# **SiT2001B**

Single-Chip, SOT23 Oscillator



#### **Features**

- Any frequency between 1 MHz and 110 MHz accurate to 6 decimal places
- Operating temperature from -40°C to 85°C.
   Refer to SiT2018 for -40°C to 85°C option and SiT2020 for -55°C to 125°C option
- Excellent total frequency stability as low as ±20 ppm
- Low power consumption of 3.5 mA typical
- Fast start-up time of 5 ms
- LVCMOS/HCMOS compatible output
- 5-pin SOT23-5: 2.9 mm x 2.8 mm
- Pb-free, RoHS and REACH compliant
- For AEC-Q100 SOT23 Oscillators, refer to SiT2024 and SiT2025

# **Applications**

- Industrial, medical, automotive, avionics and other high temperature applications
- Industrial sensors, PLC, motor servo, outdoor networking equipment, medical video cam, asset tracking systems, etc.

Related products for automotive applications.

For aerospace and defense applications SiTime recommends using only Endura™ SiT2044.



# **Electrical Specifications**

All Min and Max limits are specified over temperature and rated operating voltage with 15 pF output load unless otherwise stated. Typical values are at 25°C and nominal supply voltage.

**Table 1. Electrical Characteristics** 

Parameters	Symbol	Min.	Тур.	Max.	Unit	Condition
				Frequency F	Range	
Output Frequency Range	f	1	_	110	MHz	
			Freque	ency Stabilit	y and Agin	ig
Frequency Stability	F_stab	-20	_	+20	ppm	Inclusive of Initial tolerance at 25°C, 1st year aging at 25°C,
		-25	_	+25	ppm	and variations over operating temperature, rated power supply voltage and load (15 pF ±10%).
		-50	_	+50	ppm	Voltage and load (10 pr ±10%).
			Opera	ting Temper	rature Rang	ge
Operating Temperature	T_use	-20	_	+70	°C	Extended Commercial
Range (ambient)		-40	_	+85	°C	Industrial
		5	Supply Volta	ige and Cur	rent Consu	ımption
Supply Voltage	Vdd	1.62	1.8	1.98	V	
		2.25	2.5	2.75	V	
		2.52	2.8	3.08	V	
		2.7	3.0	3.3	V	
		2.97	3.3	3.63	V	
		2.25	-	3.63	V	
Current Consumption	ldd	-	3.8	4.5	mA	No load condition, f = 20 MHz, Vdd = 2.8 V, 3.0 V or 3.3 V
		-	3.7	4.2	mA	No load condition, f = 20 MHz, Vdd = 2.5 V
		-	3.5	4.1	mA	No load condition, f = 20 MHz, Vdd = 1.8 V
OE Disable Current	l_od	-	-	4.3	mA	Vdd = 2.5 V to 3.3 V, OE = Low, Output in high Z state.
		-	-	4.1	mA	Vdd = 1.8 V, OE = Low, Output in high Z state.
Standby Current	I_std	-	2.6	4.3	μА	$Vdd = 2.8 V to 3.3V, \overline{ST} = Low, Output is weakly pulled down$
		-	1.4	2.5	μА	Vdd = 2.5 V, $\overline{ST}$ = Low, Output is weakly pulled down
		-	0.6	1.3	μА	Vdd = 1.8 V, $\overline{ST}$ = Low, Output is weakly pulled down



## **Table 1. Electrical Characteristics (continued)**

Parameters	Symbol	Min.	Тур.	Max.	Unit	Condition		
			LVCMO	S Output Ch	aracteristic	es		
Duty Cycle	DC	45	-	55	%	All Vdds		
Rise/Fall Time	Tr, Tf	-	1.0	2.0	ns	Vdd = 2.5 V, 2.8 V, 3.0 V or 3.3 V, 20% - 80%		
		-	1.3	2.5	ns	Vdd = 1.8 V, 20% - 80%		
		-	-	2.0	ns	Vdd = 2.25 V - 3.63 V, 20% - 80%		
Output High Voltage	VOH	90%	_	-	Vdd	IOH = -4 mA (Vdd = 3.0 V or 3.3 V) IOH = -3 mA (Vdd = 2.8 V or 2.5 V) IOH = -2 mA (Vdd = 1.8 V)		
Output Low Voltage	VOL	-	-	10%	Vdd	IOL = 4 mA (Vdd = 3.0 V or 3.3 V) IOL = 3 mA (Vdd = 2.8 V or 2.5 V) IOL = 2 mA (Vdd = 1.8 V)		
			Inj	out Charact	eristics			
Input High Voltage	VIH	70%	-	-	Vdd	Pin 3, OE or ST		
Input Low Voltage	VIL	-	-	30%	Vdd	Pin 3, OE or ST		
Input Pull-up impedance	Z_in	50	87	150	kΩ	Pin 3, OE logic high or logic low, or ST logic high		
		2	-	-	ΜΩ	Pin 3, ST logic low		
			Startu	p and Resu	me Timing			
Startup Time	T_start	ı	-	5	ms	Measured from the time Vdd reaches its rated minimum value		
Enable/Disable Time	T_oe	1	-	130	ns	f = 110 MHz. For other frequencies, T_oe = 100 ns + 3 * clock periods		
Resume Time	T_resume	-	-	5	ms	Measured from the time ST pin crosses 50% threshold		
				Jitter				
RMS Period Jitter	T_jitt	-	1.8	3	ps	f = 75 MHz, Vdd = 2.5 V, 2.8 V, 3.0 V or 3.3 V		
		_	1.8	3	ps	f = 75 MHz, Vdd = 1.8 V		
Peak-to-peak Period Jitter	T_pk	_	12	20	ps	f = 75 MHz, Vdd = 2.5 V, 2.8 V, 3.0 V or 3.3 V		
		_	14	25	ps	f = 75 MHz, Vdd = 1.8 V		
RMS Phase Jitter (random)	T_phj	-	0.5	0.9	ps	f = 75 MHz, Integration bandwidth = 900 kHz to 7.5 MHz		
		-	1.3	2	ps	f = 75 MHz, Integration bandwidth = 12 kHz to 20 MHz		

# **Table 2. Pin Description**

Pin	Symbol		Functionality			
1	GND	Power	Electrical ground			
2	NC	No Connect	No connect			
		Output Enable	H <sup>[1]</sup> : specified frequency output			
	Output Enable		L: output is high impedance. Only output driver is disabled.			
			H or Open <sup>[1]</sup> : specified frequency output			
3	OE/ST/NC	Standby	L: output is low (weak pull down). Device goes to sleep mode.			
			Supply current reduces to I_std.			
		No Connect	Any voltage between 0 and Vdd or Open <sup>[1]</sup> :			
		No Connect	Specified frequency output. Pin 3 has no function.			
4	VDD	Power	Power supply voltage <sup>[2]</sup>			
5	OUT	Output	Oscillator output			

# **Top View**

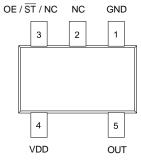


Figure 1. Pin Assignments

#### Notes:

- 1. In OE or  $\overline{\text{ST}}$  mode, a pull-up resistor of 10 k $\Omega$  or less is recommended if pin 3 is not externally driven. If pin 3 needs to be left floating, use the NC option.
- 2. A capacitor of value 0.1  $\mu\text{F}$  or higher between Vdd and GND is required.



#### **Table 3. Absolute Maximum Limits**

Attempted operation outside the absolute maximum ratings may cause permanent damage to the part. Actual performance of the IC is only guaranteed within the operational specifications, not at absolute maximum ratings.

Parameter	Min.	Max.	Unit
StorageTemperature	-65	150	°C
Vdd	-0.5	4	V
Electrostatic Discharge	-	2000	V
Soldering Temperature (follow standard Pb free soldering guidelines)	-	260	°C
Junction Temperature <sup>[3]</sup>	_	150	°C

#### Note:

3. Exceeding this temperature for extended period of time may damage the device.

#### Table 4. Thermal Consideration<sup>[4]</sup>

Package	θJA, 4 Layer Board (°C/W)	θJC, Bottom (°C/W)
SOT23-5	421	175

#### Note:

4. Refer to JESD51 for  $\theta_{JA}$  and  $\theta_{JC}$  definitions, and reference layout used to determine the  $\theta_{JA}$  and  $\theta_{JC}$  values in the above table.

## Table 5. Maximum Operating Junction Temperature<sup>[5]</sup>

Max Operating Temperature (ambient)	Maximum Operating JunctionTemperature
70°C	80°C
85°C	95°C

#### Note:

5. Datasheet specifications are not guaranteed if junction temperature exceeds the maximum operating junction temperature.

#### **Table 6. Environmental Compliance**

-				
Parameter	Condition/Test Method			
Mechanical Shock	MIL-STD-883F, Method2002			
Mechanical Vibration	MIL-STD-883F, Method2007			
Temperature Cycle	JESD22, Method A104			
Solderability	MIL-STD-883F, Method2003			
Moisture Sensitivity Level	MSL1 @ 260°C			



## **Test Circuit and Waveform**

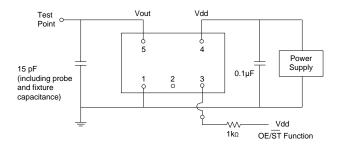


Figure 2. Test Circuit<sup>[6]</sup>

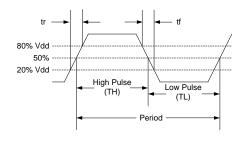


Figure 3. Output Waveform<sup>[6]</sup>

#### Note:

Duty Cycle is computed as Duty Cycle = TH/Period.

# **Timing Diagrams**

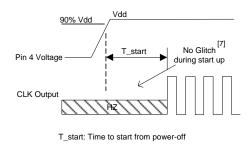
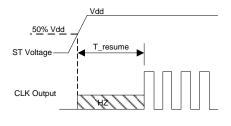


Figure 4. Startup Timing (OE/ST Mode)



T\_resume: Time to resume from ST

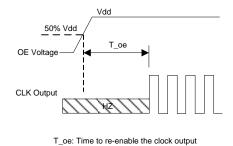
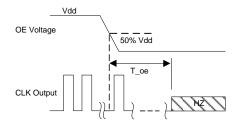


Figure 5. OE Enable Timing (OE Mode Only)

Figure 6. Standby Resume Timing (ST Mode Only)



T\_oe: Time to put the output in High Z mode

Figure 7. OE Disable Timing (OE Mode Only)

#### Note:

SiT2001 has "no runt" pulses and "no glitch" output during startup or resume.



# Performance Plots[8]

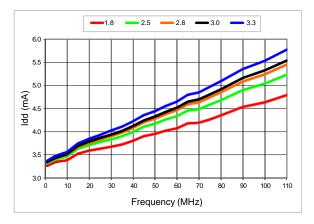


Figure 8. Idd vs Frequency

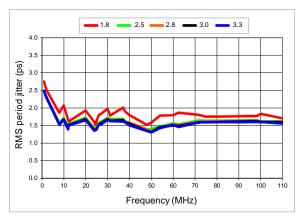


Figure 10. RMS Period Jitter vs Frequency

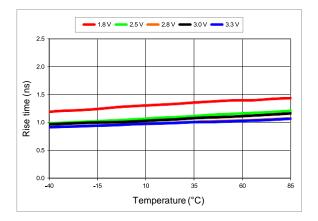


Figure 12. 20%-80% Rise Timevs Temperature

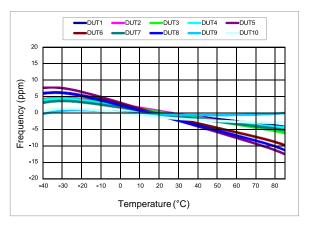


Figure 9. Frequency vs Temperature

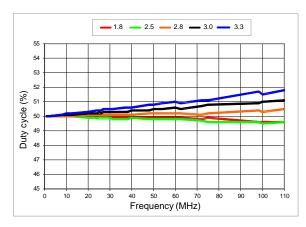


Figure 11. Duty Cycle vs Frequency

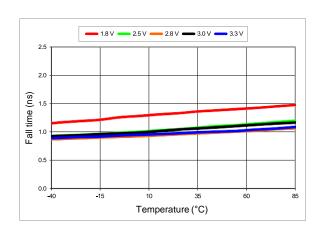
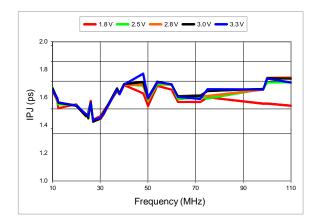


Figure 13. 20%-80% Fall Time vs Temperature



# Performance Plots[8]



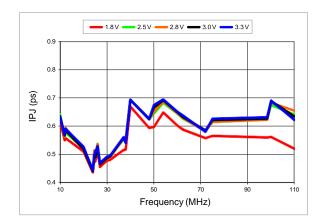


Figure 14. RMS Integrated Phase Jitter Random (12 kHz to 20 MHz) vs Frequency<sup>[9]</sup>

Figure 15. RMS Integrated Phase Jitter Random (900 kHz to 20 MHz) vs Frequency<sup>[9]</sup>

#### Notes:

- 8. All plots are measured with 15 pF load at room temperature, unless otherwise stated.
- 9. Phase noise plots are measured with Agilent E5052B signal source analyzer. Integration range is up to 5 MHz for carrier frequencies below 40 MHz.



# **Programmable Drive Strength**

The SiT2001 includes a programmable drive strength feature to provide a simple, flexible tool to optimize the clock rise/fall time for specific applications. Benefits from the programmable drive strength feature are:

- Improves system radiated electromagnetic interference (EMI) by slowing down the clock rise/fall time.
- Improves the downstream clock receiver's (RX) jitter by decreasing (speeding up) the clock rise/fall time.
- Ability to drive large capacitive loads while maintaining full swing with sharp edge rates.

For more detailed information about rise/fall time control and drive strength selection, see the SiTime Application Notes section.

#### **EMI Reduction by Slowing Rise/Fall Time**

Figure 16 shows the harmonic power reduction as the rise/fall times are increased (slowed down). The rise/fall times are expressed as a ratio of the clock period. For the ratio of 0.05, the signal is very close to a square wave. For the ratio of 0.45, the rise/fall times are very close to near-triangular waveform. These results, for example, show that the 11<sup>th</sup> clock harmonic can be reduced by 35 dB if the rise/fall edge is increased from 5% of the period to 45% of the period.

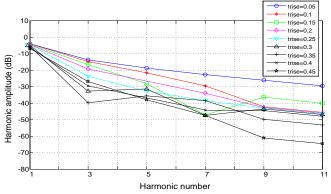


Figure 16. Harmonic EMI reduction as a Function of Slower Rise/Fall Time

#### Jitter Reduction with Faster Rise/Fall Time

Power supply noise can be a source of jitter for the downstream chipset. One way to reduce this jitter is to speed up the rise/fall time of the input clock. Some chipsets may also require faster rise/fall time in order to reduce their sensitivity to this type of jitter. Refer to the Rise/Fall Time Tables (Table 7 to Table 11) to determine the proper drive strength.

#### **High Output Load Capability**

The rise/fall time of the input clock varies as a function of the actual capacitive load the clock drives. At any given drive strength, the rise/fall time becomes slower as the output load increases. As an example, for a 3.3 V SiT2001 device with default drive strength setting, the typical rise/fall time is 1 ns for 15 pF output load. The typical rise/fall time slows down to 2.6 ns when the output load increases to 45 pF. One can choose to speed up the rise/fall time to 1.83 ns by then increasing the drive strength setting on the SiT2001.

The SiT2001 can support up to 60 pF in maximum capacitive loads with drive strength settings. Refer to the Rise/Tall Time Tables (Table 7 to 11) to determine the proper drive strength for the desired combination of output load vs. rise/fall time.

## SiT2001 Drive Strength Selection

Tables 7 through 11 define the rise/fall time for a given capacitive load and supply voltage.

- Select the table that matches the SiT2001 nominal supply voltage (1.8 V, 2.5 V, 2.8 V, 3.0 V, 3.3 V).
- Select the capacitive load column that matches the application requirement (5 pF to 60 pF)
- Under the capacitive load column, select the desired rise/fall times.
- The left-most column represents the part number code for the corresponding drive strength.
- Add the drive strength code to the part number for ordering purposes.

## **Calculating Maximum Frequency**

Based on the rise and fall time data given in Tables 7 through 11, the maximum frequency the oscillator can operate with guaranteed full swing of the output voltage over temperature can be calculated as the following:

Max Frequency = 
$$\frac{1}{5 \times \text{Trf}_20/80}$$

where  $Trf_{20/80}$  is the typical value for 20%-80% rise/fall time.

#### Example 1

Calculate f<sub>MAX</sub> for the following condition:

- Vdd = 1.8 V (Table 7)
- Capacitive Load: 30 pF
- Desired Tr/f time = 3 ns (rise/fall time part number code = E)

Part number for the above example:

SiT2001BI**E**S2-18E-66.666660



Drive strength code is inserted here. Default setting is "-"



# Rise/Fall Time (20% to 80%) vs CLOAD Tables

Table 7. Vdd = 1.8 V Rise/Fall Times for Specific  $C_{\text{LOAD}}$ 

Rise/Fall Time Typ (ns)							
Drive Strength \ C <sub>LOAD</sub>	5 pF	15 pF	30 pF	45 pF	60 pF		
L	6.16	11.61	22.00	31.27	39.91		
Α	3.19	6.35	11.00	16.01	21.52		
R	2.11	4.31	7.65	10.77	14.47		
В	1.65	3.23	5.79	8.18	11.08		
Т	0.93	1.91	3.32	4.66	6.48		
E	0.78	1.66	2.94	4.09	5.74		
U	0.70	1.48	2.64	3.68	5.09		
F or "-": default	0.65	1.30	2.40	3.35	4.56		

Table 9. Vdd = 2.8 V Rise/Fall Times for Specific C<sub>LOAD</sub>

Rise/Fall Time Typ (ns)							
Drive Strength \ C <sub>LOAD</sub>	5 pF	15 pF	30 pF	45 pF	60 pF		
L	3.77	7.54	12.28	19.57	25.27		
Α	1.94	3.90	7.03	10.24	13.34		
R	1.29	2.57	4.72	7.01	9.06		
В	0.97	2.00	3.54	5.43	6.93		
Т	0.55	1.12	2.08	3.22	4.08		
E or "-": default	0.44	1.00	1.83	2.82	3.67		
U	0.34	0.88	1.64	2.52	3.30		
F	0.29	0.81	1.48	2.29	2.99		

Table 11. Vdd = 3.3 V Rise/Fall Times for Specific  $C_{LOAD}$ 

Rise/Fall Time Typ (ns)							
Drive Strength \ C <sub>LOAD</sub>	5 pF	15 pF	30 pF	45 pF	60 pF		
L	3.39	6.88	11.63	17.56	23.59		
Α	1.74	3.50	6.38	8.98	12.19		
R	1.16	2.33	4.29	6.04	8.34		
В	0.81	1.82	3.22	4.52	6.33		
T or "-": default	0.46	1.00	1.86	2.60	3.84		
E	0.33	0.87	1.64	2.30	3.35		
U	0.28	0.79	1.46	2.05	2.93		
F	0.25	0.72	1.31	1.83	2.61		

Table 8. Vdd = 2.5 V Rise/Fall Times for Specific  $C_{LOAD}$ 

Rise/Fall Time Typ (ns)							
Drive Strength \ C <sub>LOAD</sub>	5 pF	15 pF	30 pF	45 pF	60 pF		
L	4.13	8.25	12.82	21.45	27.79		
Α	2.11	4.27	7.64	11.20	14.49		
R	1.45	2.81	5.16	7.65	9.88		
В	1.09	2.20	3.88	5.86	7.57		
T	0.62	1.28	2.27	3.51	4.45		
E or "-": default	0.54	1.00	2.01	3.10	4.01		
U	0.43	0.96	1.81	2.79	3.65		
F	0.34	0.88	1.64	2.54	3.32		

Table 10. Vdd = 3.0 V Rise/Fall Times for Specific  $C_{\text{LOAD}}$ 

Rise/Fall Time Typ (ns)								
Drive Strength \ C <sub>LOAD</sub>	Drive Strength \ C <sub>LOAD</sub> 5 pF 15 pF 30 pF 45 pF 60 pF							
L	3.60	7.21	11.97	18.74	24.30			
Α	1.84	3.71	6.72	9.86	12.68			
R	1.22	2.46	4.54	6.76	8.62			
В	0.89	1.92	3.39	5.20	6.64			
T or "-": default	0.51	1.00	1.97	3.07	3.90			
E	0.38	0.92	1.72	2.71	3.51			
U	0.30	0.83	1.55	2.40	3.13			
F	0.27	0.76	1.39	2.16	2.85			



# Pin 1 Configuration Options (OE, ST, or NC)

Pin 3 of the SiT2001 can be factory-programmed to support three modes: Output Enable (OE), standby ( $\overline{\text{ST}}$ ) or No Connect (NC).

## **Output Enable (OE) Mode**

In the OE mode, applying logic Low to the OE pin only disables the output driver and puts it in Hi-Z mode. The core of the device continues to operate normally. Power consumption is reduced due to the inactivity of the output. When the OE pin is pulled High, the output is typically enabled in  $<1\mu$ s.

# Standby (ST) Mode

In the  $\overline{ST}$  mode, a device enters into the standby mode when Pin 3 pulled Low. All internal circuits of the device are turned off. The current is reduced to a standby current, typically in the range of a few  $\mu A$ . When  $\overline{ST}$  is pulled High, the device goes through the "resume" process, which can take up to 5 ms.

#### No Connect (NC) Mode

In the NC mode, the device always operates in its normal mode and outputs the specified frequency regardless of the logic level on pin 3.

Table 12 below summarizes the key relevant parameters in the operation of the device in OE, ST, or NC mode.

Table 12. OE vs. ST vs. NC

	OE	ST	NC
Active current 20 MHz (max, 1.8 V)	4.1 mA	4.1 mA	4.1 mA
OE disable current (max. 1.8 V)	4.1 mA	N/A	N/A
Standby current (typical 1.8 V)	N/A	0.6 uA	N/A
OE enable time at 110 MHz (max)	130 ns	N/A	N/A
Resume time from standby (max, all frequency)	N/A	5 ms	N/A
Output driver in OE disable/standby mode	High Z	weak pull-down	N/A

#### **Output on Startup and Resume**

The SiT2001 comes with gated output. Its clock output is accurate to the rated frequency stability within the first pulse from initial device startup or resume from the standby mode.

In addition, the SiT2001 supports "no runt" pulses, and "no glitch" output during startup or resume as shown in the waveform captures in Figure 17 and Figure 18.



Figure 17. Startup Waveform vs. Vdd

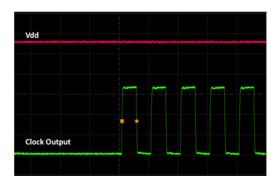
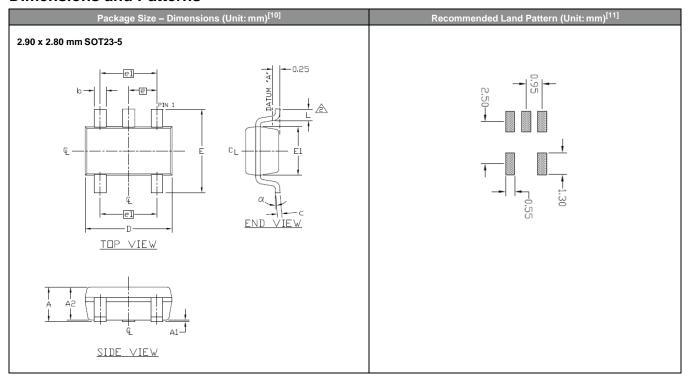


Figure 18. Startup Waveform vs. Vdd (Zoomed-in View of Figure 17)



# **Dimensions and Patterns**



#### Notes:

- 10. Top marking: Y denotes manufacturing origin and XXXX denotes manufacturing lot number. The value of "Y" will depend on the assembly location of the device.
- 11. A capacitor value of 0.1  $\mu\text{F}$  between Vdd and GND is required.

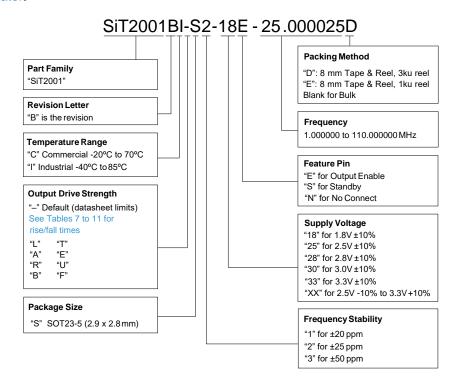
# **Table 13. Dimension Table**

Symbol	Min.	Nom.	Max.
Α	0.90	1.27	1.45
A1	0.00	0.07	0.15
A2	0.90	1.20	1.30
b	0.30	0.35	0.50
С	0.14	0.15	0.20
D	2.75	2.90	3.05
E	2.60	2.80	3.00
E1	1.45	1.60	1.75
L	0.30	0.38	0.55
L1	0.25 REF		
е	0.95 BSC.		
e1	1.90 BSC.		
α	0° – 8°		8°



# **Ordering Information**

The Part No. Guide is for reference only. To customize and build an exact part number, use the SiTime Part Number Generator.





#### **Table 14. Additional Information**

Document	Description	Download Link	
Time Machine II	MEMS oscillator programmer	http://www.sitime.com/support/time-machine-oscillator-programmer	
Field Programmable Oscillators	Devices that can be programmable in the field by Time Machine II http://www.sitime.com/products/field-programmable-osci		
Manufacturing Notes	Tape & Reel dimension, reflow profile and other manufacturing related info	brofile and other https://www.sitime.com/support/resource-library/manufacturing-notes sitime-products	
Qualification Reports	RoHS report, reliability reports, composition reports	http://www.sitime.com/support/quality-and-reliability	
Performance Reports	Reports Additional performance data such as phase noise, current consumption and jitter for selected frequencies http://www.sitime.com/support/performance-measurement-report		
Termination Techniques	Termination design recommendations	http://www.sitime.com/support/application-notes	
Layout Techniques	Layout recommendations	http://www.sitime.com/support/application-notes	

#### **Table 15. Revision History**

Revision	Release Date	Change Summary
0.95	13-Mar-2015	Initial Release Date
1.0	13-May-2015	Revised the Electrical Characteristics, Timing Diagrams and Performance Plots Revised SOT23 package diagram
1.01	29-Sep-2015	Revised the Dimension Table
1.02	18-Apr-2018	Changed Clock Generator to SOT23 Oscillator Updated logo and company address, other page layout changes
1.03	1-Jan-2023	Updated company disclaimer, links, references and icons

#### SiTime Corporation, 5451 Patrick Henry Drive, Santa Clara, CA 95054, USA | Phone: +1-408-328-4400 | Fax: +1-408-328-4439

© SiTime Corporation 2015-2023. The information contained herein is subject to change at any time without notice. SiTime assumes no responsibility or liability for any loss, damage or defect of a Product which is caused in whole or in part by (i) use of any circuitry other than circuitry embodied in a SiTime product, (ii) misuse or abuse including static discharge, neglect or accident, (iii) unauthorized modification or repairs which have been soldered or altered during assembly and are not capable of being tested by SiTime under its normal test conditions, or (iv) improper installation, storage, handling, warehousing or transportation, or (v) being subjected to unusual physical, thermal, or electrical stress.

Disclaimer: SiTime makes no warranty of any kind, express or implied, with regard to this material, and specifically disclaims any and all express or implied warranties, either in fact or by operation of law, statutory or otherwise, including the implied warranties of merchantability and fitness for use or a particular purpose, and any implied warranty arising from course of dealing or usage of trade, as well as any common-law duties relating to accuracy or lack of negligence, with respect to this material, any SiTime product and any product documentation. This product is not suitable or intended to be used in a life support application or component, to operate nuclear facilities, in military or aerospace applications, or in other mission critical applications where human life may be involved or at stake. All sales are made conditioned upon compliance with the critical uses policy set forth below.

#### CRITICAL USE EXCLUSION POLICY

BUYER AGREES NOT TO USE SITIME'S PRODUCTS FOR ANY APPLICATION OR IN ANY COMPONENTS: USED IN LIFE SUPPORT DEVICES, TO OPERATE NUCLEAR FACILITIES, FOR MILITARY OR AEROSPACE USE, OR IN OTHER MISSION CRITICAL APPLICATIONS OR COMPONENTS WHERE HUMAN LIFE OR PROPERTY MAY BE AT STAKE.

For aerospace and defense applications, SiTime recommends using only Endura™ ruggedized products.

SiTime owns all rights, title and interest to the intellectual property related to SiTime's products, including any software, firmware, copyright, patent, or trademark. The sale of SiTime products does not convey or imply any license under patent or other rights. SiTime retains the copyright and trademark rights in all documents, catalogs and plans supplied pursuant to or ancillary to the sale of products or services by SiTime. Unless otherwise agreed to in writing by SiTime, any reproduction, modification, translation, compilation, or representation of this material shall be strictly prohibited.



# **Supplemental Information**

The Supplemental Information section is not part of the datasheet and is for informational purposes only.



#### **Best Reliability**

Silicon is inherently more reliable than quartz. Unlike quartz suppliers, SiTime has in-house MEMS and analog CMOS expertise, which allows SiTime to develop the most reliable products. Figure 1 shows a comparison with quartz technology.

#### Why is SiTime Best in Class:

- SiTime's MEMS resonators are vacuum sealed using an advanced EpiSeal<sup>™</sup> process, which eliminates foreign particles and improves long term aging and reliability
- World-class MEMS and CMOS design expertise

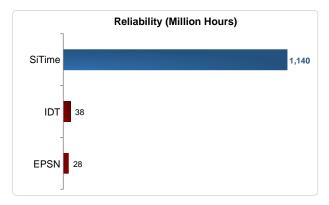


Figure 1. Reliability Comparison[1]

## **Best Aging**

Unlike quartz, MEMS oscillators have excellent long term aging performance which is why every new SiTime product specifies 10-year aging. A comparison is shown in Figure 2.

#### Why is SiTime Best in Class:

- SiTime's MEMS resonators are vacuum sealed using an advanced EpiSeal™ process, which eliminates foreign particles and improves long term aging and reliability
- Inherently better immunity of electrostatically driven MEMS resonator

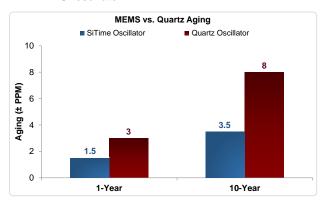


Figure 2. Aging Comparison<sup>[2]</sup>

## **Best Electro Magnetic Susceptibility (EMS)**

SiTime's oscillators in plastic packages are up to 54 times more immune to external electromagnetic fields than quartz oscillators as shown in Figure 3.

#### Why is SiTime Best in Class:

- Internal differential architecture for best common mode noise rejection
- Electrostatically driven MEMS resonator is more immune to EMS

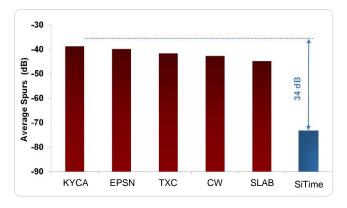


Figure 3. Electro Magnetic Susceptibility (EMS)[3]

#### **Best Power Supply Noise Rejection**

SiTime's MEMS oscillators are more resilient against noise on the power supply. A comparison is shown in Figure 4.

#### Why is SiTime Best in Class:

- On-chip regulators and internal differential architecture for common mode noise rejection
- MEMS resonator is paired with advanced analog CMOS IC

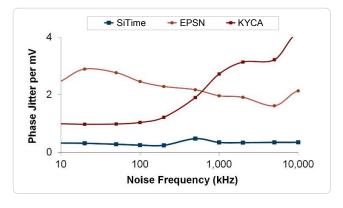


Figure 4. Power Supply Noise Rejection<sup>[4]</sup>



#### **Best Vibration Robustness**

High-vibration environments are all around us. All electronics, from handheld devices to enterprise servers and storage systems are subject to vibration. Figure 5 shows a comparison of vibration robustness.

# Why is SiTime Best in Class:

- The moving mass of SiTime's MEMS resonators is up to 3000 times smaller than quartz
- Center-anchored MEMS resonator is the most robust design

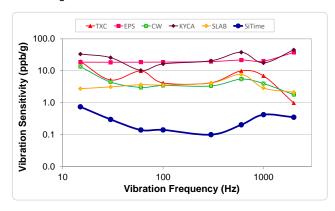


Figure 5. Vibration Robustness<sup>[5]</sup>

## Figure labels:

- TXC = TXC
- Epson = EPSN
- Connor Winfield = CW
- Kyocera = KYCA
- SiLabs = SLAB
- SiTime = EpiSeal MEMS

#### **Best Shock Robustness**

SiTime's oscillators can withstand at least 50,000~g shock. They all maintain their electrical performance in operation during shock events. A comparison with quartz devices is shown in Figure 6.

#### Why is SiTime Best in Class:

- The moving mass of SiTime's MEMS resonators is up to 3000 times smaller than quartz
- Center-anchored MEMS resonator is the most robust design

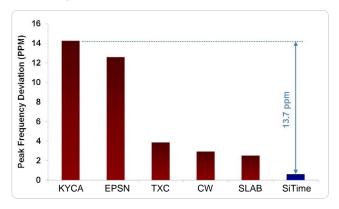


Figure 6. Shock Robustness<sup>[6]</sup>

# **Silicon MEMS Outperforms Quartz**



#### Notes:

- 1. Data source: Reliability documents of named companies.
- 2. Data source: SiTime and quartz oscillator devices datasheets.
- 3. Test conditions for Electro Magnetic Susceptibility (EMS):
  - According to IEC EN61000-4.3 (Electromagnetic compatibility standard)
  - Field strength: 3V/m
  - Radiated signal modulation: AM 1 kHz at 80% depth
  - Carrier frequency scan: 80 MHz 1 GHz in 1% steps
  - Antenna polarization: Vertical
  - DUT position: Center aligned to antenna

#### Devices used in this test:

Label	Manufacturer	Part Number	Technology
EpiSeal MEMS	SiTime	SiT9120AC-1D2-33E156.250000	MEMS + PLL
EPSN	Epson	EG-2102CA156.2500M-PHPAL3	Quartz, SAW
TXC	TXC	BB-156.250MBE-T	Quartz, 3 <sup>rd</sup> Overtone
CW	Conner Winfield	P123-156.25M	Quartz, 3 <sup>rd</sup> Overtone
KYCA	AVX Kyocera	KC7050T156.250P30E00	Quartz, SAW
SLAB	SiLab	590AB-BDG	Quartz, 3 <sup>rd</sup> Overtone + PLL

4. 50 mV pk-pk Sinusoidal voltage.

#### Devices used in this test:

Label	Manufacturer	Part Number	Technology
EpiSeal MEMS	SiTime	SiT8208AI-33-33E-25.000000	MEMS + PLL
NDK	NDK	NZ2523SB-25.6M	Quartz
KYCA	AVX Kyocera	KC2016B25M0C1GE00	Quartz
EPSN	Epson	SG-310SCF-25M0-MB3	Quartz

5. Devices used in this test:

same as EMS test stated in Note 3.

- 6. Test conditions for shock test:
  - MIL-STD-883F Method 2002
  - Condition A: half sine wave shock pulse, 500-g, 1ms
  - Continuous frequency measurement in 100 μs gate time for 10 seconds

#### Devices used in this test:

same as EMS test stated in Note 3.

7. Additional data, including setup and detailed results, is available upon request to qualified customer. Please contact productsupport@sitime.com.