



ZXCT199

26V, ZERO-DRIFT, BIDIRECTIONAL, HIGH-PRECISION CURRENT MONITOR

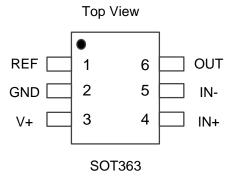
Description

The ZXCT199 series of current shunt monitors are designed to deal with very low sense voltages, enabling the use of very low value sense resistors to monitor large currents. The low offset voltage and zero-drift architecture enables current sensing with maximum drops across the shunt to as low as 10mV full-scale.

The ZXCT199 series has three fixed voltage gain options in 50V/V, 100V/V, and 200V/V. It can measure voltage across shunts at common-mode voltages from -0.1V to 26V, independent of supply voltage.

These parts operate from a 2.7V to 26V power supply with a maximum supply current of $100\mu A$. All versions have a temperature range of $-40^{\circ}C$ to $+125^{\circ}C$, and are offered in the SOT363 package.

Pin Assignments



Features

- Supply Voltage Range: 2.7V to 26V
- Wide Common-Mode Range: -0.1V to 26V
- Gain Error: (Maximum Overtemperature)
 - A and B Version: ±1.0%
 - C Version: ±0.8%
- Choice of Gains:
 - ZXCT 199X1: 50V/V
 - ZXCT 199X2: 100V/V
 - ZXCT 199X3: 200V/V
- Low Offset Voltage
 - A Version max ±150µV
 - B Version max ±100µV
 - C Version max ±80µV
- Zero-Drift Performance: 0.5µV/°C (max)
- Rail-to-Rail Output Capability
- Low Quiescent Current: 100μA (max)
- Package: 6-Pin SOT363
- Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)
- Halogen and Antimony Free. "Green" Device (Note 3)
- An automotive-compliant part is available under separate datasheet (<u>ZXCT199Q</u>)

Applications

The ZXCT199 is well suited for power supplies running at very large currents requiring the use of low-value sense resistors.

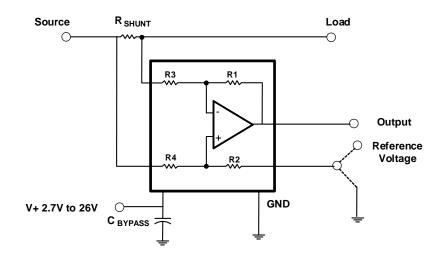
- High-side/low-side current sensing
- Large-scale computing
- Computer racks
- Server farms
- High-performance video cards
- Industrial devices
- Power-management devices
- Instrumentation applications
- Control systems
- · Metering devices

Notes:

- 1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3) compliant.
- 2. See https://www.diodes.com/quality/lead-free/ for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
- 3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.



Typical Applications Circuit



Practical Values of CBYPASS $0.01\mu F$ to $0.1\mu F$

Pin Descriptions

Pin Name	Pin Number	I/O	Description
REF	1	Analog input	Reference voltage, 0V to V+
GND	2	_	Ground
V+	3	Power	Power supply, 2.7V to 26V
IN+	4	Analog input	Connect to supply side of shunt resistor.
IN-	5	Analog input	Connect to load side of shunt resistor.
OUT	6	Analog output	Output voltage



Absolute Maximum Ratings (@ TA = +25°C, unless otherwise specified.) (Note 4)

	Description	Rating	Unit
Supply Volatge (V+)		+26	V
Analan Innerta INI. INI	Differential (IN+)-(IN-)	-26 to 26	V
Analog Inputs IN+, IN-	Common Mode	GND -0.3 to 26	V
REF Input Voltage	•	GND- 0.3 to (V+) + 0.3	V
Output		GND- 0.3 to (V+) + 0.3	V
Input Current into All Pins (Note 5)		5	mA
ESD Human Body ESD Protection (HBM)		5	kV
ESD Charged-Device Model ESD Protection (CDM)		1.5	kV
R _{θJA} (Junction-to-Ambient T	hermal Resistance)	228	°C/W
R _{BJC} (Junction-to-Case Thermal Resistance)		64	°C/W
Operating Temperature, TA		-40 to +125	°C
Storage Temperature		-65 to +150	°C

Notes:

Recommended Operating Conditions (Note 7)

Symbol	Parameter	Min	Тур	Max	Unit
Vсм	Common-Mode Input Voltage	-0.1	12	26	V
Vs	Operating Supply Voltage (Applied to V+)	2.7	5	26	V
T _A	Operating Ambient Temperature	-40		+125	°C

Note:

7. Refer to the Typical Applications Circuit.

 ^{4.} Stresses greater than those listed under *Absolute Maximum Ratings* can cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to *Absolute Maximum Ratings* for extended periods can affect device reliability.
 5. Input voltage at any pin can exceed the voltage shown if the current at that pin is limited to 5mA.
 6. R_{BJA} and R_{BJC} are measured at T_A = +25°C on a high effective thermal conductivity minimum recommend pad (MRP) FR-4 PC board.



$\textbf{Electrical Characteristics} \ \, (T_A = +25 ^{\circ}\text{C}, \ \, \text{V}_S = 5 \text{V}, \ \, \text{V}_{\text{IN+}} = 12 \text{V}, \ \, \text{V}_{\text{SENSE}} = \text{V}_{\text{IN+}} - \text{V}_{\text{IN-}}, \ \, \text{and} \ \, \text{V}_{\text{REF}} = \text{V}_{\text{S}} \, / \, 2, \ \, \text{unless otherwise noted.})$

VCM	Symbol	Par	ameter	Test Conditions	Min	Тур	Max	Unit	
CMRR Common-mode rejection T _A = -40°C to +125°C ZXCT199X2, N _N = 0V to 26V, VSENSE = 0mV 100 120 — dB ZXCT193X3, V _{NN} = 0V to 26V, VSENSE = 0mV 100 120 — dB V _{OS} Offset voltage, RTI (Note 8) ZXCT199X Version, VSENSE = 0mV — ±5 ±150 µV ZXCT199X Version, VSENSE = 0mV — ±5 ±150 µV dVos/dT Vos vs. temperature TA = -40°C to +125°C — ±5 ±150 µV dVos/dT Vos vs. temperature TA = -40°C to +125°C — 0.1 0.5 µV — Long-term stability (Note 9) — — — 270 µV PSRR Power supply rejection (Note 10) Vs = 2.7V to 18V — — 20.1 — µV lg Input bias current Vsexses = 0mV — ±0.1 — µV Ig Input offset current Vsexses = 0mV — ±0.0 — µA G Gain error ZXCT199X1 <td< td=""><td>V_{CM}</td><td colspan="2">Common-mode input</td><td>T_A = -40°C to +125°C</td><td>-0.1</td><td>_</td><td>26</td><td>V</td></td<>	V _{CM}	Common-mode input		T _A = -40°C to +125°C	-0.1	_	26	V	
Common-incode rejection T _A = -40°C to +125°C T _A = -40°C to				$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	90	120	_	dB	
Ta = -40°C to +125°C 105 120 65 120 65 120 65 120 65 120 125°C 125°C 125°C 125°C	CMRR	Common-mode	e rejection	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	100	120	_	dB	
Vos					105	120	_	dB	
ZXCT199C Version, VSENSE = 0mV				ZXCT199A Version, V _{SENSE} = 0mV	_	±5	±150	μV	
Mos/sdT	Vos	Offset voltage,	RTI (Note 8)	ZXCT199B Version, V _{SENSE} = 0mV	_	±5	±100	μV	
— Long-term stability (Note 9) — — — 270 μV PSRR Power supply rejection (Note 10) VS = 2.7V to 18V V				ZXCT199C Version, V _{SENSE} = 0mV	_	±5	±80	μV	
PSRR Power supply rejection (Note 10) Vs = 2.7V to 18V V _{NN = 18V, VSENSE} = 0mV	dVos/dT	Vos vs. temper	ature	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	_	0.1	0.5	μV/°C	
PSRR Power supply rejection (Note 10) VN+ = 18V, VSENSE = 0mV	_	Long-term stab	ility (Note 9)	_	_	_	270	μV	
Input offset current VSENSE = 0mV - ±0.02 - μA	PSRR	Power supply r	ejection (Note 10)	1 · ·	_	±0.1	_	μV/V	
G Gain ZXCT199X1 — — 50 — V/V ZXCT199X2 — — — 100 — V/V EG Gain error A and B Version, Vsense = -5mV to 5mV TA = -40°C to +125°C — ±0.03% ±1% — — C Version, Vsense = -5mV to 5mV TA = -40°C to +125°C — ±0.03% ±0.8% — — — Nonlinearity error Vsense = -5mV to 5mV — ±0.01% — — VOH Swing to V+ power-supply rail RL = 10kΩ to GND, TA = -40°C to +125°C — (V+) — (V+) — (V+) — (V+) — (V+) — (V-) — (V	lB	Input bias curre	ent	V _{SENSE} = 0mV	_	28	_	μΑ	
Gain ZXCT199X2	I _{OS}	Input offset cur	rent	V _{SENSE} = 0mV	_	±0.02	_	μΑ	
EG Gain error A and B Version, Vsense = -5mV to 5mV			ZXCT199X1	_	_	50	_		
$E_G = \begin{cases} Gain error \end{cases} & A and B Version, Vsense = -5mV to 5mV \\ TA = -40^{\circ}C to +125^{\circ}C \\ C Version, Vsense = -5mV to 5mV \\ TA = -40^{\circ}C to +125^{\circ}C \end{cases} & - \pm 0.03\% & \pm 0.8\% & - \\ - & Gain error vs. temperature \end{cases} & T_A = -40^{\circ}C to +125^{\circ}C \\ - & Nonlinearity error \end{cases} & T_A = -40^{\circ}C to +125^{\circ}C & - & 3 & 10 & ppm/^{\circ}C \\ - & Nonlinearity error & Vsense = -5mV to 5mV & - & \pm 0.01\% & - & - \\ VOH & Swing to V+ power-supply rail & R_L = 10k\Omega to GND, T_A = -40^{\circ}C to +125^{\circ}C & - & (V+) - & (V+) - & (V+) - & 0.05 & 0.2 & V \\ VOL & Swing to GND & R_L = 10k\Omega to GND, T_A = -40^{\circ}C to +125^{\circ}C & - & (Vond) + & (Vond) +$	G	Gain	ZXCT199X2	_	_	100	_	V/V	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$			ZXCT199X3	_	_	200	_		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	_	Cain arrar	1	•	_	±0.03%	±1%	_	
— Nonlinearity error VSENSE = -5mV to 5mV — ±0.01% — — VOH Swing to V+ power-supply rail RL = 10kΩ to GND, TA = -40°C to +125°C — (V+) — 0.05 0.2 V VOL Swing to GND RL = 10kΩ to GND, TA = -40°C to +125°C — (VGND) + 0.05 V — Maximum capacitive load No sustained oscillation — 1 — nF GBW Band width CLOAD = 10pF, ZXCT199X1 — 70 — kHz CLOAD = 10pF, ZXCT199X2 — 30 — kHz CLOAD = 10pF, ZXCT199X3 — 14 — — Voltage noise density — 0.5 — V/µs V Operating voltage range TA = -40°C to +125°C 2.7 — 26 V IQ Quiescent current VSENSE = 0mV — 65 100 µA — Specified range — 40°C to +125°C — - 115 µA	EG	Gam enor			_	±0.03%	±0.8%	_	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	_	Gain error vs. t	emperature	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	_	3	10	ppm/°C	
Voh Swing to V+ power-supply fall RL = 10kΩ to GND, TA = -40°C to +125°C — 0.05 0.2 V Vol Swing to GND RL = 10kΩ to GND, TA = -40°C to +125°C — (VGND) + 0.05 V — Maximum capacitive load No sustained oscillation — 1 — nF GBW Band width CLOAD = 10pF, ZXCT199X1 — 70 — kHz CLOAD = 10pF, ZXCT199X2 — 30 — kHz CLOAD = 10pF, ZXCT199X3 — 14 — V/μs — Voltage noise density — 0.5 — V/μs Vs Operating voltage range TA = -40°C to +125°C 2.7 — 26 Volusecent current Vsense = 0mV — 65 100 μA TA = -40°C to +125°C — - 115 μA — Specified range — 40°C to +125°C — - 115 μA	_	Nonlinearity err	or	V _{SENSE} = -5mV to 5mV	_	±0.01%	_	_	
No sustained oscillation No Sustained oscil	Vон	Swing to V+ po	wer-supply rail	$R_L = 10k\Omega$ to GND, $T_A = -40$ °C to +125°C	_	0.05	0.2	V	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Vol	Swing to GND		$R_L = 10k\Omega$ to GND, $T_A = -40$ °C to +125°C	_			V	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		Maximum capa	citive load	No sustained oscillation	_	1	_	nF	
				C _{LOAD} = 10pF, ZXCT199X1	_	70	_		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	GBW	Band width		CLOAD = 10pF, ZXCT199X2	_	30	_	kHz	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				CLOAD = 10pF, ZXCT199X3	_	14	_		
$ \begin{array}{c} V_S & \text{Operating voltage range} & \begin{array}{c} T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C} & 2.7 & - & 26 \\ \hline -20^{\circ}\text{C to } +85^{\circ}\text{C} & 2.5 & - & 26 \\ \end{array} \\ \begin{array}{c} I_Q & \text{Quiescent current} & \begin{array}{c} V_{SENSE} = 0\text{mV} & - & 65 & 100 & \mu\text{A} \\ \hline T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C} & - & - & 115 & \mu\text{A} \\ \hline - & Specified range & - & -40 & - & +125 & ^{\circ}\text{C} \\ \end{array} $	SR	Slew rate		_	_	0.5		V/µs	
V_S Operating voltage range -20°C to +85°C 2.5 $-$ 26 V_S	_	Voltage noise density		_	_	25	_	nV/√Hz	
	M	On a ratio as scale		T _A = -40°C to +125°C	2.7	_	26		
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	VS	Operating voita	ige range	-20°C to +85°C	2.5	_	26	V	
$T_A = -40$ °C to +125°C — — 115 μA — Specified range — -40 — +125 °C	1	Outon a set se	ant.	V _{SENSE} = 0mV	_	65	100	μA	
	IQ	Quiescent curre	₽⊓L	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	_	_	115	μA	
— Operating range — -40 — +125 °C	_	Specified range	9	_	-40	_	+125	°C	
	_	Operating rang	е	_	-40	_	+125	°C	

Notes:

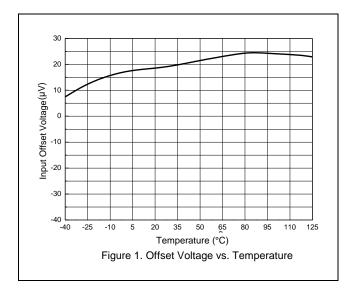
^{8.} RTI = Referred to input
9. Only for ZXCT199X1, the long-term stability is defined as maximum V_{OS} shift with time, which has been calculated during life test 1000 hours with T_A = +125°C. This V_{OS} drift with time is not a linear function of time, and the shift is great initially and slow down (become linear) over time. This parameter is

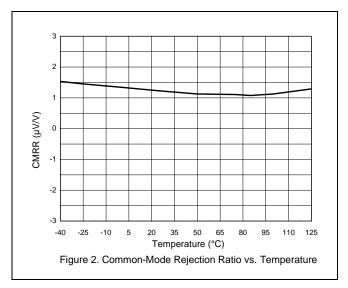
guaranteed by design.

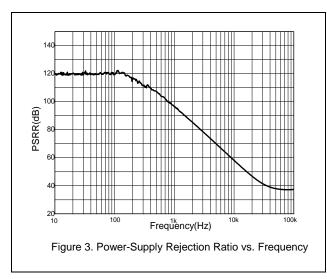
10. This parameter value is guaranteed by characterization, but not production tested.

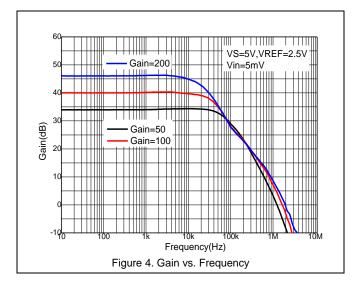


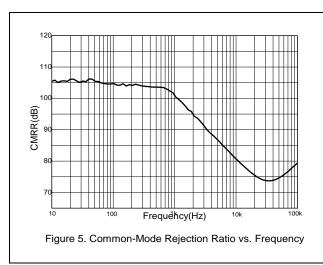
Typical Performance Characteristics

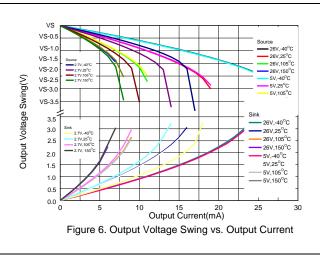






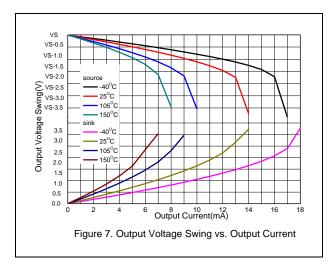


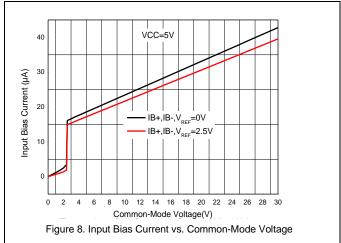


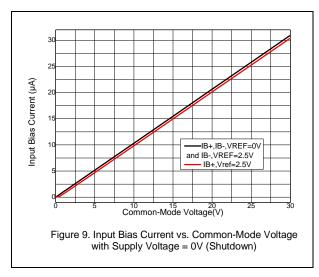


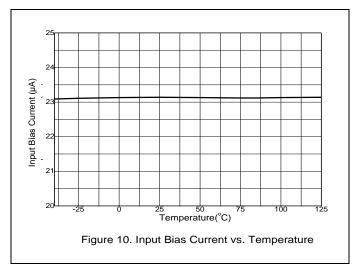


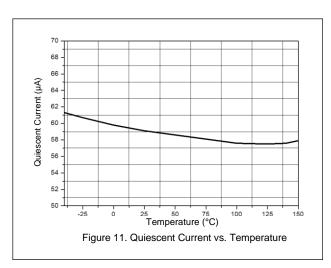
Typical Performance Characteristics (continued)

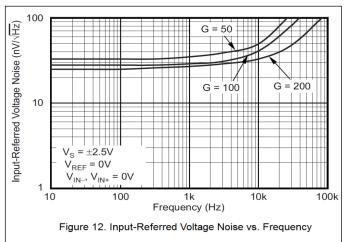














Typical Performance Characteristics (continued)

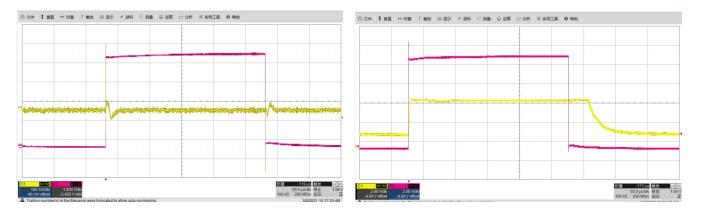


Figure 13. Common-Mode Voltage vs. Transient Response

Figure 14. Noninverting Differential Input Overload

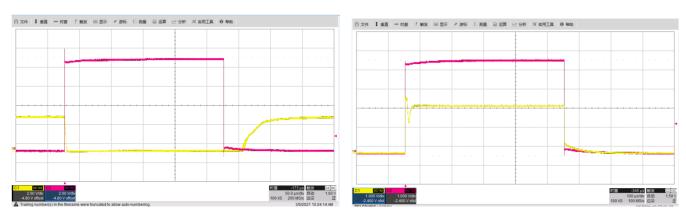


Figure 15. Inverting Differential. Input Overload

Figure 16. Startup Response

Figure 17. Brownout Recovery

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Figure 18. Output Stability with Load 2.2nF



Application Information

General Information

The ZXCT199 has a wide common mode of -0.1V to 26V and it can be used in low-side and high-side current sensing. The device is a specially designed, current-sensing amplifier able to accurately measure voltages developed across a current-sensing resistor on common-mode voltages that far exceed the supply voltage powering the device. The zero-drift topology enables high-precision measurements with maximum input offset voltages as low as 80μ V, with a maximum temperature contribution of 0.5μ V/°C over the full temperature range of -40°C to +125°C.

Input and Output Pin Voltage Ranges

The ZXCT199 can withstand the full input signal range of up to 26V at the input pins, regardless of whether the device has power applied or has the V+ pin at zero volt. The input circuitry of the ZXCT199 can accurately measure beyond its power-supply voltage. For example, the V+ power supply can be 5V, whereas the voltage applied to the analog input pins In+ or In- can be as high as 26V. However, the output voltage range of the OUT pin is limited by the voltage on the power supply and a consideration of the maximum VoH. An alternative to having a low supply voltage just to protect a converter would be to use a voltage divider at the output of the ZXCT199.

Power Supply Recommendations

The ZXCT199 can operate on as low as 2.7V. In some applications the power supply may be selected to limit the output range that is compatible with parts using this signal such as an analog converter or an analog input pin on a microcontroller. In Figure 19, the power supply has been set at 5V. This will limit the output voltage of the current monitor giving protection to the converter. The ground connections for the ADC and current monitor should be wired as a star configuration to minimize error. A power-supply bypass capacitor connected closely to the device pins is required for stability with a suggested value of $0.01\mu\text{F}$ to $0.1\mu\text{F}$. Applications with noisy or high-impedance power supplies may require additional decoupling capacitors to reject power-supply noise.

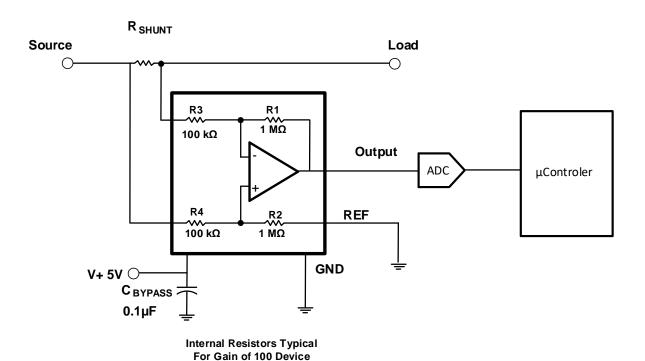


Figure 19. Typical Application



Single Direction Operation

The device is configured to monitor current flowing in one direction (single direction) or in both directions (bidirectional) depending on how the REF pin is configured. With the REF connected to the ground as depicted in Figure 20, the device will measure only signals that impose a positive voltage across the shunt.

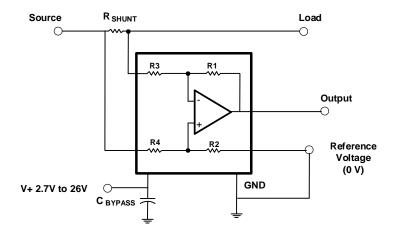


Figure 20. Single Direction Application Schematic Using Ground as a Reference

An example output response of a single directional configuration is shown in Figure 21. With the REF pin connected directly to ground, the output voltage is biased to this zero output level. The output rises above the reference voltage for positive differential input signals but cannot fall below the reference voltage for negative differential input signals because of the grounded reference voltage.

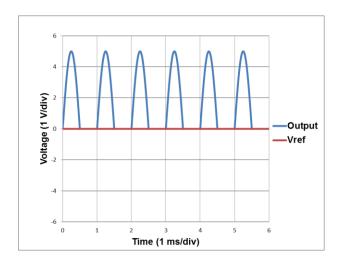


Figure 21. Single Direction Application Output Response



Bidirectional Operation

The device is a bidirectional, current-sense amplifier capable of measuring currents through a resistive shunt in two directions. This bidirectional monitoring is common in applications that include charging and discharging operations where the current flow through the shunt resistor can change directions.

The ability to measure this current flowing in both directions is enabled by applying a voltage to the REF pin, see Figure 22. The voltage applied to REF (VREF) sets the output state that corresponds to the zero-input level state. The output then responds by increasing above VREF for positive differential signals (relative to the IN- pin) and responds by decreasing below VREF for negative differential signals. This reference voltage applied to the REF pin can be set anywhere between 0V to V+. For bidirectional applications, VREF is typically set at mid-scale for equal signal range in both current directions. In some cases however, VREF is set at a voltage other than mid-scale when the bidirectional current and corresponding output signal do not need to be symmetrical. In Figure 22, the REF pin has been set to 2.5V. Therefore, when the output of the ZXCT199 is between zero and 2.5V, it represents a negative current through RSHUNT. It is desirable to have an accurate low impedance voltage supply for the REF pin. A voltage reference or a resistor divider buffered with an op-amp are recommended. Any error that is introduced at the REF pin is added to the output voltage. This error can be mitigated with differential inputs to an A-to-D converter discussed in the next section.

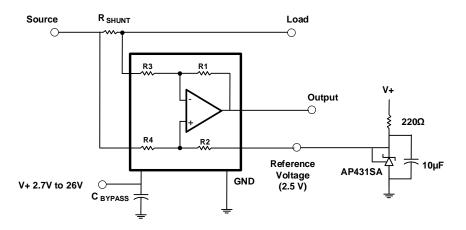


Figure 22. Bidirectional Application Schematic Using 2.5V Reference

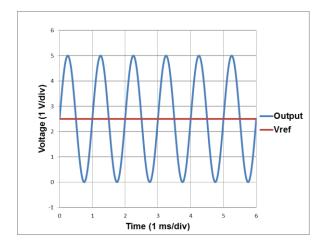


Figure 23. Bidirectional Application Output Response



REF Input Impedance Effects and Improving Accuracy

As with any difference amplifier, the ZXCT199 series common-mode rejection ratio is affected by any impedance present at the REF input. This concern is not a problem when the REF pin is connected directly to most references or power supplies. When using resistive dividers from the power supply or a reference voltage, the REF pin must be buffered by an operational amplifier.

In systems where the ZXCT199 output can be sensed differentially, such as by a differential input analog-to-digital converter (ADC) or by using two separate ADC inputs, the effects of external impedance on the REF input can be cancelled. Figure 24 depicts a method of taking the output from the ZXCT199 by using the REF pin as the differential reference.

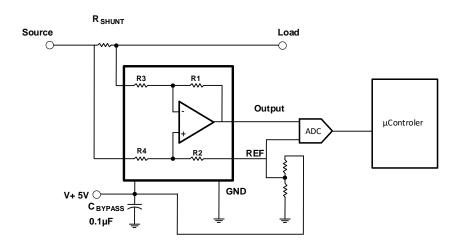


Figure 24. Differential Sensing of the ZXCT199 to Cancel Effects of Impedance on the REF Input

The linear range of the output stage is limited in how close the output voltage can approach ground under zero input conditions. In single directional applications where measuring very low input currents at high accuracy (greater than 12 bits), set the REF pin to a convenient value above 150μ V to get the output into the linear range of the device. This is needed to overcome the potential offset that may exist between the In+ and In- pins. If this type of offset were added to the application in Figure 19 the A-to-D converter and microprocessor could measure and store a zero current reading to be subtracted from subsequent readings making significant improvements to the accuracy of the low current readings.

In most cases, low current accuracy is not needed and the applications depicted in Figures 20 and 22 are adequate.



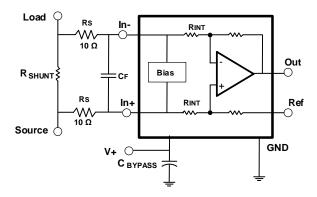


Figure 25. Filter at Input Pins

Input Filtering

Input filtering may be needed to limit the bandwidth of signals or to add protection against transients that may be generated as the result of shunt inductance. If the added source resistors are not closely matched there is an adverse impact on gain error, CMRR and Vos. Figure 25 shows a filter placed at the inputs pins. It is recommended the added input resistors (Rs) should be 10Ω or less.

As a consideration to mitigate the impact of shunt inductance in high-current and high-transient environments, the RC time constant of the added Rs and CF should be greater than the implied time constant by the Rshunt inductance and resistance.

$$2 \cdot R_S \cdot C_F \geq \frac{L_{SHUNT}}{R_{SHUNT}}$$

Due to additional current used in the bias circuit the voltage between the In- and In+ pins will differ from voltage across the sense resistor. This will appear as a gain error at the output. These internal bias currents from the inputs are not equal in magnitude and change depending on common mode conditions. This is the motivation of keeping the added resistor below 10Ω . The chart below has the equations for calculating the gain errors based on adding well matched source resistors. The equations include a provision for the additional 20μ A current used by the bias circuit block that is depicted as bias in Figure 25.

Product	Gain R _{INT}	D	Gain Error	Gain Error % *		
Product	Gaili	R _{INT}	Factor Equations	$R_S = 10\Omega$	R _S = 20Ω	$R_S = 30.1\Omega$
ZXCT199x1	50	20000	$\frac{20,000}{(17 \cdot R_S) + 20,000}$	0.8428%	1.6716%	2.4947%
ZXCT199x2	100	10000	$\frac{10,000}{(9 \cdot R_S) + 10,000}$	0.8920%	1.7682%	2.6375%
ZXCT199X3	200	5000	$\frac{1,000}{R_{\rm S} + 1000}$	0.9901%	1.9608%	2.9126%

^{*}The percentages shown should be rounded to 2 significant figures. The excess can be used to check calculations. This is for a typical semiconductor process.

 $Gain\ Error\ (\%) =\ 100 - (100\ \cdot Gain\ Error\ Factor)$

Where,

R_{INT} is the internal resistors R3 and R4 used to set the gain and differs per device type.

Rs is the added input resistors



Using the ZXCT199 with Common-Mode Transients above 30V

With a small amount of additional circuitry, the ZXCT199 series can be used in circuits subject to transients higher than 30V, such as automotive applications. Use only Zener diode or Zener-type transient absorbers; any other type of transient absorber has an unacceptable time delay. Start by adding a pair of resistors (see Figure 26) as a working impedance for the Zener. Keeping these resistors as small as possible is preferable, most often approximately 10Ω . Larger values can be used with an effect on gain as discussed in the *Input Filtering* section. Because this circuit limits only short-term transients, many applications are satisfied with a 10Ω resistor along with conventional Zener diodes of the lowest power rating that can be found

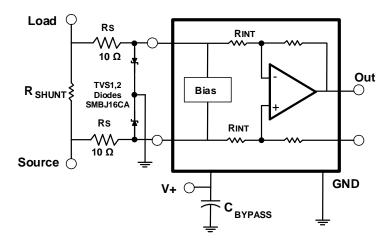


Figure 26. ZXCT199 Transient Protection Using Dual TVS Diodes

The most package-efficient solution involves using a single absorber and back-to-back diodes between the device inputs. The most space-efficient solutions are dual series-connected diodes in a single SOT523 or SOD523 package. This method is shown in Figure 27. In either of these examples, the total board area required by the ZXCT199 with all protective components is less than that of an SO-8 package, and only slightly greater than that of an MSOP-8 package.

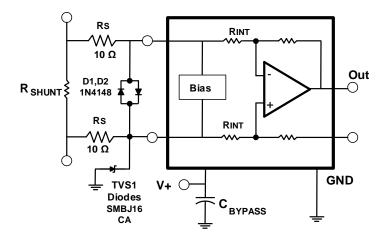


Figure 27. ZXCT199 Transient Protection Using a Single TVS and Input Clamps



Shutting Down the ZXCT199 Series

Although the ZXCT199 series does not have a shutdown pin, the low-power consumption of the device allows the output of a logic gate or transistor switch to power the ZXCT199. This gate or switch turns on and turns off the ZXCT199 power-supply quiescent current.

However, in current shunt monitoring applications, there is also a concern for how much current is drained from the shunt circuit in shutdown conditions. Evaluating this current drain involves considering the simplified schematic of the ZXCT199 in shutdown mode shown in Figure 28.

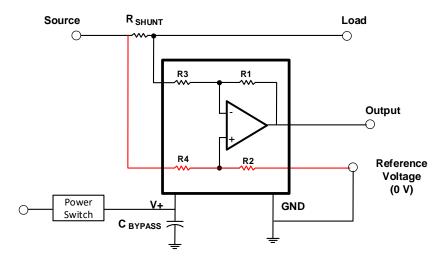
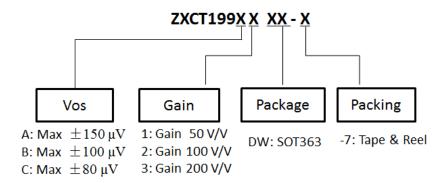


Figure 28. Basic Circuit for Shutting Down the ZXCT199 with a Grounded Reference

There is typically slightly more than $1M\Omega$ impedance (from the combination of $1M\Omega$ feedback and $5k\Omega$ input resistors) from each input of the ZXCT199 to the OUT pin and to the REF pin. The amount of current flowing through these pins depends on the Source Voltage and the REF Pin connection. For example, if the REF pin is grounded, the calculation of the effect of the $1M\Omega$ impedance from the shunt to ground is straightforward. If the ZXCT1999 is powered down the R3 and R1 path will not carry current unless there is a load on the output pin. The key point is that the R4 and R2 path depicted in red is a current path may need some consideration in the very power sensitive applications. A provision to disconnect the REF pin may be needed.



Ordering Information



Part Number	Don't Neverland Coeffice	Dankana Oak	Dankana	Packing		
Part Number	Part Number Suffix	Package Code	Package	Qty.	Carrier	
ZXCT199A1DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199A2DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199A3DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199B1DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199B2DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199B3DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199C1DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199C2DW-7	-7	DW	SOT363	3000	Tape & Reel	
ZXCT199C3DW-7	-7	DW	SOT363	3000	Tape & Reel	

Marking Information

SOT363

(Top View)



XX: Identification Code

 \underline{Y} : Year 0 to 9 (ex: 3 = 2023) W : Week : A to Z : week 1 to 26; a to z : week 27 to 52; z represents

week 52 and 53

X: Internal Code

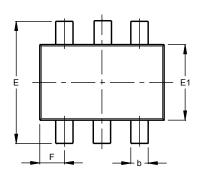
Part Number	Package	Identification Code
ZXCT199A1DW-7	SOT363	ZA
ZXCT199A2DW-7	SOT363	ZB
ZXCT199A3DW-7	SOT363	ZC
ZXCT199B1DW-7	SOT363	ZK
ZXCT199B2DW-7	SOT363	ZM
ZXCT199B3DW-7	SOT363	ZN
ZXCT199C1DW-7	SOT363	ZR
ZXCT199C2DW-7	SOT363	ZS
ZXCT199C3DW-7	SOT363	ZT

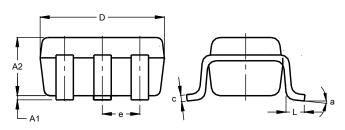


Package Outline Dimensions

Please see http://www.diodes.com/package-outlines.html for the latest version.

SOT363



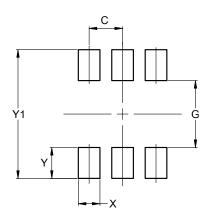


SOT363					
Dim	Min	Max	Тур		
A1	0.00	0.10	0.05		
A2	0.90	1.00	0.95		
b	0.10	0.30	0.25		
C	0.10	0.22	0.11		
D	1.80	2.20	2.15		
Е	2.00	2.20	2.10		
E1	1.15	1.35	1.30		
е	C	.650 E	SC		
F	0.40	0.45	0.425		
L	0.25	0.40	0.30		
а	0°	8°			
All Dimensions in mm					

Suggested Pad Layout

Please see http://www.diodes.com/package-outlines.html for the latest version.

SOT363



Dimensions	Value (in mm)
С	0.650
G	1.300
Х	0.420
Υ	0.600
Y1	2.500

Mechanical Data

- Moisture Sensitivity: Level 1 per J-STD-020
- Terminals: Finish Matte Tin Plated Leads, Solderable per MIL-STD-202, Method 208 (3)
- Weight: 0.006 grams (Approximate)
- Max Soldering Temperature +260°C for 30 secs as per JEDEC J-STD-020

December 2023



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