## Permanent magnet stepper motors

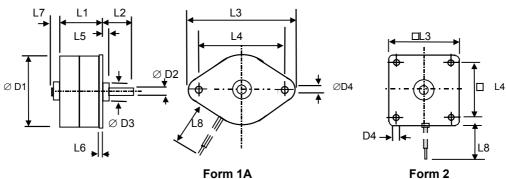
#### **Commercial series**

The M series instrument stepper motors are high quality permanent magnet types providing a choice of 18,15, 7.5 or 3.6 degree step angle.

The motors may be specified fitted with gearheads where increased torque and resolution are required at reduced operating speed. The M series motors offer excellent performance combined with low pricing. They are ideally suited to instrumentation applications where large production volumes are likely. A comprehensive programme of drives, power supplies and controllers are available for the small volume user to construct advanced single and multi-axis positioning systems.



#### **Dimensions:**



| motor type | form | dimensions mm |      |      |     |       |      |      |       |      |     |      |     |
|------------|------|---------------|------|------|-----|-------|------|------|-------|------|-----|------|-----|
|            |      | D1            | D2   | D3   | D4  | L1    | L2   | L3   | L4    | L5   | L6  | L7   | L8  |
| 15M020D    | 1 A  | 15.01         | 1.5  | 5.97 | 2.2 | 15.11 | 10   | 24   | 20    | 1.5  | 8.0 | 2.1  | 90  |
| 26S024B    | 1 A  | 26.2          | 2.0  | 7.92 | 3.3 | 13.3  | 12.7 | 42.8 | 35    | 3.8  | 8.0 | Nil  | 191 |
| 26M048B    |      |               |      | 10   |     | 13.72 | 11.3 |      |       | 1.52 |     | 3.4  |     |
| 35L048B    | 1 A  | 36            | 2.0  | 10   | 3.2 | 21.1  | 11.3 | 50   | 42    | 1.8  | 8.0 | 2    | 191 |
| 42M048C    | 1 A  | 42            | 3.0  | 10   | 3.5 | 22.0  | 11.4 | 56.5 | 49.5  | 1.52 | 8.0 | 3.5  | 305 |
| 60L 048B   | 1 A  | 59.2          | 6.35 | 12   | 4.3 | 37.9  | 19.1 | 79.4 | 66.68 | 2.0  | 1.6 | Nil  | 305 |
| 42M100B-2U | 2    | 42            | 3.0  | 10   | 3.5 | 15.5  | 11.4 | 42   | 35    | 1.52 | 8.0 | 3.4  | 305 |
| 42M100B-1U | 1 A  | 42            | 3.0  | 10   | 3.5 | 15.5  | 11.4 | 56.5 | 49.48 | 1.52 | 8.0 | 3.4  | 305 |
| MV82801    | 2    | 59.2          | 6.0  | 12   | 4.3 | 37.9  | 18   | 65   | 56    | 2.03 | 1.6 | 2.23 | 305 |

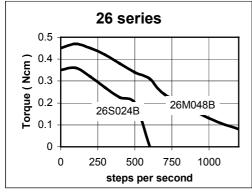
# **Specification**

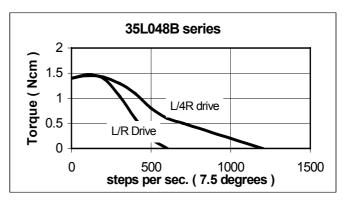
| motor type | step<br>angle | holding<br>torque | rotor<br>inertia  | resistance<br>per phase | current<br>per phase | inductance<br>per phase | number<br>of leads or | mass |
|------------|---------------|-------------------|-------------------|-------------------------|----------------------|-------------------------|-----------------------|------|
|            | degrees       | Ncm               | Kgcm <sup>2</sup> | ohms                    | amps                 | mH                      | terminals             | gms  |
| 15M020D-1B | 18            | 0.388             | 0.00011           | 40                      | 0.125                | 14                      | 4                     | 14   |
| 26S024B-2U | 15            | 0.5               | 0.00045           | 118                     | 0.1                  | 33.8                    | 6                     | 28   |
| 26M048B-2U | 7.5           | 0.9               | 0.0011            | 110                     | 0.1                  | 36.5                    | 6                     | 28   |
| 26M048B-1U |               |                   |                   | 19.6                    | 0.25                 | 5.3                     |                       |      |
| 35L048B-2U | 7.5           | 2.5               | 0.004             | 64                      | 0.18                 | 40                      | 6                     | 88   |
| 35L048B-1U | 7.5           | 2.5               | 0.004             | 11                      | 0.45                 | 7.8                     | 6                     | 88   |
| 42M048C-2U | 7.5           | 6.6               | 0.0134            | 52.4                    | 0.23                 | 51.7                    | 6                     | 144  |
| 42M048C-1U | 7.5           | 6.6               | 0.0134            | 9.1                     | 0.55                 | 8.1                     | 6                     | 144  |
| 60L048B-2U | 7.5           | 16.9              | 0.095             | 26.2                    | 0.46                 | 26.2                    | 6                     | 478  |
| 60L048B-1U | 7.5           | 16.9              | 0.095             | 4.55                    | 1.0                  | 6.4                     | 6                     | 478  |
| MV82801-P2 | 7.5           | 19.8              | 0.095             | 26                      | 0.46                 | 33                      | 6                     | 440  |
| MV82801-P1 | 7.5           | 19.8              | 0.095             | 4.6                     | 1.0                  | 6                       | 6                     | 440  |
| 42M100B-2U | 3.6           | 4.5               | 0.0118            | 75                      | 0.16                 | 37.7                    | 6                     | 87   |
| 42M100B-1U | 3.6           | 4.5               | 0.0118            | 12.5                    | 0.40                 | 6.6                     | 6                     | 87   |

note The above motors are 4 phase units suitable for use with uni-polar or bi-polar drive circuits with the exception of the 15M029D-1B motor which is designed specifically for Bi-polar operation.
Bi-polar versions of the other motors in the range are available to special order.



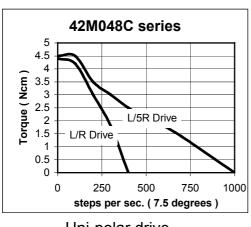
# Typical permanent magnet stepper motor performance

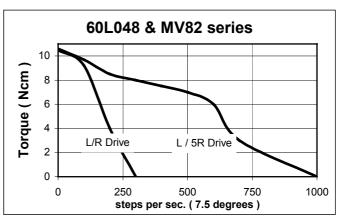




Uni-polar drive

Uni-polar drive





Uni-polar drive

Uni-polar drive

### Suitable modular drives for above motors: MSE422, PVP134, PM542

## **Explanation of terminology**

The motors may be connected directly to a dc supply of the same value as the motor rating. For example, the 35L048B-2U motor is a 12 Volt rated unit and therefore may be connected directly to a 12 Vdc supply as shown in Fig 1. This is often referred to as **L/R Drive** 

For increased high speed performance however it is quite usual to connect the motor to a higher supply voltage via series resistors since the current rise time in the motor's coils is proportional to the inductance ( L ) divided by the resistance ( R ) in the drive circuit.

For example, the 42M048C-1U motor is a 5 Volt rated unit. When connected to a 24 Vdc supply via series resistors the ratio of inductance/ resistance will be greatly improved. In this case the system, as shown in Fig 2 would approximate an **L/5R** drive.

Alternatively a more sophisticated drive system can be employed using chopped constant current techniques when the series resistors are not required. A suitable drive of this type is PM542

