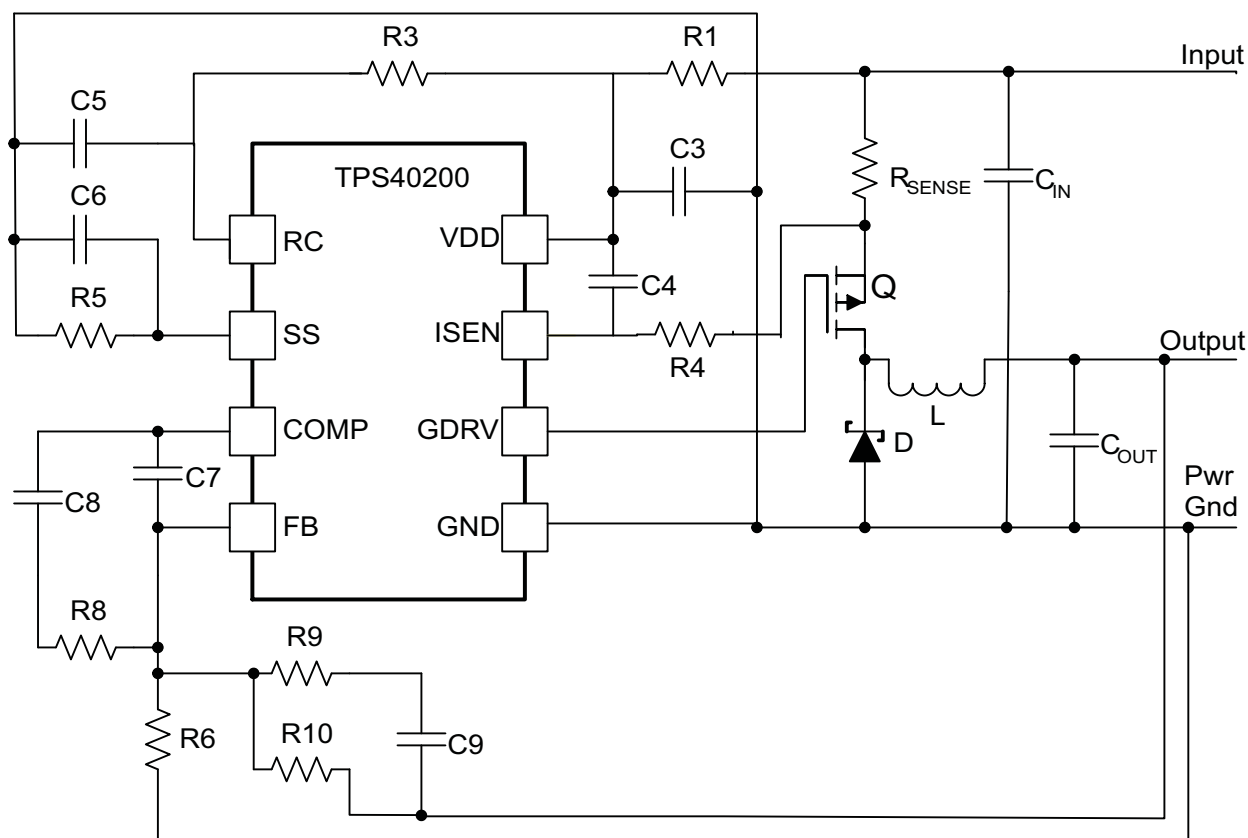


Figure 48. Efficiency vs Input Voltage

## DESIGN REFERENCES

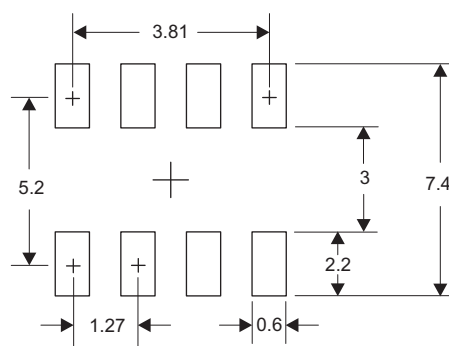


**Figure 49. PC Board Layout Recommendations**

**Layout Hints**

- AC current loops must be kept as short as possible. For the maximum effectiveness from C1, place it near the VDD pin of the controller and design the input ac loop consisting of C1-R<sub>SENSE</sub>-Q1-D1 to be as short as possible. Excessive high-frequency noise on VDD during switching degrades overall regulation as the load increases.
- Output loop A (D1-L1-C2) also should be kept as small as possible. Otherwise, the application's output noise performance is degraded.
- It is recommended that traces carrying large ac currents NOT be connected through a ground plane. Instead, use PCB traces on the top layer to conduct the ac current and use the ground plane as a noise shield. Split the ground plane as necessary to keep noise away from the TPS40200 and noise-sensitive areas, such as feedback resistors, R6 and R10.
- Keep the SW node as physically small as possible to minimize parasitic capacitance and to minimize radiated emissions
- For good output voltage regulation, Kelvin connections should be brought from the load to R6 and R10.
- The trace from the R6-R10 junction to the TPS40200 should be short and kept away from any noise source, such as the SW node.
- The gate drive trace should be as close to the power FET gate as possible.

The TPS40200 is encapsulated in a standard plastic SOIC-8 package. The typical PC-board layout for this package is shown in [Figure 50](#).



Dimensions are in millimeters

**Figure 50. Suggested SOIC-8 PC-Board Footprint**

### Related Parts

- TPS4007/9 Low Input Synchronous Buck Controller
- TL5001 Wide Input Range Controller

### Reference Documents

- *Under the Hood of Low Voltage DC/DC Converters*, SEM1500 Topic 5, 2002 Seminar Series
- *Understanding Buck Power Stages in Switchmode Power Supplies*, SLVA057, March 1999
- *Design and Application Guide for High Speed MOSFET Gate Drive Circuits*, SEM 1400, 2001 Seminar Series
- *Designing Stable Control Loops*, SEM 1400, 2001 Seminar Series
- Power.TI.com
- TPS40K designer software. This simple design tool supports the TPS40xxx family of controllers. To order a CD from the Product Information Center, request SLU015-TPS40k/SWIFT CD-ROM.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">TPS40200MDREP</a>	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-55 to 125	40200M
TPS40200MDREP.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-55 to 125	40200M
<a href="#">V62/07618-01XE</a>	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-55 to 125	40200M

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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### OTHER QUALIFIED VERSIONS OF TPS40200-EP :

- Catalog : [TPS40200](#)

- Automotive : [TPS40200-Q1](#)

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product
- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS40200MDREP	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS40200MDREP	SOIC	D	8	2500	340.5	338.1	20.6



**D0008A****PACKAGE OUTLINE****SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

**NOTES:**

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

**D0008A**

### SOIC - 1.75 mm max height

## SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:8X



## SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.125 MM] THICK STENCIL  
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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