

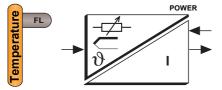
Programmable Intrinsically Safe Loop-Powered Temperature Measuring Transducer for Connection Head With HART[®] Protocol

INTERFACE

Data Sheet

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1 Description



Universal PC programmable temperature measuring transducers convert temperature signals from resistance thermometers and thermocouples as well as sensors with linear mV characteristic curves to analog 4 ... 20 mA signals.

On the output side the temperature measuring transducer is operated in a 4 ... 20 mA current loop, which simultaneously provides the devices with the required power for signal conversion.

The configuration data can be set via the HART[®] protocol. A programming adapter can be used for this in conjunction with the MCR-PI-CONF-WIN configuration software (Order No. 2814799) or a hand-held operator panel (e.g., DXR 275 from Emerson).

Customer-specific measuring range settings, linearization, and characteristic curve adjustments can also be implemented in this way. With a 2-wire circuit, the cable resistance can be compensated.

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Failure information in the event of sensor break or sensor short-circuit can be set according to NE 43. This measuring transducer maintains a high level of accuracy throughout the entire ambient temperature range.

The devices are supplied with the following default configuration: Pt 100 sensor, measuring range 0°C ... +100°C, 3-wire connection.

Features

- For resistance thermometers, thermocouples, resistance-type and voltage sensors
- For installation in connection head, form B
- Application in potentially explosive areas
- Application for safety-related functions



Observe the safety instructions on page 5.

Make sure you always use the latest documentation. It can be downloaded at www.download.phoenixcontact.com.

A conversion table is available on the Internet at www.download.phoenixcontact.com/general/7000 en 00.pdf.

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PHOENIX CONTACT GmbH & Co. KG • 32823 Blomberg • Germany Phone: +49 - 52 35 - 30 0 • Fax: +49 - 52 35 - 34 12 00 • www.phoenixcontact.com www.phoenixcontact.com/salesnetwork

Input Signals

	Designation	Measuring Range Limits	Minimum Measurement Range	
	Pt 100	-200°C +850°C	10 K	
	Pt 500	-200°C +250°C	10 K	
	Pt 1000	-200°C +250°C	10 K	
	According to IEC 60751			
Resistance Thermometer	Ni 100	-60°C +250°C	10 K	
(RTD)	Ni 500	-60°C +150°C	10 K	
	Ni 1000 -60°C +150°C		10 K	
	According to DIN 43760			
	 Connection method: 2, 3 or 4 			
	- With 2-wire termination, the cable resistance can be compensated using software $(0 \ \Omega \dots 30 \ \Omega)$			
	– With 3 and 4-wire termination, sensor cable resistance up to a maximum of 11 Ω per cable			
	– Sensor current \leq 0.2 mA			
Resistance-Type Sensor	Resistance (Ω)	10 Ω 400 Ω	10 Ω	
		10Ω 2000 Ω	100 Ω	
			Minimum	
	Designation	Measuring Range Limits	Measurement Range	
	Designation B (PtRh30-PtRh6)	Measuring Range Limits 0°C +1820°C		
			Range	
	B (PtRh30-PtRh6)	0°C +1820°C	Range 500 K	
	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹	0°C +1820°C 0°C +2320°C	Range 500 K 500 K	
	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹	0°C +1820°C 0°C +2320°C 0°C +2495°C	Range 500 K 500 K 500 K	
	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi)	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C	Range 500 K 500 K 500 K 500 K 500 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi)	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C	Range 500 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni)	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C	Range 500 K 500 K 500 K 500 K 50 K 50 K 50 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni) L (Fe-CuNi) ²	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C -200°C +900°C	Range 500 K 500 K 500 K 500 K 50 K 50 K 50 K 50 K 50 K 50 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni) L (Fe-CuNi) ² N (NiCrSi-NiSi)	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C -200°C +900°C -270°C +1300°C	Range 500 K 500 K 500 K 500 K 50 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni) L (Fe-CuNi) ² N (NiCrSi-NiSi) R (PtRh13-Pt)	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C -200°C +900°C -270°C +1300°C -50°C +1768°C	Range 500 K 500 K 500 K 50 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni) L (Fe-CuNi) ² N (NiCrSi-NiSi) R (PtRh13-Pt) S (PtRh10-Pt)	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C -200°C +900°C -270°C +1300°C -50°C +1768°C -50°C +1768°C	Range 500 K 500 K 500 K 500 K 50 K 500 K 500 K 500 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni) L (Fe-CuNi) ² N (NiCrSi-NiSi) R (PtRh13-Pt) S (PtRh10-Pt) T (Cu-CuNi)	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C -200°C +900°C -270°C +1300°C -50°C +1768°C -50°C +1768°C -270°C +400°C	Range 500 K 500 K 500 K 50 K 500 K 500 K 500 K 500 K 500 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni) L (Fe-CuNi) ² N (NiCrSi-NiSi) R (PtRh13-Pt) S (PtRh10-Pt) T (Cu-CuNi) U (Cu-CuNi) ² According to IEC 60584-1 – Reference junction: Internal (0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C -200°C +900°C -270°C +1300°C -50°C +1768°C -50°C +1768°C -270°C +400°C -200°C +600°C Pt 100)	Range 500 K 500 K 500 K 50 K 500 K 500 K 500 K 500 K 500 K	
Thermocouple (TC)	B (PtRh30-PtRh6) C (W5Re-W26Re) ¹ D (W3Re-W25Re) ¹ E (NiCr-CuNi) J (Fe-CuNi) K (NiCr-Ni) L (Fe-CuNi) ² N (NiCrSi-NiSi) R (PtRh13-Pt) S (PtRh10-Pt) T (Cu-CuNi) U (Cu-CuNi) ² According to IEC 60584-1	0°C +1820°C 0°C +2320°C 0°C +2495°C -270°C +1000°C -210°C +1200°C -270°C +1372°C -200°C +900°C -270°C +1300°C -50°C +1768°C -50°C +1768°C -270°C +400°C -200°C +600°C Pt 100)	Range 500 K 500 K 500 K 50 K 500 K 500 K 500 K 500 K 500 K	

¹ According to ASTM E988

² According to DIN 43710

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2	Ordering Data			
Temp	perature Measuring Transducer for Connection Hea	d		
Desc	ription	Туре	Order No.	Pcs./Pck.
	emperature measuring transducer for connection head, for resistance meters, thermocouples, resistance-type sensors and voltage sensors	MCR-FL-HT-TS-I-EX	2864545	1
Softv	vare			
Desc	ription	Туре	Order No.	Pcs./Pck.
Config	uration software	MCR-PI-CONF-WIN	2814799	1
3	Technical Data			
Input	t			
Resista	ance thermometers	Pt 100, Pt 500, Pt 1000 and N	Ni 100, Ni 500, Ni 1000 in :	2, 3 or 4-wire
		technology; minimum measur	rement range 10 K	
Therm	ocouple sensors	B, C, D, E, J, K, L, N, R, S, T,	, U; minimum measureme	nt range 50 K/500
Linear	mV signals	-10 mV +75 mV; minimum	measurement range 5 mV	
Resista	ance-type sensors	10 Ω 2000 Ω and 10 Ω 40	$00 \ \Omega;$ minimum measurem	ent range 10 Ω/100
Outp	ut			
Output	signal	4 mA 20 mA/20 mA 4 m	A	
Maxim	um output signal	≤ 23 mA		
Maxim	um load	(V _{supply} - 10 V)/0.023 A		
Output	signal in the event of open circuit/short circuit (not for thermocouples)			
-	ring range overrange/underrange	≤ 20.5 mA/≥ 3.8 mA (linear increase/decrease)		
Gene	eral Data			
Supply	voltage	12 V DC 30 V DC		
Permis	sible residual ripple	$U_{PP} \leq 3~V$ at $U_b \geq 13~V$ and f_n	_{nax} = 1 kHz	
Maxim	um current consumption	< 3.5 mA		
Transn	nission error ¹			
Res	istance Thermometer (RTD)	0.2 K or 0.08% (Pt 100, Ni 10 0.5 K or 0.20% (Pt 500, Ni 50 0.3 K or 0.12% (Pt 1000, Ni 1	0),	
The	rmocouple (TC)	0.5 K or 0.08% (K, J, T, E, L, U), typical, 1.0 K or 0.08% (N, C, D), typical, 2.0 K or 0.08% (S, B, R), typical		
Res	istance-type sensor (Ω)	±0.1Ω or 0.08% (10 Ω 400 Ω), ±1.5 Ω or 0.12% (10 Ω 2000 Ω)		
Volt	age sensor (mV)	±20 μV or 0.08% (-10 mV \ldots 7	75 mV)	
Influen	ce of the ambient temperature (temperature drift)			
Res	istance thermometer (RTD)	Td = $\pm(15$ ppm/K x maximum measuring range + 50 ppm/K x set measurir range) x $\Delta\vartheta)^2$		
Res	istance thermometer (Pt100)	Td = \pm (15 ppm/K x (measuring range final value + 200) + 50 ppm/K x set measuring range) x Δ 9) ²		
The	rmocouple (TC)	Td = \pm (50 ppm/K x maximum measuring range + 50 ppm/K x set measurin range) x Δ 9) ²		
Influen	ce of the load ³	$\leq \pm 0.02\%/100 \Omega$		
	nse time	< 2 s		
•	-on delay	6 s		
	bltage (input/output)	2 kV AC, 50 Hz, 1 minute		
	nt temperature range			
AIIDIEI				
	ion	See "Safety Data" on bade 4		
Operat Storag		See "Safety Data" on page 4 -40°C +100°C		

General Data (Continued)	
Condensation	Permitted
Degree of protection	IP00, IP66 (installed in connection head)
Mounting position	Any
Installation position	Connection head according to DIN 43729 form B
Resistance to shock and vibration	4g/2 Hz 150 Hz according to IEC 60068-2-6
Configuration	Via HART [®] protocol
Housing material	Polycarbonate (PC), sealing material (PUR)
Dimensions (diameter x height)	44 mm x 21 mm
Weight	40 g, approximately
Connection data	
Solid	0.2 mm ² 1.75 mm ²
Stranded	0.2 mm ² 1.75 mm ²
¹ Percentage values refer to the set measurement range.	
2 $\Delta \vartheta$ = Difference between the ambient temperature and the reference	e condition.
³ All data refers to the measuring range final value.	

Conformance With EMC Directive 89/336/EEC	
Noise emission	EN 61326 and NAMUR NE 21
Immunity to interference	EN 61326 and NAMUR NE 21
Safety Data	
Maximum input voltage Ui	30 V
Maximum input current I _i	100 mA
Maximum input power P _i	750 mW
Maximum output voltage Uo	5 V DC
Maximum output current I _o	5.4 mA
Maximum output power Po	6.6 mW
Maximum ambient temperature range	
Category 1	T6 = -20°C +40°C, T5 = -20°C +50°C, T4 = -20°C +60°C
Category 2	T6 = -40°C +55°C, T5 = -40°C +70°C, T4 = -40°C +85°C
Gas group without existing concentrated external inductance and capacitance	
Maximum external inductance Lo	1000 mH
Maximum external capacitance Co	10 μF
Gas group with existing concentrated external inductance and capacitance	II A/II B II C
Maximum external inductance Lo	100 mH 100 mH
Maximum external capacitance Co	9.9 μF 2 μF

CE
(Ex) II 1 G and II 2 G EEx ia IIC T6/T5/T4 PTB 02 ATEX 2028
εψι us
LISTED
Cl. I Zn. 0, Ex ia IIC T4/T5/T6
Cl. I Div. 2, Groups A, B, C and D
C.D. No. 83035297
 A) This equipment is suitable for use in Class I, Division 2, Groups A, B, C and D or non-hazardous locations only.
B) Warning - explosion hazard - substitution of components may impair suitability for Class 1, Division 2.
C) Warning - explosion hazard - do not disconnect equipment unless power has been switched off or the area is known to be non-hazardous.

4 Safety Instructions

4.1 Explosion Protection



- Install the device according to the manufacturer's instructions and the relevant standards and regulations.
- Parameterization in the Ex area is also permitted with an approved hand-held operator panel. Observe the relevant regulations for connecting intrinsically safe circuits together.

Safety Instructions for Zones 1 and 2



This item of equipment can be used in zone 1 (II 2G) or zone 2 (II 3G). The sensor circuit should be inserted in zone 0 (II 1G).

Safety Instructions for Zone 0

This information must only be observed if the device is installed directly in zone 0.



- Explosive vapor/air mixtures must only occur under atmospheric conditions:
- -20°C \leq T_a \leq +60°C and 0.8 bar \leq p \leq 1.1 bar.
- If there are no explosive mixtures present or additional measures have been met according to EN 61127-1, the devices may also be operated outside the atmospheric conditions according to the manufacturer's specifications.
- The supply circuit must meet protection type EEx ia IIC (EN 60079-14 12.3).
- The devices must only be used in measurement media, to which the materials used in the process
 are sufficiently resistant.
- When operating the entire device in zone 0, the compatibility of the device materials with the measurement media must be ensured (polycarbonate (PC) housing, polyurethane (PUR) sealant).
- The temperature measuring transducer must be installed in such a way that there is no risk of electrostatic discharge, e.g., by installing it in a grounded metal head or in grounded housing.



For use in the USA, Control Drawing No. 83035297 must be taken into account due to UL approval (see page 14).

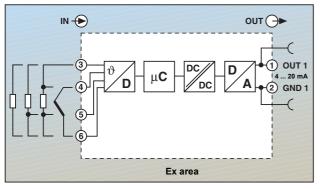
4.2 Use in Safety-Related Protective Functions (SIL)



The device is used for temperature measurements, which must meet the special requirements of safety technology according to IEC 61508/IEC 61511-1. This is the case when used in safety-related protective functions to prevent overtemperature and undertemperature.

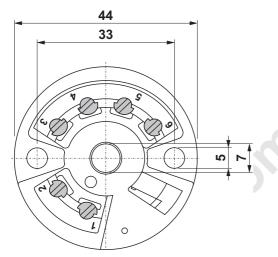
5 Structure

5.1 Block Diagram





5.2 Dimensions



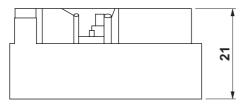


Figure 2 Dimensions (in mm)

6 Use in Safety-Related Protective Functions

The temperature measuring transducer for connection head is suitable for use in a safetyrelated protective function according to IEC 61511-1 if the corresponding safety information is observed.

FMEDA gives the following parameters:

SIL		2	
Test interval	1 year		
Device type		В	
HFT ¹	0 (single-channel application)		
SFF	> 73%		
PFD _{AVG} ²	4.69 x 10 ⁻⁴		
MTBF ³	263 years		
Safety function ⁴ monitoring	Minimum	Maximum	Range
λ _{sd}	26 FIT	101 FIT	117 FIT
λ _{su}	165 FIT	165 FIT	165 FIT
λ _{dd}	108 FIT	33 FIT	17 FIT
λ _{du}	107 FIT	107 FIT	107 FIT

¹ According to Section 11.4.4 of IEC 61511-1

- ² The value is within the range defined for SIL 2 according to ISA S84.01 and IEC 61511-1
- ³ According to Siemens SN29500
- $^{\rm 4}$ $\,$ Assuming that the setting is 4 mA \ldots 20 mA $\,$

The device has been assessed including any modifications as part of operational testing certification.

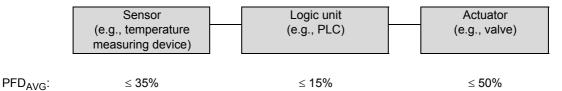


Figure 3 Typical distribution of the "average probability of failure on demand for a safety function" (PFD_{AVG}) over subsystems

B

In this documentation the MCR-FL-HT-TS-I-EX is part of a safety function.

6.1 Safety Integrity Level MCR-FL-HT-TS-I-EX (Type B) (Device Version V1.02.08 or Later)

The following table shows the achievable Safety Integrity Level (SIL) of the overall safety-related system for type B systems depending on the safe failure fraction (SFF) and the hardware fault tolerance (HFT). Type B systems include, e.g., sensors with complex components such as ASICs (see also IEC 61508-2).

Safe Failure Fraction (SFF)	Hardware Fault Tolerance (HFT)		
	0	1 (0) ¹	2 (1) ¹
< 60%	Not permitted	SIL 1	SIL 2
60% < 90%	SIL 1	SIL 2	SIL 3
90% < 99%	SIL 2	SIL 3	-
≥ 99%	SIL 3	-	-

¹ According to IEC 61511-1, Section 11.4.3, the hardware fault tolerance (HFT) for sensors and actuators with complex components can be decreased by one (value in brackets), if the following requirements are met:

- The device has been operationally tested.

- The user can only configure process-related parameters, e.g., measuring range, signal direction in the event of an error, etc.

- The device configuration level is protected, e.g., via a jumper or password (here: numerical code).

- The function has a required safety integrity level (SIL) of less than 4.

The MCR-FL-HT-TS-I-EX meets all requirements.

7 Safety Function With MCR-FL-HT-TS-I-EX 4 mA ... 20 mA Logic unit e.g., PLC, limit signal transmitter, etc. MCR-FL-HT-TS-I-EX 100262401

Figure 4 Safety function (e.g., for temperature limit monitoring) with the MCR-FL-HT-TS-I-EX as a subsystem

The MCR-FL-HT-TS-I-EX temperature measuring transducer for connection head generates an analog signal (4 mA ... 20 mA) proportional to the temperature. The analog signal is supplied to a subsequent logic unit, e.g., a PLC or a limit signal transmitter, and is monitored there for exceeding a maximum value.



The logic unit must be able to recognize HI alarms \geq 21.6 mA and LO alarms \leq 3.6 mA to enable malfunction detection.

Specifications for the Safety Function

- See "Safety Parameters" on page 10.
- A replacement time (MTTR) of 8 hours is specified.
- Safety-related systems without auto-locking function must be set to a monitored or otherwise safe state within the replacement time after execution of the safety function.
- SIL applies to device version V1.02.08 or later.

8 Startup and Periodic Checks

8.1 Using the Device for Continuous Measurements

The operation of the safety equipment must be checked at appropriate intervals. It is the operators' responsibility to select the type of checks and the checking intervals in the specified time period. The checks must be performed so that error-free operation of the safety equipment with the interaction of all components is proven.

8.2 Suggested Procedure for Periodic Checks

Tools required for periodic checks:

- Amp meter
- Wire jumper (only for RTD)

Test Steps

- Set two points within the set measuring range, either with resistance decade or a connected sensor with sufficiently accurate reference conditions. Measure output currents.
- 2. Disconnect sensor from input, the input is open. Measure output current.
- Only if using RTD: Short circuit input with wire jumper. Measure output current.

Error Classification

The following table is used to assess the test results for test steps 1 to 3. As soon as one of the test steps returns the result "dangerous", the device has failed dangerously and the remaining test steps can be ignored.

Test Step	Test Result Output Current	Classification
1	Leakage current (see page 8)	Safe
1	Output current corresponds to the created values (within the limits of the specification, see "Output" on page 3).	Normal operation
1	Output current does not correspond to the created values	Dangerous
2	Leakage current	Safe
2	Not leakage current	Dangerous
3 (only RTD)	Leakage current	Safe
3 (only RTD)	Not leakage current	Dangerous

Assessment

If one of the test steps results in a dangerous failure, a dangerous fault is present on the device.



In the event of this, please inform Phoenix Contact that a device has failed in a protective function with a dangerous fault.

8.3 Settings

For the MCR-FL-HT-TS-I-EX, the MCR-PI-CONF-WIN configuration software can be used to make various software settings.

9 Safety Parameters

TI (test interval, complete function test): Yearly

$\ensuremath{\mathsf{PFD}_{\mathsf{AVG}}}$ Depending on the Selected Maintenance Interval

The following diagram illustrates the dependency of PFD_{AVG} on the maintenance interval. PFD_{AVG} increases as the maintenance interval increases.

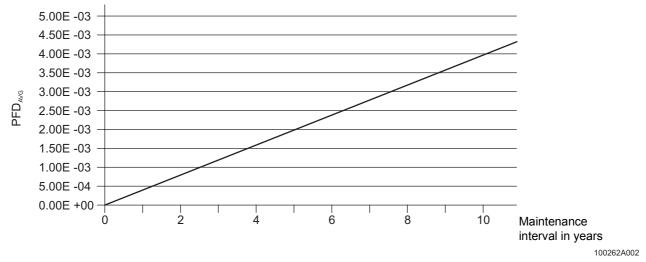


Figure 5 "Average probability of failure on demand for the safety-related system" (PFD_{AVG}) depending on the selected maintenance interval

10 Connections

10.1 2-Wire Connection Method

For short distances.



The cable resistances directly affect the measured result and falsify it, provided that they are not compensated by the software.

10.2 3-Wire Connection Method

For long distances between the resistance thermometer and the MCR-FL-HT-TS-I-EX and equal cable resistances ($R_{L1} = R_{L2} = R_{L3}$).



The cable resistance per wire must not exceed 11 $\Omega.$

10.3 4-Wire Connection Method

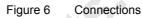
For long distances between the resistance thermometer and the MCR-FL-HT-TS-I-EX and differing cable resistances ($R_{L1} \neq R_{L2} \neq R_{L3} \neq R_{L4}$).



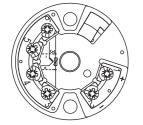
The cable resistance per wire must not exceed 11 Ω .

MCR-FL-HT-TS-LFL Ord. No.: 28 64 5 uni Ord. No.: 28 64 5 uni 2001 32825 Bierberg

Supply voltage via signal path



Sensor connection



 $2 - 1 - 12 \text{ V DC } \dots 30 \text{ V DC/4 mA} \dots 20 \text{ mA}$

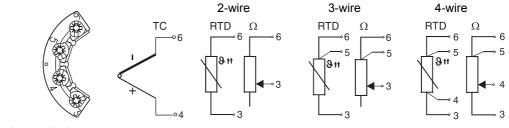


Figure 7 Connection methods

11 Installation in the Sensor Connection Head According to DIN 43729 Form B

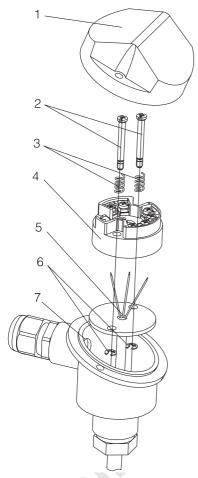


Figure 8 Installation in the sensor connection head

- 1 Cover
- 2 Mounting screws
- 3 Mounting springs
- 4 Temperature measuring transducer for connection head
- 5 Sensor insert with connection wires
- 6 Circlips
- 7 Cable feed-through
- Insert the connection wires of the sensor insert (5) in the central drill hole on the head measuring transducer.
- Place the mounting springs (3) on the mounting screws (2).

- Pass the mounting screws (2) through the drill holes in the head measuring transducer and the drill holes in the sensor insert (5). Secure both mounting screws with the circlips (6).
- Position the head measuring transducer in the connection head so that the connection terminal blocks for the current output (terminal blocks ① and ②) point towards the cable feed-through (7).
- Then secure the head measuring transducer to the sensor insert in the connection head.

12 Configuration

The devices are supplied with the following default configuration: Pt 100 sensor, measuring range 0°C ... +100°C, 3-wire connection.

The configuration data can be set via the HART[®] protocol. A programming adapter can be used for this in conjunction with the MCR-PI-CONF-WIN configuration software (Order No. 2814799) or a hand-held operator panel (e.g., DXR 275 from Emerson).

Customer-specific measuring range settings, linearization, and characteristic curve adjustments can also be implemented in this way. In addition, the online help explains the configuration options and their implementation.

Configurable Parameters:

- Sensor type and connection method
- Unit of measurement (°C/°F)
- Measuring ranges
- Internal/external reference junction
- Compensation of the cable resistance for 2-wire connection
- Faults
- Output signal (4 mA ... 20 mA/20 mA ... 4 mA)
- Attenuation
- Offset
- Measuring point designation + descriptor (8 + 16 characters)
- Output simulation
- Customer-specific linearization
- Detection of minimum/maximum process value

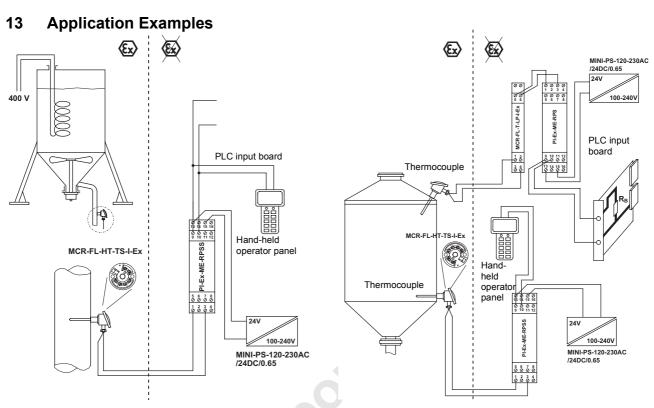
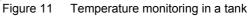


Figure 9 Temperature measurement in pipes



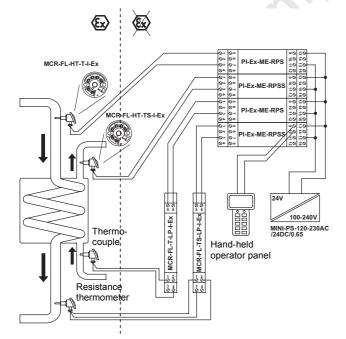
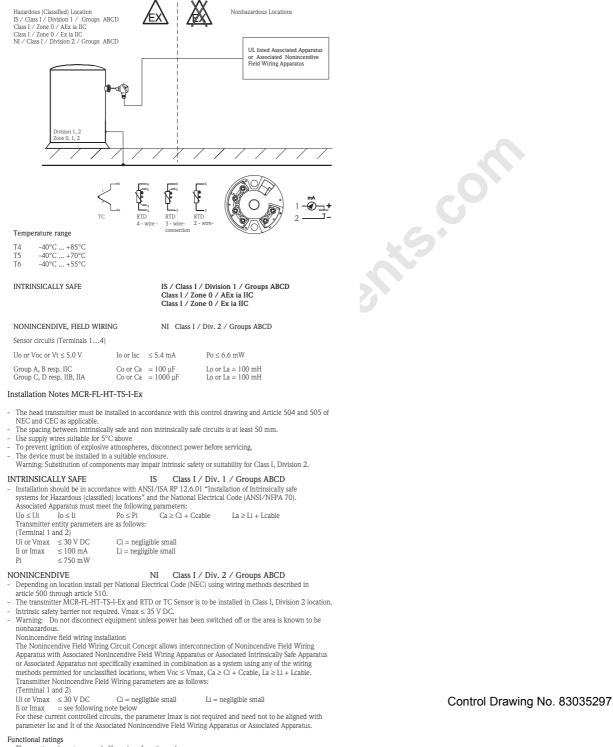


Figure 10 Temperature monitoring in a heat exchanger

14 Appendix



These ratings do not supersede Hazardous Location values Unom \leq 35 DC Inom \leq 4 to 20 mA

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